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# Existence and multiplicity of solutions for a class of quasilinear elliptic systems in Orlicz-Sobolev spaces 

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Abstract
In this paper, we investigate the following nonlinear and non-homogeneous elliptic system

$$
\begin{cases}-\operatorname{div}\left(\phi_{1}(|\nabla u \mathfrak{u}|) \nabla u\right)=\mathrm{F}_{\mathfrak{u}}(\mathrm{x}, \mathrm{u}, v) & \text { in } \Omega \\ -\operatorname{div}\left(\phi_{2}(|\nabla v|) \nabla v\right)=\mathrm{F}_{v}(x, \mathfrak{u}, v) & \text { in } \Omega \\ \mathfrak{u}=v=0 & \text { on } \partial \Omega\end{cases}
$$

where $\Omega$ is a bounded domain in $\mathbb{R}^{N}(N \geqslant 2)$ with smooth boundary $\partial \Omega$, functions $\phi_{i}(t) t(i=1,2)$ are increasing homeomorphisms from $\mathbb{R}^{+}$onto $\mathbb{R}^{+}$. When $F$ satisfies some ( $\phi_{1}, \phi_{2}$ )-superlinear and subcritical growth conditions at infinity, by using the mountain pass theorem we obtain that system has a nontrivial solution, and when $F$ satisfies an additional symmetric condition, by using the symmetric mountain pass theorem, we obtain that system has infinitely many solutions. Some of our results extend and improve those corresponding results in Carvalho et al. [M. L. M. Carvalho, J. V. A. Goncalves, E. D. da Silva, J. Math. Anal. Appl., 426 (2015), 466-483]. (c)2017 All rights reserved.

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## 1. Introduction

In this paper, we investigate the existence and multiplicity of solutions for the following nonlinear and non-homogeneous elliptic system in Orlicz-Sobolev spaces:

$$
\begin{cases}-\operatorname{div}\left(\phi_{1}(|\nabla u|) \nabla u\right)=\mathrm{F}_{\mathfrak{u}}(x, u, v) & \text { in } \Omega  \tag{1.1}\\ -\operatorname{div}\left(\phi_{2}(|\nabla v|) \nabla v\right)=\mathrm{F}_{v}(x, u, v) & \text { in } \Omega \\ u=v=0 & \text { on } \partial \Omega\end{cases}
$$

where $\Omega$ is a bounded domain in $\mathbb{R}^{N}(N \geqslant 2)$ with smooth boundary $\partial \Omega$, and $\phi_{i}(i=1,2):(0,+\infty) \rightarrow$ $(0,+\infty)$ are two functions which satisfy:
$\left(\phi_{1}\right) \phi_{i} \in C^{1}(0,+\infty), \mathrm{t} \phi_{\mathrm{i}}(\mathrm{t}) \rightarrow 0$ as $\mathrm{t} \rightarrow 0, \mathrm{t} \phi_{\mathrm{i}}(\mathrm{t}) \rightarrow+\infty$ as $\mathrm{t} \rightarrow+\infty ;$

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$\left(\phi_{2}\right) t \rightarrow t \phi_{i}(t)$ are strictly increasing;
$\left(\phi_{3}\right) 1<l_{i}:=\inf _{t>0} \frac{t^{2} \phi_{i}(t)}{\Phi_{i}(t)} \leqslant \sup _{t>0} \frac{t^{2} \phi_{i}(t)}{\Phi_{i}(t)}=: m_{i}<N$, where $\Phi_{i}(t):=\int_{0}^{|t|} s \phi_{i}(s) d s, t \in \mathbb{R}$, and $F$ satisfies
$\left(F_{0}\right) F: \Omega \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is a $C^{1}$ function such that $F(x, 0,0)=0, x \in \Omega$.
Set $\phi_{2}=\phi_{1}=: \phi, v=u$ and $F(x, u, v)=F(x, v, u)$. Then the system (1.1) reduces to the following quasilinear elliptic equation:
\[

$$
\begin{cases}-\operatorname{div}(\phi(|\nabla u|) \nabla u)=\mathrm{f}(\mathrm{x}, \mathrm{u}) & \text { in } \Omega  \tag{1.2}\\ \mathrm{u}=0 & \text { on } \partial \Omega\end{cases}
$$
\]

Under assumptions $\left(\phi_{1}\right)$ and $\left(\phi_{2}\right)$, equation (1.2) may be allowed to possess more complicated nonlinear or non-homogeneous term $\phi$, which can be used to model many phenomena (see [20]). When $\phi$ is not homogeneous, an Orlicz-Sobolev space setting may be applied for this type of equations (see Section 2). In recent years, equations like (1.2) have caused great interests among scholars. We refer readers to [4, 9, 11-15, 17-20, 24, 28, 33] and reference therein for more information. In those papers, the existence and multiplicity of solutions were obtained by various methods. Among them, variational methods have been used widely. In Clément et al. [14], the authors firstly obtained that (1.2) has a nontrivial solution by variational method when the nonlinear term $f$ satisfies Ambrosetti-Rabinowitz type growth and subcritical Orlicz-Sobolev growth conditions. Motivated by this paper, many scholars studied the existence and multiplicity of solutions when Ambrosetti-Rabinowitz type growth condition is replaced by other superlinear Orlicz-Sobolev growth conditions (see [12,13]). When nonlinear term f has a critical Orlicz-Sobolev growth, the existence of a nontrivial solution was proved in $[18,19]$ and some other results were obtained in [33]. In [28] and [17], the authors obtained that (1.2) has at least two nontrivial solutions and infinitely many solutions, respectively, when the nonlinear term $f$ has a sublinear Orlicz-Sobolev growth. In [11], by using the three critical points theorem due to Ricceri, the authors obtained that (1.2) has at least three solutions. Particularly, when $\phi(t)=|t|^{p-2}(p>1)$, equation (1.2) is the p-Laplacian equation which has been studied extensively.

Set $\phi_{1}(t)=|t|^{p-2}, \phi_{2}(t)=|t|^{q-2}(p, q>1)$. Then system (1.1) reduces to the following $(p, q)$-Laplacian system:

$$
\begin{cases}-\Delta_{\mathrm{p}} u=\mathrm{F}_{\mathrm{u}}(x, u, v) & \text { in } \Omega  \tag{1.3}\\ -\Delta_{\mathrm{q}} v=\mathrm{F}_{v}(x, u, v) & \text { in } \Omega \\ u=v=0 & \text { on } \partial \Omega\end{cases}
$$

The existence and multiplicity of solutions for systems like (1.3) have also received a wide range of interests. Some methods are important to investigate systems like (1.3), such as variational method (see $[7,8,16])$, Nehari manifold and fibering method (see [2, 10, 35]), three critical points theorem (see [3, 27]), etc.

To the best of our knowledge, there are few papers considering the existence and multiplicity of solutions for systems like (1.1) except for [23, 34, 36]. In [23], Huentutripay-Manásevich studied an eigenvalue problem to the following system:

$$
\begin{cases}-\operatorname{div}\left(\phi_{1}(|\nabla u|) \nabla u\right)=\lambda F_{u}(x, u, v) & \text { in } \Omega \\ -\operatorname{div}\left(\phi_{2}(|\nabla v|) \nabla v\right)=\lambda F_{v}(x, u, v) & \text { in } \Omega \\ u=v=0 & \text { on } \partial \Omega\end{cases}
$$

where the function $F$ has the form

$$
F(x, u, v)=A_{1}(x, u)+b(x) \Gamma_{1}(u) \Gamma_{2}(v)+A_{2}(x, v)
$$

For a certain $\lambda$, the authors translated the existence of solution into a suitable minimizing problem and proved the existence of solution under some reasonable restriction. In [23], the Orlicz-Sobolev spaces are not necessary to be reflexive.

