



New results for fractional differential equations with impulses via variational methods

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Abstract

By using variational methods and some critical points theorems, we establish some new results for the existence of infinitely many of solutions for fractional order differential equations with impulses. In addition, one example is given to illustrate our results. ©2017 all rights reserved.

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1. Introduction

Fractional calculus refers to integration or differentiation of any order. The field has a history as old as calculus itself, which did not attract enough attention for a long time. In the past decades, the theory of fractional differential equations has become an important area of investigation because of its wide applicability in many branches of physics, economics and technical sciences. For a nice introduction, we refer the reader to [6, 12–14] and references cited therein. The main methods used in the research of fractional differential equations are some fixed theorems, the coincidence degree theory and the monotone iterative methods. On the other hand, critical point theory and the variational methods have been very useful in dealing with the existence and multiplicity of solutions for integer order differential equations with some boundary conditions. We refer readers to the books (or surveys) and the papers [5, 16, 19] and the references therein. The variational methods are also a very useful tool in dealing with the fractional differential equations; see [1, 4, 10, 11, 15, 22–24]. In [10], Jiao and Zhou considered the following fractional boundary value problems

$$\begin{cases} -\frac{1}{2} \frac{d}{dt} ({}_0D_t^{-\beta} + {}_tD_T^{-\beta}) u'(t) = \nabla F(t, u(t)), & \text{a.e. } t \in [0, T], \\ u(0) = u(T) = 0, \end{cases}$$

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where $\beta \in [0, 1)$, ${}_0D_t^{-\beta}$ and ${}_tD_T^{-\beta}$ are the left and right Riemann-Liouville fractional derivatives, respectively. $F: [0, T] \times \mathbb{R}^N \rightarrow \mathbb{R}$ (with $N \geq 1$) is a suitable given function and $\nabla F(t, x)$ is the gradient of F with respect to x .

By using the least action principle and Mountain Pass theorem, they obtained some sufficient conditions for the existence of one solution. The authors in [4, 8, 9, 15, 22] further studied the existence and multiplicity of solutions for the above problem or related problems with the critical point theory. And the above problem arises from the phenomena of advection dispersion and was first investigated by Ervin and Loop in [7].

Impulsive effects are common phenomena due to short-term perturbations whose duration is negligible in comparison with the total duration of the original process. The governing equations of such phenomena may be modeled as impulsive differential equations. In recent years, there has been a growing interest in the study of impulsive differential equations as these equations provide a natural framework for mathematical modeling of many real world phenomena, namely in the control theory, physics, chemistry, population dynamics, biotechnology, economics, and medical fields [17, 21].

Recently, the study of fractional differential equations with impulses has been studied by many authors. But for almost all the works, the main methods are some fixed theorems, the coincidence degree theory, and the monotone iterative methods. To our best knowledge, the fractional boundary value problems with impulses using variational methods and critical point theory have received considerably less attention [3, 18, 20]. Bonanno et al. [3] and Rodríguez-López and Tersian [20] studied the following Dirichlet’s boundary value problem for fractional differential equations with impulses:

$$\begin{cases} {}_tD_T^\alpha({}_0^cD_t^\alpha u(t)) + a(t)u(t) = \lambda f(t, u(t)), & t \neq t_j, \text{ a.e. } t \in [0, T], \\ \Delta({}_tD_T^{\alpha-1}({}_0^cD_t^\alpha u))(t_j) = \mu I_j(u(t_j)), & j = 1, 2, \dots, n, \\ u(0) = u(T) = 0, \end{cases}$$

where $\lambda \in (0, +\infty)$ and $\mu \in (0, +\infty)$ are two parameters. They obtained the existence of triple solutions by using variational methods and a three critical points theorem due to Bonanno and Marano [2].

In [18], the authors investigated the following fractional differential equations with impulses:

$$\begin{cases} {}_tD_T^\alpha({}_0^cD_t^\alpha u(t)) + a(t)u(t) = f(t, u(t)), & t \neq t_j, \text{ a.e. } t \in [0, T], \\ \Delta({}_tD_T^{\alpha-1}({}_0^cD_t^\alpha u))(t_j) = I_j(u(t_j)), & j = 1, 2, \dots, n, \\ u(0) = u(T) = 0. \end{cases}$$

By using critical point theory and variational methods, the authors give some criteria to guarantee that the above-mentioned impulsive problems have at least one solution and infinitely many solutions.

Motivated by the work above, we consider the following problem (1.1) of impulsive fractional differential equations:

$$\begin{cases} -\frac{1}{2} \frac{d}{dt} ({}_0D_t^{-\beta} + {}_tD_T^{-\beta})u'(t) = a(t)u(t) + \lambda \nabla F(t, u(t)), & t \neq t_k, \text{ a.e. } t \in [0, T], \\ \Delta(D_t^\alpha u)(t_k) = \mu I_k(u(t_k)), & t_k \in (0, T), k = 1, 2, \dots, l, \\ u(0) = u(T) = 0, \end{cases} \quad (1.1)$$

where $\beta \in [0, 1)$, $\alpha = 1 - \frac{\beta}{2} \in (\frac{1}{2}, 1]$, ${}_0D_t^{-\beta}$, ${}_tD_T^{-\beta}$ are the left and right Riemann-Liouville fractional integrals of order β , ${}_0^cD_t^\alpha$ and ${}_t^cD_T^\alpha$ are the left and right Caputo fractional derivative of order α , respectively, $0 = t_0 < t_1 < t_2 < \dots < t_l < t_{l+1} = T$, $F: [0, T] \times \mathbb{R}^N \rightarrow \mathbb{R}$ a given function satisfying some assumptions and $\nabla F(t, x)$ is the gradient of F at x , $I_k \in C([0, T], \mathbb{R})$, $a \in C[0, T]$ and

$$\begin{aligned} (D_t^\alpha u)(t) &= \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\}(t), \\ \Delta(D_t^\alpha u)(t_k) &= \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\}(t_k^+) \end{aligned}$$

$$\begin{aligned}
 & -\frac{1}{2}\left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\}(t_k^-), \\
 \frac{1}{2}\left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\}(t_k^+) &= \lim_{t \rightarrow t_k^+} \frac{1}{2}\left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\}(t), \\
 \frac{1}{2}\left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\}(t_k^-) &= \lim_{t \rightarrow t_k^-} \frac{1}{2}\left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\}(t)
 \end{aligned}$$

for $k = 1, \dots, l$.

