# Asymptotic behavior of third-order neutral differential equations with distributed deviating arguments 

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#### Abstract

We consider the asymptotic behavior of solutions to a class of third-order neutral differential equations with distributed deviating arguments. Our criteria extend the related results reported in the literature. An illustrative example is included. (C)2017 all rights reserved.


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## 1. Introduction

Third-order differential equations arise in the study of entry-flow phenomenon, a problem of hydrodynamics, three-layer beams, and so forth; see the monograph [12] and papers [9, 15]. Analysis of the oscillation and asymptotic behavior of solutions to various classes of third-order differential equations always attracted interest of researchers; see, e.g., $[1-11,13-19,22]$ and the references cited therein.

In this paper, we consider the asymptotic properties of solutions to a class of third-order neutral equations with distributed deviating arguments

$$
\begin{equation*}
\left(a(t)\left[\left(b(t)[x(t)+p(t) x(\sigma(t))]^{\prime}\right)^{\prime}\right]^{\alpha}\right)^{\prime}+\int_{c}^{d} q(t, \xi) f(x(\tau(t, \xi))) d \xi=0, \tag{1.1}
\end{equation*}
$$

where $t \geqslant t_{0}$ and $\alpha>0$ is a ratio of two odd positive integers. Throughout this paper, we assume that the following hypotheses hold:
$\left(H_{1}\right) a(t), b(t), p(t) \in C\left(\left[t_{0}, \infty\right), \mathbb{R}\right), a(t)>0, b(t)>0,0 \leqslant p(t) \leqslant p_{0}<1, \int_{t_{0}}^{\infty} a^{-1 / \alpha}(t) d t=\infty$, $\int_{\mathrm{t}_{0}}^{\infty}(\mathrm{b}(\mathrm{t}))^{-1} \mathrm{dt}=\infty, \mathrm{q}(\mathrm{t}, \xi) \in \mathrm{C}\left(\left[\mathrm{t}_{0}, \infty\right) \times[\mathrm{c}, \mathrm{d}],[0, \infty)\right)$, and $\mathrm{q}(\mathrm{t}, \xi)$ is not identically zero for large t;

[^0]$\left(\mathrm{H}_{2}\right) \sigma(\mathrm{t}) \in \mathrm{C}\left(\left[\mathrm{t}_{0}, \infty\right), \mathbb{R}\right), \sigma(\mathrm{t}) \leqslant \mathrm{t}, \lim _{\mathrm{t} \rightarrow \infty} \sigma(\mathrm{t})=\infty, \tau(\mathrm{t}, \xi) \in \mathrm{C}\left(\left[\mathrm{t}_{0}, \infty\right) \times[\mathrm{c}, \mathrm{d}], \mathbb{R}\right)$ is a nondecreasing function for $\xi$ satisfying $\tau(\mathrm{t}, \xi) \leqslant \mathrm{t}$, and $\liminf _{\mathrm{t} \rightarrow \infty} \tau(\mathrm{t}, \xi)=\infty$ for $\xi \in[\mathrm{c}, \mathrm{d}]$;
$\left(H_{3}\right) f \in C(\mathbb{R}, \mathbb{R})$ and there exists a positive constant $k$ such that $f(u) / u^{\alpha} \geqslant k$ for all $u \neq 0$.
Let
$$
z(\mathrm{t}):=x(\mathrm{t})+\mathrm{p}(\mathrm{t}) x(\sigma(\mathrm{t})) .
$$

By a solution to (1.1) we mean a nontrivial function $x(t) \in C\left(\left[t_{x}, \infty\right), \mathbb{R}\right), t_{x} \geqslant t_{0}$, such that $z(t) \in$ $C^{1}\left(\left[\mathrm{t}_{x}, \infty\right), \mathbb{R}\right), \mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t}) \in \mathrm{C}^{1}\left(\left[\mathrm{t}_{\mathrm{x}}, \infty\right), \mathbb{R}\right), \mathrm{a}(\mathrm{t})\left[\left(\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}\right]^{\alpha} \in \mathrm{C}^{1}\left(\left[\mathrm{t}_{\mathrm{x}}, \infty\right), \mathbb{R}\right)$ and $x(\mathrm{t})$ satisfies (1.1) on the interval $\left[\mathrm{t}_{\mathrm{x}}, \infty\right)$. The solutions vanishing in some neighborhood of infinity will be excluded from our consideration. A solution of (1.1) is said to be oscillatory if it is neither eventually positive nor eventually negative; otherwise, it is termed nonoscillatory.