In [36], Xia and Wang considered a class of quasilinear elliptic system like (1.1). When $\Phi_{i}$ are $p_{i}{ }^{-}$ uniformly convex and have a $q_{i}$-asymptotical growth at infinity, $i=1,2$, respectively (see (4) and (6) in [36]), and F satisfies the following Ambrosetti-Rabinowitz type condition (see (5) in [36]):

$$
0<\theta F(x, u, v) \leqslant u F_{u}(x, u, v)+v F_{v}(x, u, v), \quad \text { for all } x \in \bar{\Omega}, \quad|u|+|v|>T,
$$

where $\theta>\max \left\{q_{1}, q_{2}\right\}$ and $T>0$, by using the mountain pass theorem, Xia and Wang proved the system has a nontrivial solution.

In [34], we investigated the following system:

$$
\begin{cases}-\operatorname{div}\left(\phi_{1}(|\nabla \mathfrak{u}|) \nabla \mathfrak{u}\right)=\lambda_{1} F_{u}(x, u, v)-\lambda_{2} G_{u}(x, u, v)-\lambda_{3} H_{u}(x, u, v) & \text { in } \Omega, \\ -\operatorname{div}\left(\phi_{2}(|\nabla v|) \nabla v\right)=\lambda_{1} F_{v}(x, u, v)-\lambda_{2} G_{v}(x, u, v)-\lambda_{3} H_{v}(x, u, v) & \text { in } \Omega \\ \mathfrak{u}=v=0 & \text { on } \partial \Omega,\end{cases}
$$

where $\lambda_{1}, \lambda_{2}, \lambda_{3}$ are three parameters, functions $F, G, H$ are of class $C^{1}\left(\Omega \times \mathbb{R}^{2}, \mathbb{R}\right)$ and satisfy some reasonable growth conditions. By using a three critical points theorem due to B. Ricceri [32], we proved that system has at least three solutions. With some additional conditions, by using a four critical points theorem due to Anello [5], we proved that system has at least four solutions.

In Carvalho et al. [12], by using the mountain pass theorem, authors obtained that equation (1.2) has at least one or two nontrivial solutions. To be precise, they obtained the following result:

Theorem 1.1 ([12, Theorem 1.1]). Assume that $\phi$ and f satisfy
$\left(\phi_{1}\right)^{\prime} \phi \in \mathrm{C}^{1}(0,+\infty), \mathrm{t} \phi(\mathrm{t}) \rightarrow 0$ as $\mathrm{t} \rightarrow 0, \mathrm{t} \phi(\mathrm{t}) \rightarrow+\infty$ as $\mathrm{t} \rightarrow+\infty ;$
$\left(\phi_{2}\right)^{\prime} \mathrm{t} \rightarrow \mathrm{t} \phi(\mathrm{t})$ is strictly increasing;
$\left(\phi_{3}\right)^{\prime}$

$$
1<l:=\inf _{t>0} \frac{t^{2} \phi(t)}{\Phi(t)} \leqslant \sup _{t>0} \frac{t^{2} \phi(t)}{\Phi(t)}=: m<N,
$$

where

$$
\Phi(\mathrm{t}):=\int_{0}^{|\mathrm{t}|} s \phi(\mathrm{~s}) \mathrm{ds}, \quad \mathrm{t} \in \mathbb{R}
$$

$\left(f_{0}\right) f: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function such that $f(x, 0)=0, x \in \Omega$;
$\left(f_{1}\right)^{\prime}$ a constant $C>0$ and an $N$-function (see Section 2) exists

$$
\Psi(\mathrm{t}):=\int_{0}^{|\mathrm{t}|} \psi(\mathrm{s}) \mathrm{ds}, \quad \mathrm{t} \in \mathbb{R},
$$

where $\psi:[0,+\infty) \rightarrow \mathbb{R}$ is continuous and it satisfies

$$
1<l \leqslant m<l_{\Psi}:=\inf _{t>0} \frac{\mathrm{t} \psi(\mathrm{t})}{\Psi(\mathrm{t})} \leqslant \sup _{\mathrm{t}>0} \frac{\mathrm{t} \psi(\mathrm{t})}{\Psi(\mathrm{t})}=: \mathrm{m}_{\Psi}<\mathrm{l}^{*}:=\frac{\mathrm{lN}}{\mathrm{~N}-\mathrm{l}^{\prime}}
$$

such that

$$
|f(x, t)| \leqslant C(1+\psi(|t|)), \quad(x, t) \in \Omega \times \mathbb{R} ;
$$

$\left(f_{2}\right)^{\prime}$

$$
\limsup _{t \rightarrow 0} \frac{|f(x, t)|}{|t| \phi(t)}=\lambda<\lambda_{1}, \quad \text { uniformly in } x \in \Omega
$$

where $\lambda_{1}>0$ satisfies the Poincaré inequality in [1] given by

$$
\lambda_{1} \int_{\Omega} \Phi(\mathfrak{u}) \mathrm{d} x \leqslant \int_{\Omega} \Phi(|\nabla(\mathfrak{u})|) \mathrm{d} x, \quad \forall u \in \mathcal{W}_{0}^{1, \Phi}(\Omega) ;
$$

$\left(f_{3}\right)^{\prime}$

$$
\lim _{t \rightarrow \infty} \frac{f(x, t)}{|t|^{m-2} t}=+\infty, \quad \text { uniformly in } x \in \Omega
$$

$\left(\mathrm{f}_{4}\right)^{\prime}$ an $N$-function exists

$$
\Gamma(\mathrm{t}):=\int_{0}^{|\mathrm{t}|} \gamma(\mathrm{s}) \mathrm{ds}, \quad \mathrm{t} \in \mathbb{R}
$$

where $\gamma:[0,+\infty) \rightarrow \mathbb{R}$ is continuous and it satisfies

$$
\frac{N}{l}<l_{\Gamma}:=\inf _{t>0} \frac{t \gamma(t)}{\Gamma(t)} \leqslant \sup _{t>0} \frac{t \gamma(t)}{\Gamma(t)}=: m_{\Gamma}<\infty,
$$

such that

$$
\Gamma\left(\frac{F(x, t)}{|t|^{l}}\right) \leqslant C \bar{F}(x, t), \quad x \in \Omega,|t| \geqslant R
$$

where $\mathrm{C}, \mathrm{R}$ are positive constants and

$$
\overline{\mathrm{F}}(\mathrm{x}, \mathrm{t})=\mathrm{tf}(\mathrm{x}, \mathrm{t})-\mathrm{mF}(\mathrm{x}, \mathrm{t}), \quad(\mathrm{x}, \mathrm{t}) \in \Omega \times \mathbb{R} .
$$

Then (1.2) admits
(i) one nonzero solution;
(ii) two nonzero solutions, say $u, v \in C^{1, \alpha}(\bar{\Omega})$ with $0<\alpha<1$ such that

$$
u>0 \quad \text { and } \quad v<0 \quad \text { in } \Omega
$$

provided that $\left(\phi_{3}\right)^{\prime}$ is replaced by a stronger condition
$\left(\phi_{4}\right)^{\prime}$

$$
0<l-1:=\inf _{\mathrm{t}>0} \frac{(\phi(\mathrm{t}) \mathrm{t})^{\prime}}{\phi(\mathrm{t})} \leqslant \sup _{\mathrm{t}>0} \frac{(\phi(\mathrm{t}) \mathrm{t})^{\prime}}{\phi(\mathrm{t})}=: \mathrm{m}-1<\mathrm{N}-1
$$

Motivated by [12], in this paper, by using the mountain pass theorem, we obtain that system (1.1) has a nontrivial solution (see Theorem 3.1 in Section 3) and the result extends the result (i) of Theorem 1.1 to system case. It is remarkable that, when system (1.1) reduces to (1.2), our corresponding result still improves the result (i) of Theorem 1.1 and one can see the details in Section 5 where we also offer an example that satisfies our results but does not satisfy Theorem 1.1. Besides, by using the symmetric mountain pass theorem, we obtain that system solutions. Since the system case is different from the scalar case, we will come across some additional difficulties, for example, the direct sum decomposition of working space. Of course more computing skills are needed in the process of our proofs.