In this paper, the existence results of infinitely many solutions of (1.1) are established. Our method is different from [3, 18, 20] and our results for (1.1) are new. The rest of this paper is organized as follows. In Section 2, some definitions and lemmas which are essential to prove our main results are stated. In Section 3, we give the main results. At last, one example is offered to demonstrate the application of our main results.

2. Preliminaries

At first, we present the necessary definitions for the fractional calculus theory and several lemmas which are used further in this paper.

Definition 2.1 ([12]). Let f be a function defined on $[a, b]$. The left and right Riemann-Liouville fractional integrals of order α for function f are denoted by ${}_aD_t^{-\alpha}$ and ${}_tD_b^{-\alpha}$, respectively, and are defined by

$$\begin{aligned}
 {}_aD_t^{-\alpha}f(t) &= \frac{1}{\Gamma(\alpha)} \int_a^t (t-s)^{\alpha-1}f(s)ds, \\
 {}_tD_b^{-\alpha}f(t) &= \frac{1}{\Gamma(\alpha)} \int_t^b (s-t)^{\alpha-1}f(s)ds,
 \end{aligned}$$

for $t \in [a, b], \alpha > 0$.

The left and right Riemann-Liouville fractional derivatives of order α for function f are denoted by ${}_aD_t^{-\alpha}f(t)$ and ${}_tD_b^{-\alpha}f(t)$, respectively, and are defined by

$$\begin{aligned}
 {}_aD_t^{-\alpha}f(t) &= \frac{d^n}{dt^n} {}_aD_t^{\alpha-n}f(t) = \frac{1}{\Gamma(n-\alpha)} \frac{d^n}{dt^n} \int_a^t (t-s)^{n-\alpha-1}f(s)ds, \\
 {}_tD_b^{-\alpha}f(t) &= (-1)^n \frac{d^n}{dt^n} {}_tD_b^{\alpha-n}f(t) = \frac{(-1)^n}{\Gamma(n-\alpha)} \frac{d^n}{dt^n} \int_t^b (s-t)^{n-\alpha-1}f(s)ds,
 \end{aligned}$$

for $t \in [a, b], n-1 \leq \alpha < n, n \in \mathbb{N}$.

The above conditions ensure that the right hand side integral is well-defined as pointwise on $[a, b]$.

Lemma 2.2 ([12]). *The left and right Riemann-Liouville fractional integral operators have the property of a semi-group, i.e.*

$${}_aD_t^{-\gamma_1}({}_aD_t^{-\gamma_2}f(t)) = {}_aD_t^{-\gamma_1-\gamma_2}f(t) \text{ and } {}_tD_b^{-\gamma_1}({}_tD_b^{-\gamma_2}f(t)) = {}_tD_b^{-\gamma_1-\gamma_2}f(t), \forall \gamma_1, \gamma_2 > 0,$$

for a.e. $t \in [a, b]$ and $f \in L^1([a, b], \mathbb{R}^N)$.

Definition 2.3 ([12]). If $\alpha \in (n-1, n)$ and $f \in AC^n([a, b], \mathbb{R})$, then the left and right Caputo fractional derivatives of order of a function f are denoted by ${}_a^cD_t^\alpha f(t)$ and ${}_t^cD_b^\alpha f(t)$, respectively, and are defined by

$$\begin{aligned}
 {}_a^cD_t^\alpha f(t) &= {}_aD_t^{\alpha-n} \frac{d^n}{dt^n} f(t) = \frac{1}{\Gamma(n-\alpha)} \int_a^t (t-s)^{n-\alpha-1}f^{(n)}(s)ds, \\
 {}_t^cD_b^\alpha f(t) &= (-1)^n {}_tD_b^{\alpha-n} \frac{d^n}{dt^n} f(t) = \frac{(-1)^n}{\Gamma(n-\alpha)} \int_t^b (s-t)^{n-\alpha-1}f^{(n)}(s)ds,
 \end{aligned}$$

for $t \in [a, b]$.

In view of Definition 2.1 and Lemma 2.2, we can easily transfer (1.1) to the following problem

$$\begin{cases} \frac{d}{dt} \left\{ \frac{1}{2} {}_0D_t^{\alpha-1} ({}_0^cD_t^\alpha u(t)) - \frac{1}{2} {}_tD_T^{\alpha-1} ({}_t^cD_T^\alpha u(t)) \right\} + a(t)u(t) + \lambda \nabla F(t, u(t)) = 0, & t \neq t_k, \text{ a.e. } t \in [0, T], \\ \Delta(D_t^\alpha u)(t_k) = \mu I_k(u(t_k)), & t_k \in (0, T), k = 1, 2, \dots, l, \\ u(0) = u(T) = 0, \end{cases} \quad (2.1)$$

where $\alpha = 1 - \frac{\beta}{2} \in (\frac{1}{2}, 1]$, ${}_0D_t^{\alpha-1}, {}_tD_T^{\alpha-1}$ are the left and right Riemann-Liouville fractional integrals of order $1 - \alpha$, ${}_0^cD_t^\alpha$ and ${}_t^cD_T^\alpha$ are the left and right Caputo fractional derivative of order α , respectively, and $(D_t^\alpha u)(t_k) = \frac{1}{2} \{ {}_0D_t^{\alpha-1} ({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1} ({}_t^cD_T^\alpha u) \}(t_k)$ for $k = 1, \dots, l$.

Then the problem (1.1) is equivalent to the problem (2.1). Therefore a solution of the problem (2.1) corresponds to a solution of the BVP (1.1).

In order to establish a variational structure which enables us to reduce the existence of solution of problem (2.1) to the existence of the critical point of corresponding functional, we construct the following appropriate function spaces.

Let us recall that for any fixed $t \in [0, T]$ and $1 \leq p \leq \infty$,

$$\|u\|_\infty = \max_{t \in [0, T]} |u(t)|, \quad \|u\|_{L^p} = \left(\int_0^T |u(s)|^p ds \right)^{\frac{1}{p}}.$$

Let $0 < \alpha \leq 1$, we define the fractional derivative spaces E_0^α by the closure of $C_0^\infty([0, T])$ with respect to the weighted norm $\|u\|_\alpha = (\int_0^T |{}_0^cD_t^\alpha u(t)|^2 dt + \int_0^T |u(t)|^2 dt)^{\frac{1}{2}}$, for all $u \in E_0^\alpha$, where

$$C_0^\infty([0, T]) = \{u \in C_0^\infty([0, T]) : u(0) = u(T) = 0\}.$$

Clearly, the fractional derivative space E_0^α is the space of functions $u \in L^2([0, T] \setminus \{t_1, t_2, \dots, t_l\})$ having α -order Caputo left and right fractional derivatives and Riemann-Liouville left and right fractional derivatives, ${}_0^cD_t^\alpha, {}_t^cD_T^\alpha, {}_0D_t^\alpha \in L^2([0, T] \setminus \{t_1, t_2, \dots, t_l\})$ and $u(0) = u(T) = 0$.

