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Stochastic fixed point theorems for a random Z-contraction in a complete probability measure space with application to non-linear stochastic integral equations

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Abstract

In this paper, we propose the random \mathcal{Z} -contraction, prove a stochastic fixed point theorem for this contraction, and show that a solution for a non-linear stochastic integral equations exists in Banach spaces. ©2017 All rights reserved.

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1. Introduction

The random fixed point theorems are stochastic generalizations of original fixed point theorems and need to use for the random equation theorems. In the same way the original fixed point theorems are the important of deterministic equation theorems. In 1955, Spacek [28] and Hans [7, 8] initiated to show the random fixed point theorems for some random contraction mappings in Polish spaces. In 1966, Mukherjee [19] provided a Schauder's random fixed point theorem over the space of atomic probability measure. In 1976, the work of Bharucha-Reid [5] allured the attention of various mathematic researchers and bring to the development of this theorem. In 1979, Itoh [9] extended theorems of Spacek and Hans to set-valued contraction mappings. Itoh [9] applied theorems of random fixed point to solve some type

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of differential equations in Banach spaces. Sehgal et al. [27] obtained many theorems of random fixed point along with random analogue of the classical theorems based on work of Rothe [22]. The common random fixed points and random coincidence points of a pair of compatible random set-valued operators in Polish spaces were studied by Beg et al. [4]. Moreover, the concept of original random fixed point theorems became the source of inspiration for many new generation mathematics researchers working on the random fixed point theorems (for example, see in [1, 6, 10, 12–17, 20, 21, 23–26]).

In the sense of non-linear analysis, Banach's contraction principle [3] is very important to show a solution of some non-linear equations, differential and integral equations, and other non-linear problems exists. The following Banach's contraction principle, many authors have studied in several ways.

Theorem 1.1. If (X, d) is a complete metric space and $T : X \to X$ is a self-mapping so that

$$d(Tx,Ty) \leq \alpha d(x,y)$$

for each $x, y \in X$ and $\alpha \in [0, 1)$, then T has a unique fixed point.

Very recently, the new generalized Banach contraction is introduced by Khojasteh et al. [11] which they defined a simulation function and \mathcal{Z} -contraction as follows.

Definition 1.2. Let $\zeta : [0, \infty) \times [0, \infty) \to \mathbb{R}$ be a mapping, then ζ is called a simulation function if it satisfies the assumptions as follows:

(Δ_1) $\zeta(0,0) = 0$; (Δ_2) $\zeta(t,s) < s-t$ for t,s > 0; (Δ_3) if { t_n }, { s_n } are sequences in ($0,\infty$) so that

$$\lim_{n\to\infty}t_n=\lim_{n\to\infty}s_n>0,$$

then

$$\limsup_{n\to\infty}\zeta(t_n,s_n)<0.$$

The set of all simulation functions is denoted by \mathcal{Z} .

Definition 1.3. Let (X, d) be a metric space, T is a self-mapping, and $\zeta \in \mathbb{Z}$. Then T is called a \mathbb{Z} -contraction by respect to ζ if the following condition holds:

$$\zeta(d(\mathsf{T}\mathsf{x},\mathsf{T}\mathsf{y}),d(\mathsf{x},\mathsf{y})) \ge 0,$$

where $x, y \in X$, with $x \neq y$.

Also, a non-linear stochastic analysis is an important mathematical discipline which is mostly connected with the study of some random operators. Their properties are important for the study of many random equations classes.

Since the importance of a non-linear stochastic analysis, we will propose the notion of random \mathcal{Z} contraction and prove a stochastic fixed point theorem for this contraction operator. Furthermore, we
apply our results for finding a solution for non-linear stochastic integral equations in Banach spaces.

2. Stochastic fixed point results

Motivated and inspired by Definition 1.3 and the work of Saha and Ganguly [26], we propose the definition of random \mathcal{Z} -contraction operators as follows.

Definition 2.1. Assume T is a continuous random operator from $\Omega \times X$ to X. The operator T is called random \mathfrak{Z} -contraction if, for any $\omega \in \Omega$,

$$\zeta(\|\mathsf{T}(\omega,\mathsf{x}_1(\omega)) - \mathsf{T}(\omega,\mathsf{x}_2(\omega))\|, \|\mathsf{x}_1(\omega) - \mathsf{x}_2(\omega)\|) \ge 0$$

for any random variables $x_1, x_2 : \Omega \to X$.