In what follows, we present some background details that motivate the contents of this paper. Agarwal et al. [1-4] and Li and Rogovchenko [17] studied the asymptotic behavior of a third-order delay differential equation

$$
\left(\mathfrak{a}(\mathrm{t})\left(\mathrm{x}^{\prime \prime}(\mathrm{t})\right)^{\alpha}\right)^{\prime}+\mathrm{q}(\mathrm{t}) \mathrm{f}(\mathrm{x}(\tau(\mathrm{t})))=0 .
$$

Baculíková and Džurina [5], Jiang et al. [14], Jiang and Li [15], and Li and Zhang [18] considered the asymptotic properties of a class of third-order neutral differential equations

$$
\left(\mathrm{a}(\mathrm{t})\left([\mathrm{x}(\mathrm{t})+\mathrm{p}(\mathrm{t}) x(\sigma(\mathrm{t}))]^{\prime \prime}\right)^{\alpha}\right)^{\prime}+\mathrm{q}(\mathrm{t}) \mathrm{x}^{\alpha}(\tau(\mathrm{t}))=0
$$

whereas Došlá and Liška [9] and Li et al. [19] investigated a general third-order neutral differential equation

$$
\left(\mathrm{a}(\mathrm{t})\left(\mathrm{b}(\mathrm{t})[\mathrm{x}(\mathrm{t})+\mathrm{p}(\mathrm{t}) \mathrm{x}(\sigma(\mathrm{t}))]^{\prime}\right)^{\prime}\right)^{\prime}+\mathrm{q}(\mathrm{t}) x(\tau(\mathrm{t}))=0
$$

Bohner et al. [6, 7] and Džurina and Kotorová [10] studied the oscillatory behavior of a third-order delay differential equation with damping

$$
x^{\prime \prime \prime}(\mathrm{t})+\mathrm{p}(\mathrm{t}) \mathrm{x}^{\prime}(\mathrm{t})+\mathrm{q}(\mathrm{t}) \mathrm{f}(\mathrm{x}(\tau(\mathrm{t})))=0
$$

whereas Li and Rogovchenko [16] considered a third-order delay differential equation

$$
x^{\prime \prime \prime}(\mathrm{t})+\mathrm{p}(\mathrm{t}) \mathrm{x}^{\prime \prime}(\mathrm{t})+\mathrm{q}(\mathrm{t}) \mathrm{f}(\mathrm{x}(\boldsymbol{\tau}(\mathrm{t})))=0 .
$$

Candan [8], Fu et al. [11], Jiang et al. [13], Şenel and Utku [20, 21], and Tian et al. [22] established several criteria for the oscillation and asymptotic behavior of a third-order neutral differential equation with distributed deviating arguments

$$
\left(a(t)\left([x(t)+p(t) x(\sigma(t))]^{\prime \prime}\right)^{\alpha}\right)^{\prime}+\int_{c}^{d} q(t, \xi) f(x(\tau(t, \xi))) d \xi=0 .
$$

Assuming that $u(t)$ is a positive solution of the equation $u^{\prime \prime}(t)+p(t) u(t)=0$, it is not difficult to see that equations

$$
x^{\prime \prime \prime}(t)+p(t) x^{\prime}(t)+\int_{c}^{d} q(t, \xi) f(x(\tau(t, \xi))) d \xi=0
$$

and

$$
\left(u^{2}(t)\left(\frac{1}{u(t)} x^{\prime}(t)\right)^{\prime}\right)^{\prime}+u(t) \int_{c}^{d} q(t, \xi) f(x(\tau(t, \xi))) d \xi=0
$$

are equivalent, and hence it is interesting to study equation (1.1).
In the sequel, all functional inequalities are assumed to hold eventually.

## 2. Auxiliary lemmas

To prove our main results, we need the following useful lemmas.
Lemma 2.1. Let conditions $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{3}\right)$ be satisfied and suppose that $\mathrm{x}(\mathrm{t})$ is an eventually positive solution of (1.1). Then there are only the following two possible cases for $z(\mathrm{t})$ :
(I) $z(\mathrm{t})>0, z^{\prime}(\mathrm{t})>0,\left(\mathrm{~b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}>0$, and $\left(\mathrm{a}(\mathrm{t})\left[\left(\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}\right]^{\alpha}\right)^{\prime} \leqslant 0$;
(II) $z(\mathrm{t})>0, z^{\prime}(\mathrm{t})<0,\left(\mathrm{~b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}>0$, and $\left(\mathrm{a}(\mathrm{t})\left[\left(\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}\right]^{\alpha}\right)^{\prime} \leqslant 0$,
for $t \geqslant t_{1}$, where $\mathrm{t}_{1} \geqslant \mathrm{t}_{0}$ is sufficiently large.
Proof. The proof is simple, and so is omitted.
Lemma 2.2. Let $\chi(\mathrm{t})$ be an eventually positive solution of (1.1). If $z(\mathrm{t})$ satisfies case ( I ) in Lemma 2.1, then for all sufficiently large $t_{1} \geqslant t_{0}$ there exists a $t_{2}>t_{1}$ such that, for $t \geqslant t_{2}$,