Lemma 2.4 ([10]). *Let $\frac{1}{2} < \alpha \leq 1$ and $1 < p < \infty$ for all $u \in E_0^\alpha$, one has*

$$\|u\|_{L^p} \leq \frac{T^\alpha}{\Gamma(\alpha + 1)} \|{}_0^cD_t^\alpha u\|_{L^p}. \quad (2.2)$$

Moreover, if $\alpha > \frac{1}{p}$ and $\frac{1}{p} + \frac{1}{q} = 1$, then

$$\|u\|_\infty \leq \frac{T^{\alpha - 1/p}}{\Gamma(\alpha) ((\alpha - 1)q + 1)^{\frac{1}{q}}} \|{}_0^cD_t^\alpha u\|_{L^p}. \quad (2.3)$$

Then we can conclude that $\|u\|_\alpha = (\int_0^T |{}_0^cD_t^\alpha u(t)|^2 dt + \int_0^T |u(t)|^2 dt)^{\frac{1}{2}}$ is equivalent to $\|u\|_\alpha = (\int_0^T |{}_0^cD_t^\alpha u(t)|^2 dt)^{\frac{1}{2}}$, for all $u \in E_0^\alpha$.

In the following, we will consider the fractional derivative spaces E_0^α with respect to the norm $\|u\|_\alpha = (\int_0^T |{}_0^cD_t^\alpha u(t)|^2 dt)^{\frac{1}{2}}$. By the discussion in [10], we know E_0^α is a reflexive and separable Banach space with the norm $\|u\|_\alpha = (\int_0^T |{}_0^cD_t^\alpha u(t)|^2 dt)^{\frac{1}{2}}$.

The following concepts are similar to Definition 2.1 and 2.2 in [3].

Definition 2.5.

$$u \in \left\{ u \in AC([0, T]) : \int_{t_j}^{t_{j+1}} \left(\int_0^T |{}_0^cD_t^\alpha u(t)|^2 + \int_0^T |u(t)|^2 \right)^{\frac{1}{2}} dt < \infty, j = 0, \dots, l \right\},$$

is called a classic solution of the problem (2.1) if

(i)

$$\begin{aligned} \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} (t_k^+) &= \lim_{t \rightarrow t_k^+} \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} (t), \\ \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} (t_k^-) &= \lim_{t \rightarrow t_k^-} \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} (t), \end{aligned}$$

exist and satisfy the impulsive condition $\Delta(D_t^\alpha)(t_k) = I_k(u(t_k))$ and the boundary condition $u(0) = u(T) = 0$ holds;

(ii) u satisfies (1.1) a.e. on $t \in [0, T] \setminus \{t_1, t_2, \dots, t_l\}$.

Definition 2.6. A function $u \in E_0^\alpha$ is called a weak solution of the problem (2.1) if

$$\begin{aligned} \int_0^T \left\{ -\frac{1}{2} [{}_0^cD_t^\alpha u(t) {}_t^cD_T^\alpha v(t) + {}_t^cD_T^\alpha u(t) {}_0^cD_t^\alpha v(t)] - a(t)u(t)v(t) \right\} dt \\ + \mu \sum_{j=1}^l I_j(u(t_j))v(t_j) - \lambda \int_0^T \nabla F(t, u(t))v(t) dt = 0, \end{aligned}$$

for all $v(t) \in E_0^\alpha$.

Similar to the proof of Lemma 2.1 in [3], we have the following lemma.

Lemma 2.7. The function $u \in E_0^\alpha$ is a classical solution of (2.1) if and only if u is a weak solution of (2.1).

Proof. By standard arguments, if $u \in E_0^\alpha$ is a classical solution of (2.1), then u is a weak solution of (2.1). Conversely, let $u \in E_0^\alpha$ be a weak solution of (2.1), we prove that u is a classical solution of (2.1).

If $u \in E_0^\alpha$ is a weak solution of (2.1), for a fixed $j \in \{0, 1, \dots, l\}$, we choose a function w_j such that $w_j = 0$, for $t \in [0, t_j] \cup [t_{j+1}, T]$. Similar to the proof of Lemma 2.1 in [3], we can obtain

$$\int_{t_j}^{t_{j+1}} -\frac{1}{2} [{}_0^cD_t^\alpha u(t) {}_t^cD_T^\alpha w_j(t) + {}_t^cD_T^\alpha u(t) {}_0^cD_t^\alpha w_j(t)] dt = \int_{t_j}^{t_{j+1}} [a(t)u(t) + \lambda \nabla F(t, u(t))] w_j(t) dt$$

with

$$\int_{t_j}^{t_{j+1}} -\frac{1}{2} [{}_0^cD_t^\alpha u(t) {}_t^cD_T^\alpha w_j(t) + {}_t^cD_T^\alpha u(t) {}_0^cD_t^\alpha w_j(t)] dt < \infty,$$

which shows

$$\frac{d}{dt} \left\{ \frac{1}{2} {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u(t)) - \frac{1}{2} {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u(t)) \right\} + a(t)u(t) + \lambda \nabla F(t, u(t)) = 0,$$

for almost all $t \in (t_j, t_{j+1})$. Then u satisfies the first equation of (2.1) for almost all $t \in (0, T)$.

Also similar to the proof of Lemma 2.1 in [3], we can prove

$$\frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} \in AC([t_j, t_{j+1}]),$$

and there exist the limits

$$\begin{aligned} \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} (t_k^+) &= \lim_{t \rightarrow t_k^+} \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} (t), \\ \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} (t_k^-) &= \lim_{t \rightarrow t_k^-} \frac{1}{2} \left\{ {}_0D_t^{\alpha-1}({}_0^cD_t^\alpha u) - {}_tD_T^{\alpha-1}({}_t^cD_T^\alpha u) \right\} (t). \end{aligned}$$

Multiplying $\Delta(D_t^\alpha u)(t_k)$ by $v \in E_0^\alpha$ and integrating by parts, due to the definition of weak solution and Proposition 2.4 in [3], we can get

$$\sum_{k=1}^l \Delta(D_t^\alpha u)(t_k)v(t_k) = \sum_{k=1}^l \mu I_k(u(t_k))v(t_k). \tag{2.4}$$

Let $v_j(t_k) = \delta_{jk}$, it follows from (2.4) that $\Delta(D_t^\alpha u)(t_k) = \mu I_k(u(t_k)), k = 1, 2, \dots, l$. Then the impulsive conditions of (2.1) are satisfied. Hence u is a classical solution of (2.1). \square

Similar to some properties in [10], we have the following results.