This paper is organized as follows. In Section 2, we recall some preliminary knowledge on Orlicz and Orlicz-Sobolev spaces. In Section 3, we present the existence result (Theorem 3.1 below) and complete the proofs by using mountain pass theorem. In Section 4, we present the multiplicity result (Theorem 4.1 below) and complete the proofs by using symmetric mountain pass theorem. In Section 5, we present the results for (1.2), which correspond to Theorem 3.1 and Theorem 4.1, and compare the results with Theorem 1.1. In Section 6, we present some examples to illustrate our Theorem 3.1 and Theorem 4.1.

## 2. Preliminaries

In this paper, we study system (1.1) where $\phi_{i}$ may be nonlinear and non-homogeneous. To deal with such problem, we need to introduce Orlicz and Orlicz-Sobolev spaces. In this section, we present some fundamental notions and important properties about Orlicz and Orlicz-Sobolev spaces. We refer readers for more details to the books $[1,31]$ and the references quoted in them.

Definition 2.1 (see [1]). Let $\phi:[0,+\infty) \rightarrow[0,+\infty)$ be a right continuous, monotone increasing function with
(1) $\phi(0)=0$;
(2) $\lim _{t \rightarrow+\infty} \phi(t)=+\infty$;
(3) $\phi(t)>0$ whenever $t>0$.

Then the function defined on $\mathbb{R}$ by $\Phi(t)=\int_{0}^{|t|} \phi(s) d s$ is called an $N$-function.
By the definition of $N$-function $\Phi$, it is obvious that $\Phi(0)=0$ and $\Phi$ is strictly convex. We recall that an $N$-function $\Phi$ satisfies a $\Delta_{2}$-condition globally (or near infinity) if

$$
\sup _{t>0} \frac{\Phi(2 t)}{\Phi(t)}<+\infty \quad\left(\text { or } \limsup _{t \rightarrow \infty} \frac{\Phi(2 t)}{\Phi(t)}<+\infty\right)
$$

which implies that there exists a constant $K>0$, such that $\Phi(2 t) \leqslant K \Phi(t)$ for all $t \geqslant 0$ (or $t \geqslant t_{0}>0$ ). We also state the equivalent form that $\Phi$ satisfies a $\Delta_{2}$-condition globally (or near infinity) if and only if for any $c \geqslant 1$, there exists a constant $K_{c}>0$ such that $\Phi(c t) \leqslant K_{c} \Phi(t)$ for all $t \geqslant 0\left(\right.$ or $\left.t \geqslant t_{0}>0\right)$.
Definition 2.2 (see [1]). For an $N$-function $\Phi$, we define

$$
\widetilde{\Phi}(\mathrm{t})=\int_{0}^{|\mathrm{t}|} \phi^{-1}(\mathrm{~s}) \mathrm{d} s, \quad \mathrm{t} \in \mathbb{R}
$$

where $\phi^{-1}$ is the right inverse of the right derivative $\phi$ of $\Phi$. Then $\widetilde{\Phi}$ is an $N$-function called the complement of $\Phi$.

It holds that Young's inequality (see $[1,31]$ )

$$
\begin{equation*}
s t \leqslant \Phi(s)+\widetilde{\Phi}(t) \quad s, t \geqslant 0 \tag{2.1}
\end{equation*}
$$

and inequality (see [18, Lemma A.2])

$$
\widetilde{\Phi}(\phi(t)) \leqslant \Phi(2 t), \quad t \geqslant 0
$$

Now, we recall the Orlicz space $L^{\Phi}(\Omega)$ associated with $\Phi$. When $\Phi$ satisfies $\Delta_{2}$-condition globally, the Orlicz space $L^{\Phi}(\Omega)$ is the vectorial space of the measurable functions $u: \Omega \rightarrow \mathbb{R}$ satisfying

$$
\int_{\Omega} \Phi(|u|) \mathrm{d} x<+\infty
$$

where $\Omega \subset \mathbb{R}^{N}$ is an open set. $L^{\Phi}(\Omega)$ is a Banach space endowed with Luxemburg norm

$$
\|u\|_{\Phi}:=\inf \left\{\lambda>0: \int_{\Omega} \Phi\left(\frac{u}{\lambda}\right) d x \leqslant 1\right\}, \quad \text { for } u \in L^{\Phi}(\Omega)
$$

Particularly, when $\Phi(t)=|t|^{p}(p>1)$, the corresponding Orlicz space $L^{\Phi}(\Omega)$ is the classical Lebesgue space $L^{p}(\Omega)$ and the corresponding Luxemburg norm $\|u\|_{\Phi}$ is equal to the classical $L^{p}(\Omega)$ norm, that is,

$$
\|u\|_{L^{p}(\Omega)}:=\left(\int_{\Omega}|u(x)|^{p} d x\right)^{\frac{1}{p}}, \quad \text { for } u \in L^{p}(\Omega)
$$

The fact that $\Phi$ satisfies $\Delta_{2}$-condition globally implies that

$$
\begin{equation*}
u_{n} \rightarrow u \text { in } L^{\Phi}(\Omega) \Longleftrightarrow \int_{\Omega} \Phi\left(u_{n}-u\right) d x \rightarrow 0 \tag{2.2}
\end{equation*}
$$

Moreover, a generalized type of Hölder's inequality (see [1, 31])

$$
\left|\int_{\Omega} u v \mathrm{~d} x\right| \leqslant 2\|u\|_{\Phi}\|v\|_{\widetilde{\Phi}^{\prime}} \quad \text { for all } u \in L^{\Phi}(\Omega), \quad v \in \mathrm{~L}^{\widetilde{\Phi}}(\Omega),
$$

can be gained by applying Young's inequality (2.1).
The corresponding Orlicz-Sobolev space (see $[1,31]$ ) is defined by

$$
W^{1, \Phi}(\Omega):=\left\{u \in L^{\Phi}(\Omega): \frac{\partial u}{\partial x_{i}} \in L^{\Phi}(\Omega), i=1, \cdots, N\right\},
$$

with the norm

$$
\|\mathfrak{u}\|_{1, \Phi}:=\|\mathfrak{u}\|_{\Phi}+\|\nabla \mathfrak{u}\|_{\Phi} .
$$

When $\Omega$ is bounded, $W_{0}^{1, \Phi}(\Omega)$ as the closure of $C_{0}^{\infty}(\Omega)$ in $W^{1, \Phi}(\Omega)$ has an equivalent norm

$$
\|\mathfrak{u}\|_{0, \Phi}:=\|\nabla \mathfrak{u}\|_{\Phi},
$$

which can be obtained by using the Poincaré inequality in [22] given as

$$
\int_{\Omega} \Phi(\mathfrak{u}) \mathrm{d} x \leqslant \int_{\Omega} \Phi(2 \mathrm{~d}|\nabla(\mathrm{u})|) \mathrm{d} x, \quad \forall u \in \mathcal{W}_{0}^{1, \Phi}(\Omega),
$$

where $\mathrm{d}=\operatorname{diam}(\Omega)$.
Next, we give some inequalities which will be used in our proofs. For more details, we refer the reader to the papers $[1,18]$.
Lemma 2.3 ( $[1,18]$ ). If $\Phi$ is an N -function, then the following conditions are equivalent:

$$
\begin{equation*}
1 \leqslant l=\inf _{t>0} \frac{t \phi(t)}{\Phi(t)} \leqslant \sup _{t>0} \frac{t \phi(t)}{\Phi(t)}=m<+\infty ; \tag{1}
\end{equation*}
$$

(2) let $\zeta_{0}(\mathrm{t})=\min \left\{\mathrm{t}^{\mathrm{l}}, \mathrm{t}^{\mathrm{m}}\right\}, \zeta_{1}(\mathrm{t})=\max \left\{\mathrm{t}^{\mathrm{l}}, \mathrm{t}^{\mathrm{m}}\right\}, \mathrm{t} \geqslant 0$. $\Phi$ satisfies

$$
\zeta_{0}(\mathrm{t}) \Phi(\rho) \leqslant \Phi(\rho \mathrm{t}) \leqslant \zeta_{1}(\mathrm{t}) \Phi(\rho), \quad \forall \rho, \mathrm{t} \geqslant 0 ;
$$

(3) $\Phi$ satisfies a $\Delta_{2}$-condition globally.