$$
\frac{z(t)}{b(t) z^{\prime}(t)} \geqslant \frac{\int_{t_{2}}^{t} \frac{\int_{1_{1}}^{s} a^{-1 / \alpha}(u) d u}{b(s)} d s}{\int_{t_{1}}^{t} a^{-1 / \alpha}(u) d u}
$$

and $\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t}) / \int_{\mathrm{t}_{1}}^{\mathrm{t}} \mathrm{a}^{-1 / \alpha}(\mathrm{u}) \mathrm{du}$ is nonincreasing eventually.
Proof. The proof is similar to that of [13, Lemma 2.2], and hence is omitted.
Lemma 2.3. Let $\chi(\mathrm{t})$ be an eventually positive solution of (1.1) and assume that $z(\mathrm{t})$ satisfies case (II) in Lemma 2.1. If

$$
\begin{equation*}
\int_{\mathrm{t}_{0}}^{\infty} \frac{1}{\mathrm{~b}(v)} \int_{v}^{\infty}\left(\frac{1}{\mathrm{a}(u)} \int_{\mathfrak{u}}^{\infty} \int_{\mathrm{c}}^{\mathrm{d}} q(s, \xi) \mathrm{d} \xi \mathrm{~d} s\right)^{1 / \alpha} \mathrm{d} u \mathrm{~d} v=\infty, \tag{2.1}
\end{equation*}
$$

then $\lim _{t \rightarrow \infty} x(t)=0$.
Proof. The proof is similar to that of [5, Lemma 2], and therefore is omitted.

## 3. Main results

For simplicity, we introduce the following notation:

$$
\begin{aligned}
& q_{1}(t):=k\left(1-p_{0}\right)^{\alpha} \int_{c}^{d} q(t, \xi) d \xi, \quad \tau_{1}(t):=\tau(t, c) \\
& \rho_{+}^{\prime}(t):=\max \left\{0, \rho^{\prime}(t)\right\}, \quad \text { and } \quad G(t):=\rho(t) q_{1}(t)\left(\frac{\int_{t_{2}}^{\tau_{1}(t)}\left(\int_{t_{1}}^{s} a^{-1 / \alpha}(u) d u / b(s)\right) d s}{\int_{t_{1}}^{t} a^{-1 / \alpha}(u) d u}\right)^{\alpha},
\end{aligned}
$$

where the meaning of $\rho(\mathrm{t})$ will be explained later.
Theorem 3.1. Assume that conditions $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{3}\right)$ and (2.1) hold. If there exists a function $\rho(\mathrm{t}) \in \mathrm{C}^{1}\left(\left(\mathrm{t}_{0}, \infty\right),(0, \infty)\right)$ such that, for all sufficiently large $t_{1} \geqslant t_{0}$ and for some $t_{3}>t_{2}>t_{1}$,

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} \int_{t_{3}}^{t}\left(G(s)-\frac{1}{(\alpha+1)^{1+\alpha}} \frac{a(s)\left(\rho_{+}^{\prime}(s)\right)^{1+\alpha}}{\rho^{\alpha}(s)}\right) d s=\infty \tag{3.1}
\end{equation*}
$$

then every solution $\mathrm{x}(\mathrm{t})$ of (1.1) is either oscillatory or satisfies $\lim _{\mathrm{t} \rightarrow \infty} \mathrm{x}(\mathrm{t})=0$.

Proof. Let $x(t)$ be a nonoscillatory solution of (1.1). Without loss of generality, we may assume that $x(t)$ is eventually positive. By Lemma 2.1, $z(\mathrm{t})$ satisfies either case (I) or case (II).