Now, we prove that a stochastic fixed point for random \mathcal{Z} -contraction exists in separable Banach spaces as follows.

Theorem 2.2. Assume that (Ω, β, μ) is a complete probability measure space and T is an operator satisfying the random \mathbb{Z} -contraction in Definition 2.1 almost surely for any $x_1(\omega), x_2(\omega) \in X$, where X is a separable Banach space. Then a random fixed point of operator T exists.

Proof. Suppose

 $A = \{ \omega \in \Omega : T(\omega, x) \text{ is a continuous of } x \}$

and

$$B_{x_1,x_2} = \{\omega \in \Omega : \zeta(\|\mathsf{T}(\omega, x_1(\omega)) - \mathsf{T}(\omega, x_2(\omega))\|, \|x_1(\omega) - x_2(\omega)\|) \ge 0\}.$$

Suppose S is a set of countable dense, where $S \subset X$. Now, we prove that

$$\bigcap_{x_1,x_2 \in X} (B_{x_1,x_2} \cap A) = \bigcap_{s_1,s_2 \in S} (B_{s_1,s_2} \cap A).$$

Then for all $s_1, s_2 \in S$, we obtain

$$\zeta(\|\mathsf{T}(\omega, \mathsf{s}_1(\omega)) - \mathsf{T}(\omega, \mathsf{s}_2(\omega))\|, \|\mathsf{s}_1(\omega) - \mathsf{s}_2(\omega)\|) \ge 0,$$

which implies that

$$\|\mathsf{T}(\omega, s_1(\omega)) - \mathsf{T}(\omega, s_2(\omega))\| < \|s_1(\omega) - s_2(\omega)\|.$$
(2.1)

Because S is dense subset of X, given by $\delta_i(x_i) > 0$ there is $s_1, s_2 \in S$ so that $||x_i - s_i|| < \delta_i(x_i)$ for each i = 1, 2. Let $x_1, x_2 \in X$. Now, we have

$$\|\mathsf{T}(\omega, x_1(\omega)) - \mathsf{T}(\omega, x_2(\omega))\| \leq \|\mathsf{T}(\omega, x_1(\omega)) - \mathsf{T}(\omega, s_1(\omega))\| + \|\mathsf{T}(\omega, s_1(\omega)) - \mathsf{T}(\omega, s_2(\omega))\| + \|\mathsf{T}(\omega, s_2(\omega)) - \mathsf{T}(\omega, x_2(\omega))\|.$$

$$(2.2)$$

Substituting (2.1) in (2.2), we get

$$\begin{aligned} \|\mathsf{T}(\omega, x_{1}(\omega)) - \mathsf{T}(\omega, x_{2}(\omega))\| &< \|\mathsf{T}(\omega, x_{1}(\omega)) - \mathsf{T}(\omega, s_{1}(\omega))\| \\ &+ \|\mathsf{T}(\omega, s_{2}(\omega)) - \mathsf{T}(\omega, x_{2}(\omega))\|) + \|s_{1}(\omega) - s_{2}(\omega)\| \\ &\leqslant \|\mathsf{T}(\omega, x_{1}(\omega)) - \mathsf{T}(\omega, s_{1}(\omega))\| + \|\mathsf{T}(\omega, s_{2}(\omega)) - \mathsf{T}(\omega, x_{2}(\omega))\|) \\ &+ \|s_{1}(\omega) - x_{1}(\omega)\| + \|x_{1}(\omega) - x_{2}(\omega)\| + \|x_{2}(\omega) - s_{2}(\omega)\|. \end{aligned}$$
(2.3)

Because the function $T(\omega, x)$ is a continuous for all $\omega \in \Omega$, thus for all $\epsilon > 0$, there exists $\delta_i(x_i) > 0$ for i = 1, 2 so that

$$\|T(\omega, x_1) - T(\omega, s_1)\| < \frac{\epsilon}{8} \text{ when } \|x_1 - s_1\| < \delta_1(x_1),$$

and

$$\|T(\omega, x_2) - T(\omega, s_2)\| < \frac{\varepsilon}{8} \text{ when } \|x_2 - s_2\| < \delta_1(x_2).$$