Lemma 2.4. If $\Phi$ is an N -function and (2.3) holds, then $\Phi$ satisfies

$$
\zeta_{0}\left(\|\mathfrak{u}\|_{\Phi}\right) \leqslant \int_{\Omega} \Phi(\mathfrak{u}) \mathrm{d} x \leqslant \zeta_{1}\left(\|\mathfrak{u}\|_{\Phi}\right), \quad \forall \mathfrak{u} \in \mathrm{L}^{\Phi}(\Omega)
$$

Lemma 2.5. If $\Phi$ is an $N$-function and (2.3) holds with $l>1$. Let $\widetilde{\Phi}$ be the complement of $\Phi$ and $\zeta_{2}(t)=$ $\min \left\{\mathrm{t}_{\mathrm{t}}, \mathrm{t}^{\widetilde{m}}\right\}, \zeta_{3}(\mathrm{t})=\max \left\{\mathrm{t}^{\widetilde{\imath}}, \mathrm{t}^{\widetilde{m}}\right\}$, for $\mathrm{t} \geqslant 0$, where $\widetilde{\mathrm{l}}:=\frac{l}{l-1}$ and $\widetilde{\mathfrak{m}}:=\frac{\mathrm{m}}{m-1}$. Then $\widetilde{\Phi}$ satisfies

$$
\begin{equation*}
\widetilde{\mathfrak{m}}=\inf _{t>0} \frac{t \widetilde{\Phi}^{\prime}(\mathrm{t})}{\widetilde{\Phi}(\mathrm{t})} \leqslant \sup _{\mathrm{t}>0} \frac{\mathrm{t} \widetilde{\Phi}^{\prime}(\mathrm{t})}{\widetilde{\Phi}(\mathrm{t})}=\widetilde{\mathrm{l}} ; \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\zeta_{2}(t) \widetilde{\Phi}(\rho) \leqslant \widetilde{\Phi}(\rho t) \leqslant \zeta_{3}(t) \widetilde{\Phi}(\rho), \quad \forall \rho, t \geqslant 0 ; \tag{2}
\end{equation*}
$$

$$
\begin{equation*}
\zeta_{2}\left(\|\mathfrak{u}\|_{\widetilde{\Phi}}\right) \leqslant \int_{\Omega} \widetilde{\Phi}(\mathfrak{u}) \mathrm{d} x \leqslant \zeta_{3}\left(\|\mathfrak{u}\|_{\widetilde{\Phi}}\right), \quad \forall \mathfrak{u} \in \mathrm{L}^{\widetilde{\Phi}}(\Omega) . \tag{3}
\end{equation*}
$$

Lemma 2.6. If $\Phi$ is an $N$-function and (2.3) holds with $\mathrm{l}, \mathrm{m} \in(1, \mathrm{~N})$. Let $\zeta_{4}(\mathrm{t})=\min \left\{\mathrm{t}^{*}, \mathrm{t}^{\mathrm{m}^{*}}\right\}$, $\zeta_{5}(\mathrm{t})=\max \left\{\mathrm{t}^{\mathrm{t}^{*}}, \mathrm{t}^{\mathrm{m}^{*}}\right\}$, for $\mathrm{t} \geqslant 0$, where $\mathrm{l}^{*}:=\frac{\mathrm{lN}}{\mathrm{N}-\mathrm{l}}, \mathrm{m}^{*}:=\frac{\mathrm{mN}}{\mathrm{N}-\mathrm{m}}$. Then $\Phi_{*}$ satisfies

$$
\begin{equation*}
l^{*}=\inf _{\mathrm{t}>0} \frac{\mathrm{t} \Phi_{*}^{\prime}(\mathrm{t})}{\Phi_{*}(\mathrm{t})} \leqslant \sup _{\mathrm{t}>0} \frac{\mathrm{t} \Phi_{*}^{\prime}(\mathrm{t})}{\Phi_{*}(\mathrm{t})}=\mathrm{m}^{*} \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\zeta_{4}(\mathrm{t}) \Phi_{*}(\rho) \leqslant \Phi_{*}(\rho \mathrm{t}) \leqslant \zeta_{5}(\mathrm{t}) \Phi_{*}(\rho), \quad \forall \rho, \mathrm{t} \geqslant 0 ; \tag{2}
\end{equation*}
$$

(3)

$$
\zeta_{4}\left(\|u\|_{\Phi_{*}}\right) \leqslant \int_{\Omega} \Phi_{*}(\mathfrak{u}) \mathrm{d} x \leqslant \zeta_{5}\left(\|u\|_{\Phi_{*}}\right), \quad \forall u \in \mathrm{~L}^{\Phi_{*}}(\Omega)
$$

where $\Phi_{*}$ is the Sobolev conjugate function of $\Phi$, which is defined by

Lemma 2.7. Under the assumptions of Lemma 2.6, the embedding from $W_{0}^{1, \Phi}(\Omega)$ into $L^{\Phi_{*}}(\Omega)$ is continuous and into $L^{\curlyvee}(\Omega)$ is compact for any $N$-function $\curlyvee$ increasing essentially more slowly than $\Phi_{*}$ near infinity, that is,

$$
\lim _{t \rightarrow+\infty} \frac{\Upsilon(c t)}{\Phi_{*}(t)}=0
$$

for any constant $\mathrm{c}>0$. Therefore, there exists $\mathrm{C}_{\Gamma}>0$ such that

$$
\begin{equation*}
\|\mathfrak{u}\|_{\Gamma} \leqslant \mathrm{C}_{\Gamma}\|\nabla \mathfrak{u}\|_{\Phi}, \quad \forall \mathfrak{u} \in \mathrm{W}_{0}^{1, \Phi}(\Omega) . \tag{2.4}
\end{equation*}
$$

Remark 2.8. By Lemma 2.3 and Lemma 2.5, assumptions $\left(\phi_{1}\right)-\left(\phi_{3}\right)$ show that $\Phi_{i}(i=1,2)$ and $\widetilde{\Phi}_{i}(i=$ $1,2)$ are $N$-functions satisfying $\Delta_{2}$-condition globally. Thus $L^{\Phi_{i}}(\Omega)(i=1,2)$ and $W_{0}^{1, \Phi_{i}}(\Omega)(i=1,2)$ are separable and reflexive Banach spaces (see [1, 31]).
Notation. Throughout this paper, C is used to denote a positive constant which may be different in various places.

## 3. Existence

In this section, we present the following existence result by using mountain pass theorem.
Theorem 3.1. Assume that $\left(\phi_{1}\right)-\left(\phi_{3}\right),\left(\mathrm{F}_{0}\right)$ and the following conditions hold:
$\left(F_{1}\right)$ there exist two continuous functions $\psi_{i}(i=1,2):[0,+\infty) \rightarrow \mathbb{R}$, which satisfy that $\Psi_{i}(\mathrm{t}):=\int_{0}^{|\mathrm{t}|} \psi_{i}(\mathrm{~s}) \mathrm{d}$, $t \in \mathbb{R}(i=1,2)$ are two $N$-functions increasing essentially more slowly than $\Phi_{i *}(i=1,2)$ near infinity, respectively, moreover,

$$
\begin{equation*}
m_{i}<l_{\Psi_{i}}:=\inf _{t>0} \frac{t \psi_{i}(t)}{\Psi_{i}(t)} \leqslant \sup _{t>0} \frac{t \psi_{i}(t)}{\Psi_{i}(t)}=: m_{\Psi_{i}}<+\infty, \tag{3.1}
\end{equation*}
$$

such that

$$
\left\{\begin{array}{l}
\left|\mathrm{F}_{\mathfrak{u}}(\mathrm{x}, \mathrm{u}, v)\right| \leqslant \mathrm{c}_{1}\left(1+\Psi_{1}(|\mathfrak{u}|)+\widetilde{\Psi}_{1}^{-1}\left(\Psi_{2}(v)\right)\right),  \tag{3.2}\\
\left|\mathrm{F}_{v}(\mathrm{x}, \mathrm{u}, v)\right| \leqslant \mathrm{c}_{1}\left(1+\widetilde{\Psi}_{2}^{-1}\left(\Psi_{1}(u)\right)+\psi_{2}(|v|)\right)
\end{array}\right.
$$