Assume first that case (I) holds for $t \geqslant t_{1}$. By virtue of the definition of $z(t)$,

$$
\begin{equation*}
x(\mathrm{t})=z(\mathrm{t})-\mathrm{p}(\mathrm{t}) x(\sigma(\mathrm{t})) \geqslant z(\mathrm{t})-\mathrm{p}(\mathrm{t}) z(\sigma(\mathrm{t})) \geqslant\left(1-\mathrm{p}_{0}\right) z(\mathrm{t}) . \tag{3.2}
\end{equation*}
$$

It follows from (1.1) and (3.2) that

$$
\begin{align*}
\left(a(t)\left[\left(b(t) z^{\prime}(t)\right)^{\prime}\right]^{\alpha}\right)^{\prime} & \leqslant-k \int_{c}^{d} q(t, \xi) x^{\alpha}(\tau(t, \xi)) d \xi \\
& \leqslant-k\left(1-p_{0}\right)^{\alpha} \int_{c}^{d} q(t, \xi) z^{\alpha}(\tau(t, \xi)) d \xi  \tag{3.3}\\
& \leqslant-k\left(1-p_{0}\right)^{\alpha} z^{\alpha}(\tau(t, c)) \int_{c}^{d} q(t, \xi) d \xi \\
& =-q_{1}(t) z^{\alpha}\left(\tau_{1}(t)\right) .
\end{align*}
$$

Define a new function $\omega(\mathrm{t})$ by

$$
\begin{equation*}
\omega(\mathrm{t}):=\rho(\mathrm{t}) \frac{\mathrm{a}(\mathrm{t})\left[\left(\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}\right]^{\alpha}}{\left[\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right]^{\alpha}} . \tag{3.4}
\end{equation*}
$$

Then $\omega(t)>0$ and

$$
\begin{equation*}
\omega^{\prime}(\mathrm{t})=\frac{\rho^{\prime}(\mathrm{t})}{\rho(\mathrm{t})} \omega(\mathrm{t})+\rho(\mathrm{t}) \frac{\left(\mathrm{a}(\mathrm{t})\left[\left(\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}\right]^{\alpha}\right)^{\prime}}{\left[\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right]^{\alpha}}-\alpha \rho(\mathrm{t}) \mathrm{a}(\mathrm{t}) \frac{\left[\left(\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}\right]^{\alpha+1}}{\left[\mathrm{~b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right]^{\alpha+1}} \tag{3.5}
\end{equation*}
$$

By (3.4), we get

$$
\begin{equation*}
\left(\frac{\left(\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right)^{\prime}}{\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})}\right)^{\alpha+1}=\left(\frac{\omega(\mathrm{t})}{\rho(\mathrm{t}) \mathrm{a}(\mathrm{t})}\right)^{(\alpha+1) / \alpha} \tag{3.6}
\end{equation*}
$$

Substituting (3.3) and (3.6) into (3.5), we conclude that

$$
\begin{align*}
\omega^{\prime}(\mathrm{t}) & \leqslant \frac{\rho^{\prime}(\mathrm{t})}{\rho(\mathrm{t})} \omega(\mathrm{t})-\rho(\mathrm{t}) \mathrm{q}_{1}(\mathrm{t}) \frac{z^{\alpha}\left(\tau_{1}(\mathrm{t})\right)}{\left[\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})\right]^{\alpha}}-\alpha \frac{\omega^{(\alpha+1) / \alpha}(\mathrm{t})}{(\rho(\mathrm{t}) \mathrm{a}(\mathrm{t}))^{1 / \alpha}} \\
& =\frac{\rho^{\prime}(\mathrm{t})}{\rho(\mathrm{t})} \omega(\mathrm{t})-\rho(\mathrm{t}) \mathfrak{q}_{1}(\mathrm{t})\left(\frac{z\left(\tau_{1}(\mathrm{t})\right)}{\mathrm{b}\left(\tau_{1}(\mathrm{t})\right) z^{\prime}\left(\tau_{1}(\mathrm{t})\right)} \frac{\mathrm{b}\left(\tau_{1}(\mathrm{t})\right) z^{\prime}\left(\tau_{1}(\mathrm{t})\right)}{\mathrm{b}(\mathrm{t}) z^{\prime}(\mathrm{t})}\right)^{\alpha}-\alpha \frac{\omega^{(\alpha+1) / \alpha}(\mathrm{t})}{(\rho(\mathrm{t}) \mathfrak{a}(\mathrm{t}))^{1 / \alpha}} . \tag{3.7}
\end{align*}
$$

By virtue of Lemma 2.2, there exists a $t_{2}>t_{1}$ such that, for $t \geqslant t_{2}$,

$$
\frac{z\left(\tau_{1}(t)\right)}{b\left(\tau_{1}(t)\right) z^{\prime}\left(\tau_{1}(t)\right)} \geqslant \frac{\int_{t_{2}}^{\tau_{1}(t)}\left(\int_{\mathfrak{t}_{1}}^{s} a^{-1 / \alpha}(u) d u / b(s)\right) d s}{\int_{\mathfrak{t}_{1}}^{\tau_{1}(t)} a^{-1 / \alpha}(u) d u}
$$

and

$$
\frac{b\left(\tau_{1}(t)\right) z^{\prime}\left(\tau_{1}(t)\right)}{b(t) z^{\prime}(t)} \geqslant \frac{\int_{t_{1}}^{\tau_{1}(t)} a^{-1 / \alpha}(u) d u}{\int_{t_{1}}^{t} a^{-1 / \alpha}(u) d u} .
$$