Lemma 2.8. *Let $0 < \alpha \leq 1$. The fractional derivative space E_0^α is a reflexive and a separable Banach space.*

Lemma 2.9. *Let $\frac{1}{2} < \alpha \leq 1$ and the sequence $\{u_k\}$ converges weakly to u in E_0^α . Then $u_k \rightarrow u$ in $C([0, T], \mathbb{R})$, that is, $\|u_k - u\|_\infty \rightarrow 0$ as $k \rightarrow \infty$.*

Lemma 2.10. *Let $\frac{1}{2} < \alpha \leq 1$. For any $u \in E_0^\alpha$, one has*

$$|\cos(\pi\alpha)| \|u\|_\alpha^2 \leq - \int_0^T {}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha u(t) dt \leq \frac{1}{|\cos(\pi\alpha)|} \|u\|_\alpha^2.$$

Proof. Noticing that $\cos(\pi\alpha) \in [-1, 0)$ for $\alpha \in (\frac{1}{2}, 1]$, by calculation, we have

$$- \int_0^T {}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha u(t) dt \geq -\cos(\pi\alpha) \int_0^T |{}_0^c D_t^\alpha u(t)|^2 dt = |\cos(\pi\alpha)| \int_0^T |{}_0^c D_t^\alpha u(t)|^2 dt = |\cos(\pi\alpha)| \|u\|_\alpha^2.$$

By using Young’s inequality and a standard derivation, we can get another inequality. For more details, one can see Proposition 4.1 in [10]. \square

Finally, we recall the following critical point theorem.

Lemma 2.11. *Let X be a reflexive real Banach space $\Phi, \Psi: X \rightarrow \mathbb{R}$ be two Gâteaux differentiable functionals such that Φ is sequentially weakly lower semi-continuous, strongly continuous, and coercive, and Ψ is sequentially weakly upper semicontinuous. For every $r > \inf_X \Phi$, let us put*

$$\varphi(r) = \inf_{u \in \Phi^{-1}([-\infty, r])} \frac{\sup_{v \in \Phi^{-1}([-\infty, r])} \Psi(v) - \Psi(u)}{r - \Phi(u)}$$

and

$$\gamma = \liminf_{r \rightarrow +\infty} \varphi(r), \quad \delta = \liminf_{r \rightarrow (\inf_X \Phi)^+} \varphi(r).$$

(1) *If $\gamma < +\infty$, then, for each $\lambda \in]0, \frac{1}{\gamma}[$, the following alternative holds: either the functional $\Phi - \lambda\Psi$ has a global minimum, or there exists a sequence $\{u_n\}$ of critical points (local minima) of $\Phi - \lambda\Psi$ such that $\lim_{n \rightarrow +\infty} \Phi(u_n) = +\infty$.*

(2) *If $\delta < +\infty$, then, for each $\lambda \in]0, \frac{1}{\delta}[$, the following alternative holds: either there exists a global minimum of Φ which is a local minimum of $\Phi - \lambda\Psi$, or there exists a sequence $\{u_n\}$ of pairwise distinct critical points (local minima) of $\Phi - \lambda\Psi$, with $\lim_{n \rightarrow +\infty} \Phi(u_n) = \inf_X \Phi$, which weakly converges to a global minimum of Φ .*

3. Main results

Define

$$\Phi(u) = \int_0^T -\frac{1}{2} {}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha u(t) dt - \frac{1}{2} \int_0^T a(t)u^2(t) dt, \tag{3.1}$$

$$\Psi(u) = \int_0^T F(t, u(t)) dt - \frac{\mu}{\lambda} \sum_{j=1}^l \int_0^{u(t_j)} I_j(s) ds. \tag{3.2}$$

Clearly, Φ, Ψ are Gâteaux differentiable functionals whose Gâteaux derivatives at the point $u \in E_0^\alpha$ are given by

$$\begin{aligned} \Phi'(u)v &= \int_0^T -\frac{1}{2} [{}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha v(t) + {}_t^c D_T^\alpha u(t) {}_0^c D_t^\alpha v(t)] dt - \int_0^T a(t)u(t)v(t) dt, \\ \Psi'(u)v &= \int_0^T \nabla F(t, u(t))v(t) dt - \frac{\mu}{\lambda} \sum_{j=1}^l I_j(u(t_j))v(t_j). \end{aligned}$$

Then the critical point of $\Phi - \lambda\Psi$ is exactly the weak solution of the problem (2.1). By Lemma 2.7, it is the classical solution of the problem (2.1). By the equivalence of (1.1) and (2.1), we know it is also a classical solution of (1.1).

Throughout this paper, we assume that

(H₁) $\lambda, \mu > 0$ are real parameters, $\beta \in [0, 1), \alpha = 1 - \frac{\beta}{2} \in (\frac{1}{2}, 1], F: [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a function such that $F(\cdot, x)$ is continuous in $[0, T]$ for every $x \in \mathbb{R}, F(\cdot, x)$ is a C^1 -function in \mathbb{R} for any $t \in [0, T]$, and $\nabla F(t, x)$ is the gradient of F at $x, a \in C[0, T]$ and there exist two positive constants a_1 and a_2 such that $0 < a_1 \leq a \leq a_2, I_j \in C([0, T], \mathbb{R}^+), j = 1, \dots, l$.

By the assumptions (H₁), (3.1), (3.2), we can easily get the following lemma.

Lemma 3.1. *Let $\alpha \in (\frac{1}{2}, 1]$ and assumption (H₁) be satisfied. If $u \in E_0^\alpha$, then the functional $\Phi: E^\alpha \rightarrow \mathbb{R}^N$ denoted by (3.1) is convex and continuous on E_0^α .*

Proof. From Definition 2.3, (H₁), and (3.1), it is easy to see that $\Phi: E^\alpha \rightarrow \mathbb{R}^N$ is continuous. From (H₁), by a standard argument, we can easily prove that $\frac{1}{2} \int_0^T a(t)u^2(t)dt$ is convex. So in order to show Φ is convex, we only need to prove the convexity of $\int_0^T -\frac{1}{2} {}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha u(t) dt$.