for all $(x, u, v) \in \Omega \times \mathbb{R} \times \mathbb{R}$, where constant $c_{1}>0, \widetilde{\Psi}_{i}$ denote the complements of $\Psi_{i}(i=1,2)$, respectively;
$\left(F_{2}\right)$

$$
\limsup _{|(u, v)| \rightarrow 0} \frac{|F(x, u, v)|}{\lambda_{1} \Phi_{1}(u)+\lambda_{2} \Phi_{2}(v)}=c_{2} \text { uniformly in } x \in \Omega,
$$

where constants $\mathrm{c}_{2} \in[0,1)$ and $\lambda_{i}(i=1,2)>0$ satisfy the Poincaré inequalities in [1] supplied by

$$
\lambda_{1} \int_{\Omega} \Phi_{1}(u) \mathrm{d} x \leqslant \int_{\Omega} \Phi_{1}(|\nabla u|) \mathrm{d} x, \quad \forall u \in W_{0}^{1, \Phi_{1}}(\Omega)
$$

and

$$
\lambda_{2} \int_{\Omega} \Phi_{2}(v) \mathrm{d} x \leqslant \int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{d} x, \quad \forall v \in \mathrm{~W}_{0}^{1, \Phi_{2}}(\Omega) ;
$$

( $F_{3}$ )

$$
\lim _{|(u, v)| \rightarrow+\infty} \frac{F(x, u, v)}{\Phi_{1}(u)+\Phi_{2}(v)}=+\infty \text { uniformly in } x \in \Omega ;
$$

$\left(\mathrm{F}_{4}\right)$ there exists a continuous function $\gamma:[0, \infty) \rightarrow \mathbb{R}$ and it satisfies that $\Gamma(\mathrm{t}):=\int_{0}^{|\mathrm{t}|} \gamma(\mathrm{s}) \mathrm{ds}, \mathrm{t} \in \mathbb{R}$ is an N -function with

$$
1<l_{\Gamma}:=\inf _{t>0} \frac{t \gamma(\mathrm{t})}{\Gamma(\mathrm{t})} \leqslant \sup _{\mathrm{t}>0} \frac{\mathrm{t} \gamma(\mathrm{t})}{\Gamma(\mathrm{t})}=: \mathfrak{m}_{\Gamma}<+\infty,
$$

and functions $H_{i}(\mathrm{t}):=|\mathrm{t}|^{\frac{\mathfrak{l}_{i} \mathrm{l}_{r}-1}{\Gamma}}, \mathrm{t} \in \mathbb{R}(\mathfrak{i}=1,2)$ increase essentially more slowly than $\Phi_{i *}(\mathfrak{i}=1,2)$ near infinity, respectively, such that

$$
\begin{equation*}
\Gamma\left(\frac{F(x, u, v)}{|u|^{l_{1}}+|v|^{l_{2}}}\right) \leqslant c_{3} \bar{F}(x, u, v), \quad x \in \Omega, \quad|(u, v)| \geqslant r, \tag{3.3}
\end{equation*}
$$

where constants $\mathrm{c}_{3}, \mathrm{r}>0$ and

$$
\overline{\mathrm{F}}(x, u, v):=\frac{1}{m_{1}} \mathrm{~F}_{\mathfrak{u}}(x, u, v) u+\frac{1}{m_{2}} F_{v}(x, u, v) v-F(x, u, v), \quad \forall(x, u, v) \in \Omega \times \mathbb{R} \times \mathbb{R} .
$$

Then system (1.1) possesses a nontrivial weak solution.
Remark 3.2. Under assumptions $\left(\phi_{1}\right)-\left(\phi_{3}\right),\left(F_{1}\right)$ and $\left(F_{4}\right)$, by Lemma 2.7, the following embeddings are compact:

$$
W_{0}^{1, \Phi_{i}}(\Omega) \hookrightarrow \mathrm{L}^{\Psi_{i}}(\Omega), W_{0}^{1, \Phi_{i}}(\Omega) \hookrightarrow \mathrm{L}^{\mathfrak{l}_{i} \widetilde{\mathfrak{l}_{\Gamma}}}(\Omega) \quad \text { and } \quad W_{0}^{1, \Phi_{i}}(\Omega) \hookrightarrow \mathrm{L}^{\mathfrak{l}_{\mathfrak{i}} \widetilde{m_{\Gamma}}}(\Omega), \quad i=1,2
$$

where $\tilde{l_{\Gamma}}=\frac{l_{\Gamma}}{l_{\Gamma}-1}$ and $\widetilde{m_{\Gamma}}=\frac{m_{\Gamma}}{m_{\Gamma}-1}$.
Remark 3.3. By (2) in Lemma 2.3, assumptions ( $\mathrm{F}_{3}$ ) and ( $\mathrm{F}_{4}$ ) show

$$
\lim _{|(u, v)| \rightarrow+\infty} \bar{F}(x, u, v) \rightarrow+\infty, \quad \text { uniformly in } x \in \Omega .
$$

Remark 3.4. Based on the Young's inequality (2.1), $\mathrm{F}(\mathrm{x}, 0,0)=0$ and the fact

$$
F(x, u, v)=\int_{0}^{u} F_{s}(x, s, v) d s+\int_{0}^{v} F_{t}(x, 0, t) d t+F(x, 0,0), \quad \forall(x, u, v) \in \Omega \times \mathbb{R} \times \mathbb{R},
$$

equation (3.2) shows that there exists a constant $\mathrm{c}_{4}>0$ such that

$$
|F(x, u, v)| \leqslant c_{4}\left(|u|+|v|+\Psi_{1}(u)+\Psi_{2}(v)\right), \quad \forall(x, u, v) \in \Omega \times \mathbb{R} \times \mathbb{R},
$$

which, together with (3.1) and (2) in Lemma 2.3, shows that there exists a constant $\mathrm{c}_{5}>0$ such that

$$
\begin{equation*}
|F(x, u, v)| \leqslant c_{5}\left(1+\Psi_{1}(u)+\Psi_{2}(v)\right), \quad \forall(x, u, v) \in \Omega \times \mathbb{R} \times \mathbb{R} \tag{3.4}
\end{equation*}
$$

Define $W:=W_{0}^{1, \Phi_{1}}(\Omega) \times W_{0}^{1, \Phi_{2}}(\Omega)$ with the norm

$$
\|(u, v)\|:=\|u\|_{0, \Phi_{1}}+\|v\|_{0, \Phi_{2}}=\|\nabla u\|_{\Phi_{1}}+\|\nabla v\|_{\Phi_{2}}
$$

Remark 2.8 shows $W$ is a separable and reflexive Banach space. We observe that the energy functional I on $W$ corresponding to system (1.1) is

$$
\mathrm{I}(u, v):=\int_{\Omega} \Phi_{1}(|\nabla u|) \mathrm{d} x+\int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{d} x-\int_{\Omega} F(x, u, v) \mathrm{d} x, \quad(u, v) \in W
$$

Denote by $\mathrm{I}_{\mathrm{i}}(\mathrm{i}=1,2): \mathrm{W} \rightarrow \mathbb{R}$ the functionals

$$
\mathrm{I}_{1}(\mathrm{u}, v)=\int_{\Omega} \Phi_{1}(|\nabla u|) \mathrm{d} x+\int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{dx}, \quad \text { and } \quad \mathrm{I}_{2}(u, v)=\int_{\Omega} \mathrm{F}(x, u, v) \mathrm{d} x
$$