Now, we choose

$$\delta_1 = \min(\delta_1(\mathbf{x}_1), \frac{\varepsilon}{8})$$

and

$$\delta_2 = \min(\delta_2(\mathbf{x}_2), \frac{\varepsilon}{8}).$$

For such a choice of δ_1 , δ_2 by (2.3), we obtain

$$\|\mathsf{T}(\omega, x_1(\omega)) - \mathsf{T}(\omega, x_2(\omega))\| < \frac{\varepsilon}{8} + \frac{\varepsilon}{8} + \frac{\varepsilon}{8} + \|x_1(\omega) - x_2(\omega)\| + \frac{\varepsilon}{8} = \frac{\varepsilon}{2} + \|x_1(\omega) - x_2(\omega)\|$$

As $\varepsilon > 0$ is arbitrary, if

$$\|\mathsf{T}(\omega, \mathsf{x}_1(\omega)) - \mathsf{T}(\omega, \mathsf{x}_2(\omega))\| < \|\mathsf{x}_1(\omega) - \mathsf{x}_2(\omega)\|,$$

then

$$\zeta(\|\mathsf{T}(\omega, x_1(\omega)) - \mathsf{T}(\omega, x_2(\omega))\|, \|x_1(\omega) - x_2(\omega)\|) \ge 0$$

Thus we have $\omega \in \bigcap_{x_1, x_2 \in X} (B_{x_1, x_2} \cap A)$, which implies that

S

$$\bigcap_{x_1,x_2\in S} (B_{s_1,s_2}\cap A) \subset \bigcap_{x_1,x_2\in X} (B_{x_1,x_2}\cap A).$$

Also, we have

$$\bigcap_{x_1,x_2\in X} (B_{x_1,x_2}\cap A) \subset \bigcap_{s_1,s_2\in S} (B_{s_1,s_2}\cap A).$$

Therefore, we get

$$\bigcap_{s_1, s_2 \in S} (B_{s_1, s_2} \cap A) = \bigcap_{x_1, x_2 \in X} (B_{x_1, x_2} \cap A).$$

Let $N' = \bigcap_{s_1,s_2 \in S} (B_{s_1,s_2} \cap A)$. Then $\mu(N') = 1$, which implies that for all $\omega \in N'$, $T(\omega, x)$ are deterministic continuous operators. Therefore, T has a unique random fixed point in X. Next, we show $x(\omega)$ is random and measurable. We construct a sequence of random variable $x_n(\omega)$. Let $x_0(\omega)$ be an arbitrary random variable and $x_1(\omega) = T(\omega, x_0(\omega))$. Thus $x_1(\omega)$ is a random variable. Next, we get $x_{n+1}(\omega) = T(\omega, x_n(\omega))$. By repeated generating, it gives that $\{x_n(\omega)\}_{n=1,2,\dots}$ is a random variables sequence converging to $x(\omega)$. So, $x(\omega)$ is a random variable and therefore $x(\omega)$ is measurable. Thus $x(\omega)$ is a random fixed point of T.

If we do not consider the simulation function, we obtain the corollary as follows.

Corollary 2.3. Assume that (Ω, β, μ) is a complete probability measure space and T is an operator satisfying

$$\|\mathsf{T}(\omega, \mathsf{x}_1(\omega)) - \mathsf{T}(\omega, \mathsf{x}_2(\omega))\| < \|\mathsf{x}_1(\omega) - \mathsf{x}_2(\omega)\|$$

almost surely for any $x_1(\omega), x_2(\omega) \in X$, where X is a separable Banach space. Then a random fixed point of T exists in X.

Proof. Suppose

 $A = \{\omega \in \Omega : T(\omega, x) \text{ is a continuous of } x\}$

and

$$B_{x_1,x_2} = \{\omega \in \Omega : \|T(\omega, x_1(\omega)) - T(\omega, x_2(\omega))\| < \|x_1(\omega) - x_2(\omega)\|\}.$$

Suppose S is a countable dense set, $S \subset X$. Now, we prove that

$$\bigcap_{x_1, x_2 \in X} (B_{x_1, x_2} \cap A) = \bigcap_{s_1, s_2 \in S} (B_{s_1, s_2} \cap A).$$

Then for all $s_1, s_2 \in S$, we get

$$\|\mathsf{T}(\omega, s_1(\omega)) - \mathsf{T}(\omega, s_2(\omega))\| < \|s_1(\omega) - s_2(\omega)\|.$$

Following the proof in Theorem 2.2, we get the result.

From Theorem 2.2 and Corollary 2.3, we can illustrate example as follows.

Example 2.4. Assume that $X = \mathbb{R}$ with the usual norm of reals and $\Omega = \mathbb{R}$. Let β be a σ -algebra of Lebesgue measurable sets of \mathbb{R} .