We denote

$$H(u) = \int_0^T -\frac{1}{2} {}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha u(t) dt.$$

Let $\lambda \in (0, 1), u, v \in E_0^\alpha, \bar{u}, \bar{v}$ be the extension of u and v by zero on $\mathbb{R}/[0, T]$. Since the Caputo fractional derivative operator is linear operator, then by Lemma 5.1 in [10], we have

$$\begin{aligned} H[(1-\lambda)u + \lambda v] &= -\frac{1}{2} \int_0^T {}_0^c D_t^\alpha [(1-\lambda)u(t) + \lambda v(t)] {}_t^c D_T^\alpha [(1-\lambda)u(t) + \lambda v(t)] dt \\ &= \frac{|\cos(\pi\alpha)|}{2} \int_{-\infty}^{+\infty} | {}_{-\infty} D_t^\alpha [(1-\lambda)\bar{u}(t) + \lambda\bar{v}(t)] |^2 dt \\ &\leq \frac{|\cos(\pi\alpha)|}{2} \int_{-\infty}^{+\infty} [(1-\lambda) | {}_{-\infty} D_t^\alpha \bar{u}(t) |^2 + \lambda | {}_{-\infty} D_t^\alpha \bar{v}(t) |^2] dt \\ &= \int_0^T \left[-\frac{1-\lambda}{2} ({}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha u(t)) - \frac{\lambda}{2} ({}_0^c D_t^\alpha v(t) {}_t^c D_T^\alpha v(t)) \right] dt \\ &= (1-\lambda)H(u) + \lambda H(v). \end{aligned}$$

Then $H(u)$ is convex on E_0^α , which also implies the convexity of Φ . The proof is complete. □

For convenience, we put

$$M = \Gamma(\alpha) \sqrt{\frac{(2\alpha - 1)}{T [|\cos(\pi\alpha)| T^{2(\alpha-1)} - a_2 \Gamma^2(\alpha) (2\alpha - 1)] }},$$

$$\lambda_1 = \frac{1}{2[M^2\Gamma(d+1) + B(\alpha, T)]}, \quad \lambda_2 = \frac{1}{2M^2\Gamma(d+1)},$$

where

$$B(\alpha, T) = \frac{36}{\Gamma^2} \left\{ \frac{1 + (\frac{1}{6})^{3-2\alpha} + (\frac{5}{6})^{3-2\alpha}}{3-2\alpha} T^{3-2\alpha} - 2 \int_{\frac{T}{6}}^T [t(t - \frac{1}{6}T)]^{(1-\alpha)} dt - 2 \int_{\frac{5T}{6}}^T [(t(t - \frac{5T}{6}))^{(1-\alpha)} - ((t - \frac{1}{6}T)(t - \frac{5T}{6}))^{(1-\alpha)}] dt \right\}.$$

Theorem 3.2. Let (H_1) hold. Assume

$$\frac{7B(\alpha, T)}{3|\cos(\pi\alpha)|\Gamma^2(2-\alpha)\Gamma} < a_1 \leq a_2 < \frac{|\cos(\pi\alpha)|}{\Gamma^2(\alpha)(2\alpha-1)} T^{2(\alpha-1)}. \tag{3.3}$$

If there exists a positive constant μ_0 such that $\mu_0 b \leq \frac{a_1}{8}$ and the following hypotheses (H_2) - (H_3) are satisfied:

(H_2) $F(t, u) \geq 0$ for $(t, u) \in [0, T] \times \mathbb{R}^+$ and $\limsup_{s \rightarrow +\infty} \frac{F(t, s)}{s^2} = d < +\infty$, for a.e $t \in [0, T]$.

(H_3) For any $j = 1, \dots, l$, there exists $b_j > 0$ such that

$$\limsup_{|s| \rightarrow \infty} \frac{I_j(s)}{s^2} \leq b_j,$$

where $b = \max_{1 \leq j \leq l} b_j$. Then for any $\lambda \in]\lambda_1, \lambda_2[$, $\mu \in [0, \mu_0[$, the problem (1.1) possesses an unbounded sequence of solutions in E_0^α .

Proof. We note that (H_3) implies there exist a positive constant a_3 large enough such that

$$I_j(s) < b_j s^2 \text{ for } |s| > a_3, j = 1, \dots, l.$$

For any $j = 1, \dots, l$, from the continuity of $I_j(s)$, we conclude that $I_j(s)$ is bounded for $|s| \leq a_3, t \in [0, T]$. Then there exist constants $c_j > 0$ such that

$$I_j(s) < c_j,$$

for $|s| \leq a_3, j = 1, \dots, l$.

Hence, for $s \in \mathbb{R}, j = 1, \dots, l$, we can get

$$I_j(s) < c_j + b_j s^2.$$

Then it follows that

$$\sum_{j=1}^l \int_0^{u(t_j)} I_j(s) ds \leq b \int_0^T s^2 ds + c_0 T, \tag{3.4}$$

where $b = \max_{1 \leq j \leq l} b_j, c_0 = \max_{1 \leq j \leq l} c_j$.

From (H_2) , there exists a positive constant e_0 large enough such that

$$F(t, s) < (d+1)s^2 \text{ for } |s| > e_0.$$

From (H_1) , we know $F(t, \cdot)$ is a function in \mathbb{R} for any $t \in [0, T]$. So we conclude that $F(t, s)$ is bounded for $|s| \leq e_0, t \in [0, T]$. Then there exists a constant $d_1 > 0$ such that

$$|F(t, s)| < d_1,$$

for $|s| \leq e_0, t \in [0, T]$.

Hence, for $s \in \mathbb{R}, t \in [0, T]$, we have

$$|F(t, s)| < d_1 + (d + 1)s^2. \tag{3.5}$$

Now, we prove all the conditions of Lemma 2.11 hold.

By Lemma 3.1 and (H_1) , we know that Φ is continuously Gâteaux differentiable and convex. Let $u_n \rightharpoonup u$ weakly in E_0^α , by Lemma 2.9, it is easy to know

$$\liminf_{n \rightarrow \infty} \Phi(u_n) = \liminf_{n \rightarrow \infty} \int_0^T -\frac{1}{2} {}_0^c D_t^\alpha u_n(t) {}_t^c D_T^\alpha u_n(t) dt \geq \int_0^T -\frac{1}{2} {}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha u(t) dt = \Phi(u),$$

so Φ is weakly sequentially lower semi-continuous.

Moreover, it follows from (2.2) and Lemma 2.10 that Φ is coercive.

From (H_1) and (3.2), we can conclude that the functional Ψ is continuously Gâteaux differentiable with $\Psi'(u)v = \int_0^T \nabla F(t, u(t))v(t) dt - \frac{\mu}{\lambda} \sum_{j=1}^l I_j(u(t_j))v(t_j)$. By a standard procedure (see [19]), we can prove the derivative of Ψ is compact. By Fatou’s Lemma, one has

$$\limsup_{n \rightarrow \infty} \int_0^T F(t, u_n(t)) dt \leq \int_0^T F(t, u(t)) dt.$$

Then we can easily get that Ψ is sequentially weakly upper semicontinuous.