Then

$$
\mathrm{I}(u, v)=\mathrm{I}_{1}(u, v)-\mathrm{I}_{2}(u, v)
$$

Under the assumptions $\left(\phi_{1}\right)-\left(\phi_{3}\right)$, by similar arguments as [21], we can prove that $I_{1}$ is well-defined and of class $C^{1}(W, \mathbb{R})$ and

$$
\left\langle\mathrm{I}_{1}^{\prime}(u, v),(\tilde{\mathrm{u}}, \tilde{v})\right\rangle=\int_{\Omega} \phi_{1}(|\nabla u|) \nabla u \nabla \tilde{u} \mathrm{~d} x+\int_{\Omega} \phi_{2}(|\nabla v|) \nabla v \nabla \tilde{v} \mathrm{~d} x
$$

for all $(\tilde{u}, \tilde{v}) \in W$. Furthermore, under the assumption $\left(F_{1}\right)$, standard arguments show that $I_{2}$ is also well-defined and of class $C^{1}(W, \mathbb{R})$ and

$$
\left\langle I_{2}^{\prime}(u, v),(\tilde{u}, \tilde{v})\right\rangle=\int_{\Omega} F_{u}(x, u, v) \tilde{u} d x+\int_{\Omega} F_{v}(x, u, v) \tilde{v} d x
$$

for all $(\tilde{u}, \tilde{v}) \in W$. Therefore, I is well-defined and of class $C^{1}(W, \mathbb{R})$ and

$$
\begin{aligned}
\left\langle\mathrm{I}^{\prime}(\mathrm{u}, v),(\tilde{u}, \tilde{v})\right\rangle= & \int_{\Omega} \phi_{1}(|\nabla \mathrm{u}|) \nabla \mathfrak{u} \nabla \tilde{u} d x+\int_{\Omega} \phi_{2}(|\nabla v|) \nabla v \nabla \tilde{v} \mathrm{~d} x \\
& -\int_{\Omega} \mathrm{F}_{\mathfrak{u}}(x, \mathfrak{u}, v) \tilde{u} d x-\int_{\Omega} \mathrm{F}_{v}(x, u, v) \tilde{v} \mathrm{~d} x
\end{aligned}
$$

for all $(\tilde{u}, \tilde{v}) \in W$. Then, the critical points of I on $W$ are weak solutions of system (1.1).
We will use the mountain pass theorem (see [30, Theorem 2.2]) to prove Theorem 3.1, and use the symmetric mountain pass theorem (see [30, Theorem 9.12]) to prove Theorem 4.1 in Section 4 . By arguments in [6], it turns out that the (PS)-condition due to Palais-Smale can be replaced by $(\mathrm{C})_{c}$-condition due to Cerami in the mountain pass theorem and in the symmetric mountain pass theorem.

We recall that $I \in C^{1}(E, \mathbb{R})$ satisfies $(C)_{c}$-condition if any $(C)_{c}$-sequence $\left\{u_{n}\right\} \subset E$ has a convergent subsequence, where $(C)_{c}$-sequence $\left\{u_{n}\right\}$ means that

$$
\begin{equation*}
\mathrm{I}\left(\mathrm{u}_{\mathrm{n}}\right) \rightarrow \mathrm{c}, \quad\left(1+\left\|\mathrm{u}_{n}\right\|\right)\left\|\mathrm{I}^{\prime}\left(\mathrm{u}_{n}\right)\right\| \rightarrow 0, \text { as } n \rightarrow \infty \tag{3.5}
\end{equation*}
$$

Lemma 3.5 ([30, Theorem 2.2]). Let E be a real Banach space and $I \in C^{1}(E, \mathbb{R})$ satisfying (PS)-condition. Suppose $\mathrm{I}(0)=0$ and
( $\mathrm{I}_{1}$ ) there are constants $\rho, \alpha>0$ such that $\left.\mathrm{I}\right|_{\partial \mathrm{B}_{\rho}} \geqslant \alpha$, and
$\left(\mathrm{I}_{2}\right)$ there is an $\mathrm{e} \in \mathrm{E} \backslash \mathrm{B}_{\rho}$ such that $\mathrm{I}(\mathrm{e}) \leqslant 0$.
Then I possesses a critical value $c \geqslant \alpha$.
Lemma 3.6. Suppose that $\left(\phi_{1}\right)-\left(\phi_{3}\right),\left(F_{1}\right)$ and $\left(F_{2}\right)$ hold. Then there are constants $\rho, \alpha>0$ such that $\left.\mathrm{I}\right|_{\partial \mathrm{B}_{\rho}} \geqslant \alpha$.

Proof. By $\left(\mathrm{F}_{2}\right)$, (3.4) and the fact that F is continuous, we obtain that there exist constants $\varepsilon>0$ and $\mathrm{C}>0$ such that

$$
\begin{equation*}
|F(x, u, v)| \leqslant(1-\varepsilon)\left(\lambda_{1} \Phi_{1}(u)+\lambda_{2} \Phi_{2}(v)\right)+C\left(\Psi_{1}(u)+\Psi_{2}(v)\right), \quad \forall(x, u, v) \in \Omega \times \mathbb{R} \times \mathbb{R} . \tag{3.6}
\end{equation*}
$$

When $\|(u, v)\| \leqslant 1$, by (3.6), Poincaré inequality in $\left(F_{2}\right)$, Lemma 2.4, Remark 3.2 and (2.4), we obtain

$$
\begin{aligned}
& \mathrm{I}(\mathbf{u}, v)=\int_{\Omega} \Phi_{1}(|\nabla \boldsymbol{u}|) \mathrm{d} x+\int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{d} x-\int_{\Omega} \mathrm{F}(\mathrm{x}, \mathbf{u}, v) \mathrm{d} x \\
& \geqslant \int_{\Omega} \Phi_{1}(|\nabla u|) \mathrm{d} x+\int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{d} x-\int_{\Omega}|F(x, u, v)| \mathrm{d} x \\
& \geqslant \varepsilon \int_{\Omega} \Phi_{1}(|\nabla u|) \mathrm{d} x+\varepsilon \int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{d} x-\mathrm{C} \int_{\Omega} \Psi_{1}(\mathfrak{u}) \mathrm{d} x-\mathrm{C} \int_{\Omega} \Psi_{2}(v) \mathrm{d} x \\
& \geqslant \varepsilon \min \left\{\|\nabla \mathfrak{u}\|_{\Phi_{1}}^{\boldsymbol{l}_{1}},\|\nabla \mathfrak{u}\|_{\Phi_{1}}^{\mathfrak{m}_{1}}\right\}+\varepsilon \min \left\{\|\nabla v\|_{\Phi_{2_{2}}}^{\mathrm{l}_{2}}\|\nabla v\|_{\Phi_{2}}^{m_{2}}\right\} \\
& -\mathrm{C} \max \left\{\|u\|_{\Psi_{1}}^{\boldsymbol{l}_{1}},\|u\|_{\Psi_{1}}^{\mathfrak{m} \Psi_{1}}\right\}-\mathrm{C} \max \left\{\|v\|_{\Psi_{2}}^{{ }_{\Psi_{2}}},\|v\|_{\Psi_{2}}^{\mathfrak{m}_{2} \Psi_{2}}\right\} \\
& \geqslant \varepsilon \min \left\{\|\nabla u\|_{\Phi_{1}}^{l_{1}},\|\nabla u\|_{\Phi_{1}}^{\boldsymbol{m}_{1}}\right\}+\varepsilon \min \left\{\|\nabla v\|_{\Phi_{2^{\prime}}}^{\mathrm{l}_{2}}\|\nabla v\|_{\Phi_{2}}^{\mathrm{m}_{2}}\right\}
\end{aligned}
$$

$$
\begin{aligned}
& =\varepsilon\|\nabla u\|_{\Phi_{1}}^{m_{1}}+\varepsilon\|\nabla v\|_{\Phi_{2}}^{m_{2}}-\mathrm{C}\|\nabla u\|_{\Phi_{1}}^{\boldsymbol{m}_{1}}-\mathrm{C}\|\nabla v\|_{\Phi_{2}}^{\boldsymbol{q}_{\Psi_{2}}} \\
& =\|\nabla u\|_{\Phi_{1}}^{m_{1}}\left(\varepsilon-\mathrm{C}\|\nabla u\|_{\Phi_{1}}^{\boldsymbol{q}_{1}-\mathfrak{m}_{1}}\right)+\|\nabla v\|_{\Phi_{2}}^{m_{2}}\left(\varepsilon-\mathrm{C}\|\nabla v\|_{\Phi_{2}}^{\mathfrak{m}_{2}-\mathfrak{m}_{2}}\right) .
\end{aligned}
$$

Since $1<m_{i}<l_{\Psi_{i}}$, we can choose positive constants $\rho$ and $\alpha$ small enough such that $\mathrm{I}(u, v) \geqslant \alpha$ for all $(u, v) \in W$ with $\|(u, v)\|=\rho$.