Now, we define the random operator $T : \Omega \times X \to X$ by $T(\omega, x) = \frac{x}{2}$.

Since conditions of Theorem 2.2 and Corollary 2.3 are satisfied, we get that $x : \Omega \to X$ with $x(\omega) = 0$ is the random fixed point of T in \mathbb{R} .

We show the random fixed point of operator T by Figure 1.



Figure 1: A random fixed point of operator $T(\omega, x) = \frac{x}{2}$ is $x(\omega) = 0$.

3. Applications to non-linear stochastic integral equations

Now, we use Theorem 2.2 to show a solution of a non-linear stochastic integral equation exists in a Banach space. Assume that S is a locally compact metric space and (Ω, β, μ) is the probability measure space with β being σ -algebra and μ the probability measure. We can write this equation of the Hammerstein type ([20]) as follows:

$$x(t_1;\omega) = h(t_1;\omega) + \int_S k(t_1;t_2;\omega) f(t_2;x(t_2;\omega)) d\mu(t_2),$$
(3.1)

where

- (a) d is a metric imposed on product Cartesian of S;
- (b) μ_0 is a complete σ -finite measure imposed on the collection of Borel subsets of S;
- (c) $\omega \in \Omega$ where Ω is the supporting set of (Ω, β, μ) ;
- (d) $x(t_1; \omega)$ is the unknown vector-valued random variable for any $t_1 \in S$;
- (e) $h(t_1; \omega)$ is the stochastic free term imposed for $t_1 \in S$;
- (f) $k(t_1, t_2; \omega)$ is the stochastic kernel imposed for $t_1, t_2 \in S$;
- (g) $f(t_1, x)$ is a vector-valued function for $t_1 \in S$ and x.

Note that (3.1) is called a Bochner integral (see in [29]).

Next, we suppose that the union of a countable family $\{C_n\}$ of compact sets by $C_{n+1} \subset C_n$ is imposed as S so that, for each another compact set in S, there is C_i which contains it (see [2]).

We impose a space of all continuous functions from S into $L_2(\Omega, \beta, \mu)$ by $C = C(S, L_2(\Omega, \beta, \mu))$ by the topology of uniform convergence on compact sets of S, that is, $x(t_1; \omega)$ is a vector-valued random variable for any fixed $t_1 \in S$ so that

$$\|x(t_1;\omega)\|^2_{L_2(\Omega,\beta,\mu)} = \int_\Omega |x(t_1;\omega)|^2 d\mu(\omega) < \infty.$$

Observe that $C(S, L_2(\Omega, \beta, \mu))$ is a locally convex space ([29]) whose topology is given by

$$\|\mathbf{x}(t_1;\omega)\|_n = \sup_{t_1 \in C_n} \|\mathbf{x}(t_1;\omega)\|_{L_2(\Omega,\beta,\mu)},$$
(3.2)

which is the countable family of semi-norms for any $n \ge 1$. Moreover, because $L_2(\Omega, \beta, \mu)$ is complete, then $C(S, L_2(\Omega, \beta, \mu))$ is complete relative to (3.2).

Later, we impose a Banach space of all bounded continuous functions from S into $L_2(\Omega, \beta, \mu)$ by $BC = BC(S, L_2(\Omega, \beta, \mu))$ by the norm

$$\|\mathbf{x}(t_1; \omega)\|_{BC} = \sup_{t_1 \in S} \|\mathbf{x}(t_1; \omega)\|_{L_2(\Omega, \beta, \mu)}.$$

 $BC \subset C$ is a space of all second order vector-valued stochastic processes imposed on S which are bounded and continuous in mean square.

Now, we consider the functions $h(t_1; \omega)$ and $f(t_1, x(t_1; \omega))$ to be in $C(S, L_2(\Omega, \beta, \mu))$ space by respect to the stochastic kernel and suppose that, for any pair (t_1, t_2) , $k(t_1, t_2; \omega) \in L_{\infty}(\Omega, \beta, \mu)$ and the norm denoted by

$$|||k(t_1, t_2; \omega)||| = ||k(t_1, t_2; \omega)||_{L_{\infty}(\Omega, \beta, \mu)} = \mu - ess \sup_{\omega \in \Omega} |k(t_1, t_2; \omega)|.$$