It follows now from (3.7) and the latter inequalities that

$$
\begin{equation*}
\omega^{\prime}(t) \leqslant \frac{\rho_{+}^{\prime}(t)}{\rho(t)} \omega(t)-\rho(t) q_{1}(t)\left(\frac{\int_{t_{2}}^{\tau_{1}(t)}\left(\int_{t_{1}}^{s} a^{-1 / \alpha}(u) d u / b(s)\right) d s}{\int_{t_{1}}^{t} a^{-1 / \alpha}(u) d u}\right)^{\alpha}-\alpha \frac{\omega^{(\alpha+1) / \alpha}(t)}{(\rho(t) a(t))^{1 / \alpha}} . \tag{3.8}
\end{equation*}
$$

Let

$$
y:=\omega(t), \quad A:=\frac{\alpha}{(\rho(t) a(t))^{1 / \alpha}}, \quad \text { and } \quad B:=\frac{\rho_{+}^{\prime}(t)}{\rho(t)} .
$$

Using the inequality (see [16])

$$
\mathrm{By}-\mathrm{A} \mathrm{y}^{(\alpha+1) / \alpha} \leqslant \frac{\alpha^{\alpha}}{(\alpha+1)^{\alpha+1}} \frac{\mathrm{~B}^{1+\alpha}}{\mathrm{A}^{\alpha}}, \quad \mathrm{A}>0
$$

we have

$$
\frac{\rho_{+}^{\prime}(t)}{\rho(t)} \omega(t)-\alpha \frac{\omega^{(\alpha+1) / \alpha}(t)}{(\rho(t) a(t))^{1 / \alpha}} \leqslant \frac{1}{(\alpha+1)^{1+\alpha}} \frac{a(t)\left(\rho_{+}^{\prime}(t)\right)^{1+\alpha}}{\rho^{\alpha}(t)}
$$

By (3.8), we deduce that

$$
\omega^{\prime}(t) \leqslant-G(t)+\frac{1}{(\alpha+1)^{1+\alpha}} \frac{a(t)\left(\rho_{+}^{\prime}(t)\right)^{1+\alpha}}{\rho^{\alpha}(t)}
$$

Hence, there exists a $t_{3}>t_{2}$ such that

$$
\int_{t_{3}}^{t}\left(G(s)-\frac{1}{(\alpha+1)^{1+\alpha}} \frac{a(s)\left(\rho_{+}^{\prime}(s)\right)^{1+\alpha}}{\rho^{\alpha}(s)}\right) d s \leqslant \omega\left(t_{3}\right)
$$

which contradicts (3.1).
Assume now that case (II) holds for $t \geqslant t_{1}$. It follows from Lemma 2.3 that $\lim _{t \rightarrow \infty} x(t)=0$. This completes the proof.

Remark 3.2. One can derive from Theorem 3.1 a number of asymptotic criteria for (1.1) with an appropriate choice of $\rho(t)$. For example, we have the following result by letting $\rho(t)=1$.
Corollary 3.3. Let conditions $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{3}\right)$ and (2.1) be satisfied. If for all sufficiently large $\mathrm{t}_{1} \geqslant \mathrm{t}_{0}$ and for some $t_{3}>t_{2}>t_{1}$,

$$
\int_{t_{3}}^{\infty} G(t) d t=\infty
$$

then the conclusion of Theorem 3.1 remains intact.
Remark 3.4. Theorem 3.1 extends [19, Theorem 2.1].
We provide the following example to illustrate the main results.
Example 3.5. For $t \geqslant 1$, consider a third-order neutral differential equation

$$
\begin{equation*}
\left[e^{-t}\left(x(t)+e^{-\pi} x(t-\pi)\right)^{\prime}\right]^{\prime \prime}+\left(1-e^{-2 \pi}\right) \int_{-5 \pi / 2}^{-\pi} e^{-t-\xi} x(t+\xi) d \xi=0 \tag{3.9}
\end{equation*}
$$

Let $\rho(\mathrm{t})=\mathrm{t}$. It is not difficult to verify that all assumptions of Theorem 3.1 are satisfied. Therefore, every solution $x(t)$ of (3.9) is either oscillatory or satisfies $\lim _{t \rightarrow \infty} x(t)=0$. In fact, $x(t)=e^{t} \sin t$ is an oscillatory solution to this equation.

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