Lemma 3.7. Suppose that $\left(\phi_{1}\right)-\left(\phi_{3}\right)$ and $\left(F_{3}\right)$ hold. Then there is a point $(u, v) \in W \backslash B_{\rho}$ such that $\mathrm{I}(u, v) \leqslant 0$.
Proof. By $\left(F_{3}\right)$ and the fact that $F$ is continuous, then for any given constant $M>0$, there exists a constant $\mathrm{C}_{\mathrm{M}}>0$ such that

$$
\begin{equation*}
F(x, u, v) \geqslant M(\Phi(u)+\Phi(v))-C_{M}, \quad \forall(x, u, v) \in \Omega \times \mathbb{R} \times \mathbb{R} \tag{3.7}
\end{equation*}
$$

Now, choose $u_{0} \in C_{0}^{\infty}(\Omega) \backslash\{0\}$ with $0 \leqslant u_{0}(x) \leqslant 1$. Then $\left(u_{0}, 0\right) \in W$, and by (3.7) and (2) in Lemma 2.3, when $t>0$ we have

$$
\begin{aligned}
\mathrm{I}\left(\mathrm{tu} u_{0}, 0\right) & =\int_{\Omega} \Phi_{1}\left(\mathrm{t}\left|\nabla \mathrm{u}_{0}\right|\right) \mathrm{d} x-\int_{\Omega} \mathrm{F}\left(x, \mathrm{tu} u_{0}, 0\right) \mathrm{d} x \\
& \leqslant \int_{\Omega} \Phi_{1}\left(\mathrm{t}\left|\nabla u_{0}\right|\right) \mathrm{d} x-M \int_{\Omega} \Phi_{1}\left(\mathrm{tu}_{0}\right) \mathrm{d} x+\mathrm{C}_{M}|\Omega| \\
& \leqslant \Phi_{1}(\mathrm{t}) \int_{\Omega} \max \left\{\left|\nabla u_{0}\right|^{l_{1}},\left|\nabla u_{0}\right|^{m_{1}}\right\} \mathrm{d} x-M \Phi_{1}(\mathrm{t}) \int_{\Omega} \min \left\{\left|u_{0}\right|^{l_{1}},\left|u_{0}\right|^{m_{1}}\right\} \mathrm{d} x+\mathrm{C}_{M}|\Omega| \\
& \leqslant \Phi_{1}(\mathrm{t})\left(\left\|\left|\nabla u_{0}\right|\right\|\left\|_{L_{1}(\Omega)}^{\mathrm{l}_{1}}+\right\|| | \nabla u_{0} \mid\left\|_{\mathrm{L}^{m_{1}}(\Omega)}^{m_{1}}-M\right\| u_{0} \|_{m_{1}}^{m_{1}}\right)+C_{M}|\Omega| .
\end{aligned}
$$

Since $M>0$ is arbitrary and $\lim _{t \rightarrow+\infty} \Phi_{1}(t)=+\infty$, we can choose $M>\frac{\left\|\nabla u_{0}\right\|\left\|_{L^{1} 1_{1(\Omega)}}^{l_{1}}+\right\|\left\|u_{0}\right\| \|_{L^{m_{1}}}^{m_{1}}}{\left\|u_{0}\right\|_{m_{1}}^{m_{1}}}$ and large t such that $\mathrm{I}\left(\mathrm{tu} \mathrm{u}_{0}, 0\right) \leqslant 0$ and $\left\|\left(\mathrm{tu}_{0}, 0\right)\right\|>\rho$.

Lemma 3.8. Suppose that $\left(\phi_{1}\right)-\left(\phi_{3}\right),\left(F_{1}\right),\left(F_{3}\right)$ and $\left(F_{4}\right)$ hold. Then $(\mathrm{C})_{c}$-sequence in W is bounded.
Proof. This proof is partially motivated by [12, Lemma 4.1]. Let $\left\{\left(u_{n}, v_{n}\right)\right\}$ be a $(C)_{c}$-sequence of I in $W$. Then, for $n$ large enough, by (3.5) and ( $\phi_{3}$ ), we obtain

$$
c+1 \geqslant I\left(u_{n}, v_{n}\right)-\left\langle I^{\prime}\left(u_{n}, v_{n}\right),\left(\frac{1}{m_{1}} u_{n}, \frac{1}{m_{2}} v_{n}\right)\right\rangle
$$

$$
\begin{align*}
= & \int_{\Omega} \Phi_{1}\left(\left|\nabla u_{n}\right|\right) d x+\int_{\Omega} \Phi_{2}\left(\left|\nabla v_{n}\right|\right) d x-\int_{\Omega} F\left(x, u_{n}, v_{n}\right) d x \\
& -\frac{1}{m_{1}} \int_{\Omega} \phi_{1}\left(\left|\nabla u_{n}\right|\right)\left|\nabla u_{n}\right|^{2} d x-\frac{1}{m_{2}} \int_{\Omega} \Phi_{2}\left(\left|\nabla v_{n}\right|\right)\left|\nabla v_{n}\right|^{2} d x \\
& +\frac{1}{m_{1}} \int_{\Omega} F_{u}\left(x, u_{n}, v_{n}\right) u_{n} d x+\frac{1}{m_{2}} \int_{\Omega} F_{v}\left(x, u_{n}, v_{n}\right) v_{n} d x  \tag{3.8}\\
= & \int_{\Omega}\left(\Phi_{1}\left(\left|\nabla u_{n}\right|\right)-\frac{1}{m_{1}} \phi_{1}\left(\left|\nabla u_{n}\right|\right)\left|\nabla u_{n}\right|^{2}\right) d x+\int_{\Omega}\left(\Phi_{2}\left(\left|\nabla u_{n}\right|\right)-\frac{1}{m_{2}} \phi_{2}\left(\left|\nabla v_{n}\right|\right)\left|\nabla v_{n}\right|^{2}\right) d x \\
& +\int_{\Omega}\left(\frac{1}{m_{1}} F_{u}\left(x, u_{n}, v_{n}\right) u_{n}+\frac{1}{m_{2}} F_{v}\left(x, u_{n}, v_{n}\right) v_{n}-F\left(x, u_{n}, v_{n}\right)\right) d x \\
\geqslant & \int_{\Omega} \bar{F}\left(x, u_{n}, v_{n}\right) d x .
\end{align*}
$$

To prove the boundedness of $\left\{\left(u_{n}, v_{n}\right)\right\}$, arguing by contradiction, suppose that there exists a subsequence of $\left\{\left(u_{n}, v_{n}\right)\right\}$, still denoted by $\left\{\left(u_{n}, v_{n}\right)\right\}$, such that $\left\|\left(u_{n}, v_{n}\right)\right\|=\left\|\nabla u_{n}\right\|_{\Phi_{1}}+\left\|\nabla v_{n}\right\|_{\Phi_{2}} \rightarrow+\infty$. Next, we discuss the problem in two cases.
Case 1. Suppose that $\left\|\nabla \mathfrak{u}_{n}\right\|_{\Phi_{1}} \rightarrow+\infty$ and also $\left\|\nabla v_{n}\right\|_{\Phi_{2}} \rightarrow+\infty$. Let $\bar{u}_{n}=\frac{u_{n}}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}}$ and $\bar{v}_{n}=\frac{v_{n}}{\left\|\nabla v_{n}\right\|_{\Phi_{2}}}$. Then $\left\{\left(\bar{u}_{n}, \bar{v}_{n}\right)\right\}$ is bounded in separable, reflexive Banach space $W$. Passing to a subsequence $\left\{\left(\bar{u}_{n}, \bar{v}_{n}\right)\right\}$, by Remark 3.2, there exists a point $(\bar{u}, \bar{v}) \in W$ such that
$\star \quad \bar{u}_{n} \rightharpoonup \bar{u}$ in $W_{0}^{1, \Phi_{1}}(\Omega), \quad \bar{u}_{n} \rightarrow \bar{u}$ in $L^{l_{1} \widetilde{\Gamma_{\Gamma}}}(\Omega)$ and in $L^{l_{1} \widetilde{m_{\Gamma}}}(\Omega), \quad \bar{u}_{n}(x) \rightarrow \bar{u}(x)$ a.e. in $\Omega$;
$\star \quad \bar{v}_{n} \rightharpoonup \bar{v}$ in $W_{0}^{1, \Phi_{2}}(\Omega), \quad \bar{v}_{n} \rightarrow \bar{v}$ in $L^{l_{2} \widetilde{l_{\Gamma}}}(\Omega)$ and in $L^{l_{2} \widetilde{m_{\Gamma}}}(\Omega), \quad \bar{v}_{n}(x) \rightarrow \bar{v}(x)$ a.e. in $\Omega$.
Firstly, we assume that $[\bar{u} \neq 0]:=\{x \in \Omega: \bar{u}(x) \neq 0\}$ or $[\bar{v} \neq 0]:=\{x \in \Omega: \bar{v}(x) \neq 0\}$ has nonzero Lebesgue measure. It is clear that