Also, we assume that $k(t_1, t_2; \omega) \in L_{\infty}(\Omega, \beta, \mu)$ is so that $|||k(t_1, t_2; \omega)|| = ||x(t_2; \omega)||_{L_2(\Omega, \beta, \mu)}$ is μ -integrable by respect to t_2 for any $t_1 \in S$ and $x(t_2; \omega) \in C(S, L_2(\Omega, \beta, \mu))$ and there is a real-valued function G μ -a.e. on S so that $G(S)||x(t_2; \omega)||_{L_2(\Omega, \beta, \mu)}$ is μ -integrable and, for any (t_1, t_2) in $S \times S$,

$$\||k(t_1, u; \omega) - k(t_2, u; \omega)|\| \cdot \|x(u; \omega)\|_{L_2(\Omega, \beta, \mu)} \leq G(u)\|x(u; \omega)\|_{L_2(\Omega, \beta, \mu)} \quad \mu-a.e.$$

Later, suppose that, for almost every $t_2 \in S$, $k(t_1, t_2; \omega)$ is continuous in t_1 from S into $L_{\infty}(\Omega, \beta, \mu)$. Now, we impose the random integral operator T on $C(S, L_2(\Omega, \beta, \mu))$ by

$$(Tx)(t_1;\omega) = \int_{S} k(t_1, t_2; \omega) x(t_2; \omega) d\mu(t_2),$$
(3.3)

which is called a Bochner integral. By the assumptions on $k(t_1, t_2; \omega)$, it follows that, for each $t_1 \in S$, $(Tx)(t_1; \omega) \in L_2(\Omega, \beta, \mu)$ and $(Tx)(t_1; \omega)$ is continuous in mean square by Lebesgue's dominated convergence theorem, that is, $(Tx)(t_1; \omega) \in C(S, L_2(\Omega, \beta, \mu))$.

Lemma 3.1 ([20]). *The linear operator* T *defined by* (3.3) *is continuous from* C(S, L₂(Ω , β , μ)) *into itself.*

Definition 3.2 ([1, 18]). Let B and D be Banach spaces. The pair (B, D) is called *admissible* by respect to a linear operator T if $T(B) \subset D$.

Lemma 3.3 ([20]). *If* T *is a continuous linear operator from* C(S, L₂(Ω , β , μ)) *into itself,* B, D \subset C(S, L₂(Ω , β , μ)) *are Banach spaces stronger than* C(S, L₂(Ω , β , μ)) *so that* (B, D) *is admissible by respect to* T, *then* T *is continuous from* B *into* D.

By a *random solution* of (3.1), we mean a function

$$\mathbf{x}(\mathbf{t}_1; \boldsymbol{\omega}) \in \mathbf{C}(\mathbf{S}, \mathbf{L}_2(\Omega, \boldsymbol{\beta}, \boldsymbol{\mu}))$$

which satisfies (3.1) µ-a.e.

By using Theorem 2.2, we are now in state to prove the theorem as follows.

Theorem 3.4. *Suppose that* (3.1) *is subject to the assumptions as follows:*

- (1) B and D are Banach spaces stronger than $C(S, L_2(\Omega, \beta, \mu))$ so that (B, D) is admissible by respect to the integral operator imposed by (3.3);
- (2) $x(t_1; \omega) \mapsto f(t_1, x(t_1; \omega))$ is an operator from $Q(\rho) = \{x(t_1; \omega) : x(t_1; \omega) \in D, \|x(t_1; \omega)\|_D \le \rho\}$ into B satisfying

$$\zeta(\|f(t_1, x_1(t_1, \omega)) - f(t_1, x_2(t_1, \omega))\|_{B}, \|x_1(t_1, \omega) - x_2(t_1, \omega)\|) \ge 0$$
(3.4)

 $\label{eq:constraint} \begin{array}{l} \textit{for any } x_1(t_1,\omega), x_2(t_1,\omega) \in Q(\rho); \\ \text{(3) } h(t_1;\omega) \in D, \end{array}$

then a unique stochastic solution of (3.1) exists in $Q(\rho)$ provided that

$$\|\mathbf{h}(\mathbf{t}_1, \boldsymbol{\omega})\|_{\mathbf{D}} + \sigma(\boldsymbol{\omega}) \|\mathbf{f}(\mathbf{t}_1, \mathbf{0})\|_{\mathbf{B}} \leq \rho(1 - \sigma(\boldsymbol{\omega})),$$

where the norm of $T(\omega)$ is denoted by $\sigma(\omega)$.