Next, we divide our proof into three steps.

Step 1. We prove that $\gamma < +\infty$. Let ρ_n be a sequence of positive numbers such that $\lim_{n \rightarrow \infty} \rho_n = +\infty$. We choose $r_n = \frac{\rho_n^2}{2M^2}$ for all $n \in \mathbb{N}$. For $v \in E_0^\alpha$, if $\Phi(v) \leq r_n$, by Lemma 2.10 and (2.3), it follows that

$$\begin{aligned} \frac{\rho_n^2}{2M^2} = r_n &\geq \Phi(v) = \int_0^T -\frac{1}{2} {}_0^c D_t^\alpha u(t) {}_t^c D_T^\alpha u(t) dt - \frac{1}{2} \int_0^T a(t)u^2(t) dt \\ &> \frac{1}{2} \left[|\cos(\pi\alpha)| \|u\|_\alpha^2 - a_2 T \|u\|_\infty^2 \right] \\ &> \frac{1}{2} \left[|\cos(\pi\alpha)| \frac{T^{2\alpha-1}}{\Gamma^2(\alpha)(2\alpha-1)} - a_2 T \right] \|u\|_\infty^2. \end{aligned}$$

By (3.3), we know

$$\frac{1}{2} \left[|\cos(\pi\alpha)| \frac{T^{2\alpha-1}}{\Gamma^2(\alpha)(2\alpha-1)} - a_2 T \right] > 0.$$

Then it is easily gotten that $\|u\|_\infty \leq \rho_n$, which implies that

$$\Phi^{-1}]-\infty, r_n[= \{v: \Phi(v) < r_n\} \subseteq \{v: \|v\|_\infty < \rho_n\} \subseteq \{v: |v| < \rho_n\}.$$

It follows from (3.2), (3.5), and (H_1) that

$$\begin{aligned} \gamma = \liminf_{r \rightarrow +\infty} \varphi(r) &\leq \liminf_{n \rightarrow +\infty} \varphi(r_n) = \liminf_{n \rightarrow +\infty} \inf_{u \in \Phi^{-1}]-\infty, r_n[} \frac{\sup_{v \in \Phi^{-1}]-\infty, r_n[} \Psi(v) - \Psi(u)}{r_n - \Phi(u)} \\ &\leq \liminf_{n \rightarrow +\infty} \frac{\sup_{v \in \Phi^{-1}]-\infty, r_n[} \Psi(v)}{r_n} \\ &\leq \lim_{n \rightarrow \infty} \sup_{|v| < \rho_n} \frac{2M^2 \int_0^T F(t, v(t)) dt}{\rho_n^2} \\ &\leq \lim_{n \rightarrow \infty} 2M^2 \frac{T[d_1 + (d + 1)\rho_n^2]}{\rho_n^2} \\ &= 2M^2 T(d + 1) < +\infty. \end{aligned}$$

Step 2. We show that $]\lambda_1, \lambda_2[\subset]0, \frac{1}{\gamma}[$.
 From the proof of Step 1, we have

$$\gamma \geq 2M^2T(d+1) = \frac{1}{\lambda_2}. \tag{3.6}$$

Assume $\{x_n\}$ is a positive real sequence with $x_n \rightarrow +\infty$ as $n \rightarrow +\infty$. We define functions ω_n by

$$\omega_n = \begin{cases} \frac{6\Gamma(2-\alpha)x_n t}{T}, & t \in \left[0, \frac{T}{6}\right), \\ \Gamma(2-\alpha)x_n, & t \in \left[\frac{T}{6}, \frac{5T}{6}\right], \\ \frac{6\Gamma(2-\alpha)x_n}{T}(T-t), & t \in \left(\frac{5T}{6}, T\right]. \end{cases}$$

It is easy to verify that $\omega_n(0) = \omega_n(T) = 0$ and $\omega_n \in L^2[0, T]$. By Definition 2.3, we can directly calculate the left Caputo fractional derivative of order α for ω_n .

If $t \in [0, \frac{T}{6})$, one has

$${}^C_0D_t^\alpha f(t) = \frac{1}{T(1-\alpha)} \int_0^t (t-s)^{-\alpha} \frac{6\Gamma(2-\alpha)x_n}{T} ds = \frac{6\Gamma(2-\alpha)x_n}{T} \frac{(t-s)^{1-\alpha}}{1-\alpha} \Big|_t^0 = \frac{6x_n t^{1-\alpha}}{T}.$$

If $t \in [\frac{T}{6}, \frac{5T}{6}]$, we get

$$\begin{aligned} {}^C_0D_t^\alpha f(t) &= \frac{1}{T(1-\alpha)} \int_0^t (t-s)^{-\alpha} f'(s) ds \\ &= \frac{1}{T(1-\alpha)} \left[\int_0^{\frac{T}{6}} (t-s)^{-\alpha} \frac{6\Gamma(2-\alpha)x_n}{T} ds + \int_{\frac{T}{6}}^t (t-s)^{-\alpha} 0 ds \right] \\ &= \frac{6\Gamma(2-\alpha)x_n}{T} \frac{(t-s)^{1-\alpha}}{1-\alpha} \Big|_{\frac{T}{6}}^0 = \frac{6x_n(t^{1-\alpha} - (t - \frac{T}{6})^{1-\alpha})}{T}. \end{aligned}$$

If $t \in (\frac{5T}{6}, T]$, we can obtain

$$\begin{aligned} {}^C_0D_t^\alpha f(t) &= \frac{1}{T(1-\alpha)} \int_0^t (t-s)^{-\alpha} f'(s) ds \\ &= \frac{1}{T(1-\alpha)} \left[\int_0^{\frac{T}{6}} (t-s)^{-\alpha} \frac{6\Gamma(2-\alpha)x_n}{T} ds + \int_{\frac{T}{6}}^{\frac{5T}{6}} (t-s)^{-\alpha} 0 ds - \int_{\frac{5T}{6}}^t (t-s)^{-\alpha} \frac{6\Gamma(2-\alpha)x_n}{T} ds \right] \\ &= \frac{6\Gamma(2-\alpha)x_n}{T} \left[\frac{(t-s)^{1-\alpha}}{1-\alpha} \Big|_{\frac{T}{6}}^0 - \frac{(t-s)^{1-\alpha}}{1-\alpha} \Big|_t^{\frac{5T}{6}} \right] \\ &= \frac{6x_n [t^{1-\alpha} - (t - \frac{T}{6})^{1-\alpha}] - (t - \frac{5T}{6})^{1-\alpha}}{T}. \end{aligned}$$

