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TWO CONTINUITY CONCEPTS IN APPROXIMATION THEORY

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1 Introduction.

There has been much recent interest in studying various continuity criteria for the set-valued metric projection onto a set V. Particular interest has centered around the relationship between these criteria and either the structure of the set V itself or the geometry of the whole space. See, for example, [3], [4], [7], [8], [10], [16], [17], [18] and [21]. In essentially all of these papers, the concepts of lower semicontinuity (l.s.c.) and/or upper semicontinuity (u.s.c.) for set-valued mappings (as defined, for example, in Hahn [12]) played the key role. In this note we introduce some simpler and more general radial continuity criteria. Roughly speaking, these criteria require that the restriction of the metric projection to certain prescribed line segments be l.s.c. or u.s.c. It turns out that these criteria, which are formally much weaker than l.s.c. or u.s.c, are still strong enough to generalize a number of known results, and weak enough so that many of these theorems now have valid converses (which they did not have under the stronger hypotheses of l.s.c. or u.s.c.).

Throughout this note X will denote a (real or complex) normed linear

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space. For $x \in X$ and r > 0, let

$$S(x,r) = \{ y \in X : ||x - y|| = r \}$$

The distance from a point x to a subset V of X is defined by

$$d(x, V) = \inf\{||x - v|| : v \in V\}$$

The metric projection onto a subset V of X is the mapping P_V which associates with each $x \in X$ its set of best approximations in V, i.e.

$$P_V(x) = \{ v \in V : ||x - v|| = d(x, V) \}$$

V is called proximinal (resp. Chebyshev) provided $P_V(x)$ contains at least (resp. exactly) one point for each $x \in X$. V is called a sun if for each $x \in X$ and $v \in P_V(x)$, $v \in P_V(v + \lambda(x - v))$ for every $\lambda \geq 0$. The convex hull of a set A is denoted co(A). The notation (x, y) is used for the open interval $\{\lambda x + (1 - \lambda)y : 0 < \lambda < 1\}$. P_V is said to be l.s.c. (resp. u.s.c.) at x_0 if, for open set W with $W \cap P_V(x_0) \neq \emptyset$ (resp. $W \supset P_V(x_0)$), there exists a neighborhood U of x_0 such that $W \cap P_V(x) \neq \emptyset$ (resp. $W \supset P_V(x)$) for every $x \in U$.

All other undefined notation or terminology can be found in [11].

2 ORL continuity.

The first generalization of l.s.c. is

Definition 2.1. Let $V \subset X$ and $x_0 \in X$. P_V is said to be outer radially lower (abbreviated ORL) continuous at x_0 if for each $v_0 \in P_V(x_0)$ and each open set W with $W \cap P_V(x_0) \neq \emptyset$, there exists a neighborhood U of x_0 such that $W \cap P_V(x) \neq \emptyset$ for every x in $U \cap \{v_0 + \lambda(x_0 - v_0) : \lambda \geq 1\}$. P_V is called ORL continuous if it is ORL continuous at every point.

Theorem 2.2. [14] Let $V \subset X$ and consider the following statements.

- (1) V is a sun.
- (2) P_V is ORL continuous.
- (3) For each $x \in X$, every local minimum of the function $\Phi(v) = ||x v||$ on V is a global minimum.
- (4) V is a "moon" (in the sense of [1]).

Then $(1) \Rightarrow (2) \Rightarrow (3) \Rightarrow (4)$.

The The implication $(3) \Rightarrow (2)$ is false in general (e.g. take V to be the complement of the open unit ball in the Euclidean plane). Also, the implication $(4) \Rightarrow (3)$ is false in general. However, it is an open question whether

 $(2) \Rightarrow (1).$

We call a space X an MS-space if every moon in X is a sun. In such a space all the conditions of Theorem 2.2 are obviously equivalent. In [1], the spaces of type C(T), T compact Hausdorff (or more generally $C_0(T)$, T locally compact Hausdorff) and $l_1(S)$ for any set S, were shown to be MS-spaces. On the negative side, no strictly convex space is a MS-space. In particular, we can state

Corollary 2.3. Let X be an MS-space and $V \subset X$. Then V is a sun if and only if P_V is ORL continuous.

It is interesting to compare this result with a particular consequence of two theorems of Vlasov ([21, Theorem 7] and [20, Theorem 13]) which establishes the hard part of the following theorem (cf. also Asplund [2] for an alternate proof):

Theorem 2.4. A Chebyshev set V in a Hilbert space is a sun (i.e. is convex) if and only if P_V is continuous.

It is still unknown whether every Chebyshev set in a Hilbert space is convex. In fact, it is apparently unknown whether there exists a Chebyshev set in any space which is not a sun.

3 ORU continuity.

A generalization of u.s.c. is given by

Definition 3.1. Let $V \subset X$ and $x_0 \in X$. P_V is called outer radially upper (abbreviated ORU) continuous at x_0 if, for each $v_0 \in P_V(x_0)$ and each open set $W \supset P_V(x_0)$, there exists a neighborhood U of x_0 such that $W \supset P_V(x)$ for every x in $U \cap \{v_0 + \lambda(x_0 - v_0) : \lambda \ge 1\}$. P_V is called ORU continuous if it is ORU continuous at each point.

Theorem 3.2. [14] Let $V \subset X$ be proximinal and suppose $P_V(x)$ is convex for every $x \in X$. If P_V is ORU continuous, then $P_V(x)$ is compact for every $x \in X$.

This theorem generalizes one of Singer's [18] who had proved it in the particular case when V is a subspace and P_V is u.s.c. Theorem 3.2 is false in general if P_V is not convex-valued. To see this, we need only take $X = l_2$ and V to be the complement of the open unit ball. Then P_V is ORU continuous but $P_V(0) = S(0,1)$ is not compact.

Theorem 3.3. [14] Let V be a sun such that $P_V(x)$ is compact for every $x \in X$. Then P_V is ORU continuous.

Combining Theorems 3.2 and 3.3 we obtain

Corollary 3.4. Let V be a proximinal convex set. Then P_V is ORU

continuous if and only if $P_V(x)$ is compact for every x.

It is worth mentioning that Corollary 3.4 is false with u.s.c. in place of ORU continuity, even if V is a subspace. This follows since there exist Chebyshev subspaces with discontinuous metric projections. (The first such example was given by Lindenstrauss [15, pp. 87-88].)

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