Proof. Let a mapping $\mathcal{U}(\omega) : Q(\rho) \to D$ defined by

$$(\mathfrak{U}\mathbf{x})(\mathbf{t}_1,\boldsymbol{\omega}) = \mathbf{h}(\mathbf{t}_1,\boldsymbol{\omega}) + \int_{S} \mathbf{k}(\mathbf{t}_1,\mathbf{t}_2,\boldsymbol{\omega}) \mathbf{f}(s,\mathbf{x}(\mathbf{t}_2,\boldsymbol{\omega})) \mathbf{d}_{\mu_0}(s).$$

Then we get

$$\begin{split} \|(\mathfrak{U}x)(t_{1},\omega)\|_{D} &\leq \|h(t_{1},\omega)\|_{D} + \sigma(\omega)\|f(t_{1},x(t_{1},\omega))\|_{B} \\ &= \|h(t_{1},\omega)\|_{D} + \sigma(\omega)\|f(t_{1},0) + f(t_{1},x(t_{1},\omega)) - f(t_{1},0)\|_{B} \\ &\leq \|h(t_{1},\omega)\|_{D} + \sigma(\omega)\|f(t_{1},0)\|_{B} + \sigma(\omega)\|f(t_{1},x(t_{1},\omega)) - f(t_{1},0)\|_{B}. \end{split}$$

Thus, it follows by (3.4) that

$$\zeta(\|f(t_1, x(t_1, \omega)) - f(t_1, 0)\|_{\mathsf{B}}, \|x(t_1, \omega)\|_{\mathsf{D}}) \ge 0)$$

which implies that

 $\|f(t_1,x(t_1,\omega)) - f(t_1,0)\|_B < \|x(t_1,\omega)\|_D.$

Therefore, we obtain

$$\|f(t_1, x(t_1, \omega)) - f(t_1, 0)\|_B \le \rho.$$
(3.5)

Therefore, by (3.5), we have

$$\| (\mathcal{U}x)(t_{1},\omega) \|_{D} \leq \| h(t_{1},\omega) \|_{D} + \sigma(\omega) \| f(t_{1},0) \|_{B} + \sigma(\omega) \| f(t_{1},x(t_{1},\omega)) - f(t_{1},0) \|_{B}$$

$$\leq \| h(t_{1},\omega) \|_{D} + \sigma(\omega) \| f(t_{1},0) \|_{B} + \sigma(\omega) \rho < \rho$$
(3.6)

and so, by (3.6), $(\mathcal{U}x)(t_1, \omega) \in Q(\rho)$. Thus, for any $x_1(t_1, \omega), x_2(t_1, \omega) \in Q(\rho)$ and, by (2), we get

$$\begin{aligned} \|(\mathfrak{U}x_1)(t_1,\omega) - (\mathfrak{U}x_2)(t_1,\omega)\|_{\mathbf{D}} &= \left\| \int_{S} k(t_1,t_2,\omega)[f(t_2,x_1(t_2,\omega)) - f(t_2,x_2(t_2,\omega))]d\mu_0(s) \right\|_{\mathbf{D}} \\ &\leqslant \sigma(\omega) \|f(t_2,x_1(t_2,\omega)) - f(t_2,x_2(t_2,\omega))\|_{\mathbf{B}} \leqslant \|x_1(t_1,\omega) - x_2(t_1,\omega)\|_{\mathbf{D}}. \end{aligned}$$

Consequently, $\mathcal{U}(\omega)$ is a random contraction mapping over $Q(\rho)$. Therefore, by Theorem 2.2, there is a unique $x^*(t_1, \omega) \in Q(\rho)$, which is a random fixed point of \mathcal{U} , i.e., x^* is a stochastic solution of equation (3.1). This completes the proof.

Example 3.5. Consider the non-linear stochastic integral equation as follows:

$$x(t_1;\omega) = \int_0^\infty \frac{e^{-t_1-t_2}}{8(1+|x(t_2;\omega)|)} dt_2$$

Next, we compare between equations (3.1) and (3.5), we get that $h(t_1; \omega) = 0$, $k(t_1; t_2; \omega) = \frac{1}{2}e^{-t_1-t_2}$ and $f(t_2; x(t_2; \omega)) = \frac{1}{4(1+|x(t_2; \omega)|)}$. Then, equation (3.4) holds.

Also, comparing with integral equation (3.3), we get that $\sigma(\omega) = \frac{1}{2}$ which $\sigma(\omega)$ is the norm of $T(\omega)$. Thus, all assumptions of Theorem 3.4 are satisfied and therefore, random operator T has a random fixed point.

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