Then

$$\begin{aligned} \|\omega_n\|_\alpha^2 &= \int_0^T \left[{}^C_0D_t^\alpha \omega_n(t) \right]^2 dt \\ &= \int_0^{\frac{T}{6}} \left(\frac{6x_n t^{1-\alpha}}{T} \right)^2 dt + \int_{\frac{T}{6}}^{\frac{5T}{6}} \left[\frac{6x_n (t^{1-\alpha} - (t - \frac{T}{6})^{1-\alpha})}{T} \right]^2 dt \end{aligned}$$

$$\begin{aligned}
 & + \int_{\frac{5T}{6}}^T \left[\frac{6x_n \left[t^{1-\alpha} - \left(t - \frac{T}{6}\right)^{1-\alpha} - \left(t - \frac{5T}{6}\right)^{1-\alpha} \right]}{T} \right]^2 dt \\
 & = \frac{36x_n^2}{T^2} \left\{ \int_0^T t^{2(1-\alpha)} dt + \int_{\frac{T}{6}}^{\frac{5T}{6}} \left(t - \frac{1}{6}T\right)^{2(1-\alpha)} dt + \int_{\frac{5T}{6}}^T \left(t - \frac{5T}{6}\right)^{2(1-\alpha)} dt \right. \\
 & \quad \left. - 2 \int_{\frac{T}{6}}^T \left[t\left(t - \frac{1}{6}T\right)\right]^{(1-\alpha)} dt - 2 \int_{\frac{5T}{6}}^T \left[\left(t\left(t - \frac{5T}{6}\right)\right)^{(1-\alpha)} - \left(\left(t - \frac{T}{6}\right)\left(t - \frac{5T}{6}\right)\right)^{(1-\alpha)}\right] dt \right\} \\
 & = \frac{36x_n^2}{T^2} \left\{ \frac{1 + \left(\frac{1}{6}\right)^{3-2\alpha} + \left(\frac{5}{6}\right)^{3-2\alpha}}{3-2\alpha} T^{3-2\alpha} - 2 \int_{\frac{T}{6}}^T \left[t\left(t - \frac{1}{6}T\right)\right]^{(1-\alpha)} dt \right. \\
 & \quad \left. - 2 \int_{\frac{5T}{6}}^T \left[\left(t\left(t - \frac{5T}{6}\right)\right)^{(1-\alpha)} - \left(\left(t - \frac{T}{6}\right)\left(t - \frac{5T}{6}\right)\right)^{(1-\alpha)}\right] dt \right\} \\
 & = B(\alpha, T)x_n^2.
 \end{aligned}$$

So we can see $B(\alpha, T) = \frac{\|\omega_n\|_\alpha^2}{x_n^2} \geq 0$. It follows that

$$0 < \lambda_1 = \frac{1}{2[M^2T(d+1) + B(\alpha, T)]} < \lambda_2. \tag{3.7}$$

Together with (3.6) and (3.7), we can obtain that

$$] \lambda_1, \lambda_2 [\subset] 0, \frac{1}{\gamma} [.$$

Step 3. We verify that the operator $\Phi - \lambda\Psi$ is unbounded from below, which implies $\Phi - \lambda\Psi$ has no global minimum. By (3.1) and Lemma 2.10, for $\omega_n \in E_0^\alpha$, one has

$$\begin{aligned}
 \Phi(\omega_n) & = \int_0^T -\frac{1}{2} {}_0^c D_t^\alpha \omega_n(t) {}_t^c D_T^\alpha \omega_n(t) dt - \frac{1}{2} \int_0^T a(t) \omega_n^2(t) dt \\
 & \leq \frac{1}{2|\cos(\pi\alpha)|} \|\omega_n\|_\alpha^2 - \frac{1}{2} \int_0^T a(t) \omega_n^2(t) dt \\
 & = \frac{1}{2} \left[\frac{1}{|\cos(\pi\alpha)|} B(\alpha, T)x_n^2 - \int_0^T a(t) \omega_n^2(t) dt \right].
 \end{aligned} \tag{3.8}$$

From (3.2) and (3.4), for $\omega_n \in E_0^\alpha$, and any $\lambda \in] \lambda_1, \lambda_2 [, \mu \in [0, \mu_0[$, we have

$$\begin{aligned}
 \Psi(\Psi) & = \int_0^T F(t, \omega_n(t)) dt - \frac{\mu}{\lambda} \sum_{j=1}^l \int_0^{u(t_j)} I_j(s) ds \\
 & > \int_0^T F(t, \omega_n(t)) dt - \frac{\mu_0}{\lambda} \left(b \int_0^T \omega_n^2 ds + c_0 T \right) \\
 & = \int_0^T F(t, \omega_n(t)) dt - \frac{\mu_0 b}{\lambda} \int_0^T \omega_n^2(t) dt - \frac{c_0 \mu_0 T}{\lambda}.
 \end{aligned} \tag{3.9}$$

It follows from (3.3), (3.8), (3.9), and the condition $\mu_0 b \leq \frac{\alpha_1}{8}$ that

$$\begin{aligned}
 \Phi(\omega_n) - \lambda\Psi(\omega_n) & < \frac{1}{2} \left[\frac{1}{|\cos(\pi\alpha)|} B(\alpha, T)x_n^2 - \int_0^T a(t) \omega_n^2(t) dt. \right] \\
 & \quad - \lambda \int_0^T F(t, \omega_n(t)) dt + \mu_0 b \int_0^T \omega_n^2(t) dt + c_0 \mu_0 T
 \end{aligned}$$

$$\begin{aligned}
 &\leq \frac{1}{2} \left[\frac{1}{|\cos(\pi\alpha)|} B(\alpha, T) x_n^2 - \int_0^T a(t) \omega_n^2(t) dt + \mu_0 b \int_0^T \omega_n^2(t) dt + c_0 \mu_0 T \right] \\
 &= \frac{1}{2|\cos(\pi\alpha)|} B(\alpha, T) x_n^2 - \left(\frac{a_1}{2} - \mu_0 b \right) \left\{ \int_0^{\frac{T}{6}} \left[\frac{6\Gamma(2-\alpha)x_n t}{T} \right]^2 dt \right. \\
 &\quad \left. + \int_{\frac{T}{6}}^{\frac{5T}{6}} [\Gamma(2-\alpha)x_n]^2 dt + \int_{\frac{5T}{6}}^T \left[\frac{6\Gamma(2-\alpha)x_n(T-t)}{T} \right]^2 dt \right\} + c_0 \mu_0 T \\
 &< \frac{1}{2|\cos(\pi\alpha)|} B(\alpha, T) x_n^2 - \left(\frac{a_1}{2} - \mu_0 b \right) \int_{\frac{T}{6}}^{\frac{5T}{6}} [\Gamma(2-\alpha)x_n]^2 dt + c_0 \mu_0 T \\
 &= x_n^2 \left[\frac{B(\alpha, T)}{2|\cos(\pi\alpha)|} - \frac{2T\Gamma^2(2-\alpha)}{3} \left(\frac{a_1}{2} - \mu_0 b \right) \right] + c_0 \mu_0 T \\
 &< -\frac{B(\alpha, T)}{12|\cos(\pi\alpha)|} x_n^2 + c_0 \mu_0 T \\
 &\rightarrow -\infty, \text{ as } n \rightarrow +\infty.
 \end{aligned}$$

Hence, one can obtain

$$\lim_{n \rightarrow +\infty} \Phi(\omega_n) - \lambda \Psi(\omega_n) = -\infty,$$

which yields $\Phi - \lambda \Psi$ is unbounded from below, then $\Phi - \lambda \Psi$ has no global minimum.

So all the conditions of case 1 in Lemma 2.11 are satisfied. By virtue of Lemma 2.11, the functional $\Phi - \lambda \Psi$ admits a sequence $\{u_n\}$ of critical points (local minima) such that $\lim_{n \rightarrow +\infty} \Phi(u_n) = +\infty$. It follows from (3.1) and Lemma 2.10 that

$$\begin{aligned}
 \Phi(u_n) &= \int_0^T -\frac{1}{2} {}_0^c D_t^\alpha u_n(t) {}_t^c D_T^\alpha u_n(t) dt - \frac{1}{2} \int_0^T a(t) u_n^2(t) dt \\
 &\leq \int_0^T -\frac{1}{2} {}_0^c D_t^\alpha u_n(t) {}_t^c D_T^\alpha u_n(t) dt \leq \frac{1}{2|\cos(\pi\alpha)|} \|u\|_\alpha^2,
 \end{aligned}$$

which implies $\lim_{n \rightarrow +\infty} \|u_n\|_\alpha^2 = +\infty$. Then $\{u_n\}$ is an unbounded sequence. That is, the boundary value problem (2.1) has an unbounded sequence of weak solutions. As a consequence of Lemma 2.7, we deduce that the boundary value problem (2.1) possesses an unbounded sequence of classical solutions in E_0^α . Then the problem (1.1) has an unbounded sequence of classical solutions in E_0^α . \square

Remark 3.3. The assumption (H_2) includes the asymptotically quadratic case and subquadratic case for $F(t, s)$. If $F(t, s)$ in (H_2) is superquadratic, we cannot obtain the result by Lemma 2.11. In fact, in this case,

$$\liminf_{n \rightarrow +\infty} \frac{\sup_{v \in \Phi^{-1}([-\infty, r_n])} \Psi(v)}{r_n} \rightarrow +\infty.$$

Next, by the case 2 of Lemma 2.11 and a similar proof, we can get the following existence result of infinitely many solutions of (1.1) converging at zero.

We denote

$$\lambda_3 = \frac{1}{2[M^2 T(d' + 1) + B(\alpha, T)]}, \quad \lambda_4 = \frac{1}{2M^2 T(d' + 1)}.$$

Theorem 3.4. *Let (H_1) hold. Assume*

$$\frac{7B(\alpha, T)}{3|\cos(\pi\alpha)|\Gamma^2(2-\alpha)T} < a_1 \leq a_2 < \frac{|\cos(\pi\alpha)|}{\Gamma^2(\alpha)(2-\alpha)} T^{2(\alpha-1)}.$$

If there exists a positive constant μ'_0 such that $\mu'_0 b' < \frac{a_1}{8}$ and the following hypotheses are satisfied:

(H₂)' $F(t, u) \geq 0$ for $(t, u) \in [0, T] \times \mathbb{R}^+$ and $\limsup_{s \rightarrow 0^+} \frac{F(t, s)}{s^2} = d' > 0$ for a.e. $t \in [0, T]$;

(H₃)' for any $j = 1, \dots, l$, there exists $b'_j > 0$ such that

$$\limsup_{|s| \rightarrow 0^+} \frac{I_j(s)}{s^2} \leq b'_j,$$

where $b' = \max_{1 \leq j \leq l} b'_j$, then for any $\lambda \in]\lambda_3, \lambda_4[$, $\mu \in [0, \mu'_0[$, the problem (1.1) possesses a sequence $\{u_n\}$ of solutions with $\{u_n\}$ converging strongly to 0 in E_0^α .

Finally, we give an example to illustrate the usefulness of our main result. Consider the following impulsive system of fractional differential equations.

Example 3.5.

$$\begin{cases} -\frac{1}{2} \frac{d}{dt} ({}_0D_t^{-0.5} + {}_tD_1^{-0.5})u'(t) = 0.069u(t) + \lambda \nabla F(t, u(t)), & t \neq 50, \text{ a.e., } t \in [0, 100], \\ \Delta(D_t^\alpha u)(50) = \mu \frac{u^2(50)}{50}, \\ u(0) = u(100) = 0. \end{cases} \quad (3.10)$$

From (3.10), we can see that $\beta = 0.5$, $\alpha = 0.75$, $a = 0.069$, $I(u) = \frac{u^2}{50}$, $T = 100$.

Let $F(t, u(t)) = \frac{u^2}{6}$, then it easy to verify the assumptions (H₁)-(H₃) hold with $b = \frac{1}{50}$, $d = \frac{1}{6}$, $a_1 = 0.066$, $a_2 = 0.07$.

We choose $\mu_0 = 0.41$, a direct calculation shows that

$$\frac{7B(\alpha, T)}{3|\cos(\pi\alpha)|\Gamma^2(2-\alpha)T} < a_1 = 0.066 \leq a_2 = 0.07 < \frac{|\cos(\pi\alpha)|}{\Gamma^2(\alpha)(2-\alpha)} T^{2(\alpha-1)}, \quad \mu_0 b = 0.0082 < 0.00825 = \frac{a_1}{8}.$$

Then our results can be applied to the problem (3.10), which shows that the problem (3.10) possesses an unbounded sequence of solutions in E_0^α for $\lambda \in [0.3, 61]$, $\mu \in [0, 0.41]$.

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