$$
\left|\mathfrak{u}_{n}\right|=\left|\bar{u}_{n}\right|\left\|\nabla \mathfrak{u}_{n}\right\|_{\Phi_{1}} \rightarrow+\infty \quad \text { in }[\bar{u} \neq 0]
$$

and

$$
\left|v_{\mathfrak{n}}\right|=\left|\bar{v}_{\mathfrak{n}}\right|\left\|\nabla v_{\mathfrak{n}}\right\|_{\Phi_{2}} \rightarrow+\infty \quad \text { in }[\bar{v} \neq 0] .
$$

Then, by (3.8), Remark 3.3 and Fatou's Lemma, we have

$$
c+1 \geqslant \int_{\Omega} \bar{F}\left(x, u_{n}, v_{n}\right) d x \rightarrow+\infty,
$$

which is a contradiction. Next, we assume that both $[\bar{u} \neq 0]$ and $[\bar{v} \neq 0]$ have zero Lebesgue measure, that is, $\bar{u}=0$ in $W_{0}^{1, \Phi_{1}}(\Omega)$ and $\bar{v}=0$ in $W_{0}^{1, \Phi_{2}}(\Omega)$. By Lemma 2.4, we have

$$
\begin{align*}
\min \left\{\left\|\nabla \mathfrak{u}_{n}\right\|_{\Phi_{1}}^{\mathfrak{l}_{1}}\left\|\nabla \mathfrak{u}_{n}\right\|_{\Phi_{1}}^{\boldsymbol{m}_{1}}\right\}+\min \left\{\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{\boldsymbol{l}_{2}}\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{\boldsymbol{m}_{2}}\right\} & \leqslant \int_{\Omega} \Phi_{1}\left(\left|\nabla u_{n}\right|\right) \mathrm{dx}+\int_{\Omega} \Phi_{2}\left(\left|\nabla v_{n}\right|\right) \mathrm{d} x  \tag{3.9}\\
& =\mathrm{I}\left(u_{n}, v_{n}\right)+\int_{\Omega} \mathrm{F}\left(x, u_{n}, v_{n}\right) \mathrm{d} x .
\end{align*}
$$

When $n$ large enough, that is

$$
\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{\mathbf{l}_{1}}+\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{l_{2}} \leqslant I\left(u_{n}, v_{n}\right)+\int_{\Omega} F\left(x, u_{n}, v_{n}\right) d x
$$

which is equivalent to

$$
\begin{align*}
1 & \leqslant \frac{\mathrm{I}\left(u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{l_{2}}}+\left(\int_{\left|\left(u_{n}, v_{n}\right)\right| \leqslant R}+\int_{\left|\left(u_{n}, v_{n}\right)\right|>R}\right) \frac{F\left(x, u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}+\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{l_{2}}} d x}  \tag{3.10}\\
& =o_{n}(1)+\int_{\left|\left(u_{n}, v_{n}\right)\right| \leqslant R} \frac{F\left(x, u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{l_{2}}} d x+\int_{\left|\left(u_{n}, v_{n}\right)\right|>R} \frac{F\left(x, u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{l_{2}}} d x,
\end{align*}
$$

where $R$ is a positive constant such that $R>r\left(\right.$ see $\left.\left(F_{4}\right)\right)$ and

$$
F(x, u, v) \geqslant 0, \quad \forall x \in \Omega, \quad|(u, v)|>R \quad\left(b y\left(F_{3}\right)\right)
$$

By the fact that $F$ is continuous, there exists a constant $C_{R}>0$ such that

$$
\begin{equation*}
|F(x, u, v)|<C_{R}, \quad \forall x \in \Omega, \quad|(u, v)| \leqslant R . \tag{3.11}
\end{equation*}
$$

Then

$$
\begin{equation*}
\int_{\left|\left(u_{n}, v_{n}\right)\right| \leqslant R} \frac{F\left(x, u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{l_{2}}} d x \leqslant \frac{C_{R}|\Omega|}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{l_{2}}}=o_{n}(1) \tag{3.12}
\end{equation*}
$$

Besides, it follows from Hölder's inequality that

$$
\begin{array}{rl}
\int_{\left|\left(u_{n}, v_{n}\right)\right|>R} & F\left(x, u_{n}, v_{n}\right) \\
\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+\left\|\nabla v_{n}\right\|_{\Phi_{2}}^{l_{2}}  \tag{3.13}\\
= & \int_{\left|\left(u_{n}, v_{n}\right)\right|>R} \frac{F\left(x, u_{n}, v_{n}\right)}{\frac{\left|u_{n}\right|^{l_{1}}}{\left|\bar{u}_{n}\right|^{l_{1}}}+\frac{\left|v_{n}\right|^{l_{2}}}{\left|\bar{v}_{n}\right|^{l_{2}}}} d x \\
& \leqslant \int_{\left|\left(u_{n}, v_{n}\right)\right|>R} \frac{F\left(x, u_{n}, v_{n}\right)}{\left|u_{n}\right|^{l_{1}}+\left|v_{n}\right|^{l_{2}}}\left(\left|\bar{u}_{n}\right|^{l_{1}}+\left|\bar{v}_{n}\right|^{l_{2}}\right) d x \\
& \leqslant 2\left\|\frac{F\left(x, u_{n}, v_{n}\right)}{\left|u_{n}\right|^{l_{1}}+\left|v_{n}\right|^{l_{2}}} \chi\left\{\left|\left(u_{n}, v_{n}\right)\right|>R\right\}\right\|_{\Gamma}\left\|\left(\left|\bar{u}_{n}\right|^{l_{1}}+\left|\bar{v}_{n}\right|^{l_{2}}\right) \chi\left\{\left|\left(u_{n}, v_{n}\right)\right|>R\right\}\right\| \tilde{\Gamma}^{\prime}
\end{array}
$$

where $\chi$ denotes the characteristic function which satisfies

$$
\chi\left\{\left|\left(u_{n}(x), v_{n}(x)\right)\right|>R\right\}= \begin{cases}1 & \text { for } x \in\left\{x \in \Omega:\left|\left(u_{n}(x), v_{n}(x)\right)\right|>R\right\} \\ 0 & \text { for } x \in\left\{x \in \Omega:\left|\left(u_{n}(x), v_{n}(x)\right)\right| \leqslant R\right\}\end{cases}
$$

For $n$ large enough, by (3.3), (3.8) and the fact that $\overline{\mathrm{F}}$ is continuous, we obtain

$$
\int_{\Omega} \Gamma\left(\frac{F\left(x, u_{n}, v_{n}\right)}{\left|u_{n}\right|^{l_{1}}+\left|v_{n}\right|^{l_{2}}} x\left\{\left|\left(u_{n}, v_{n}\right)\right|>R\right) d x \leqslant c_{3} \int_{\Omega} \bar{F}\left(x, u_{n}, v_{n}\right) d x+C \leqslant c_{3}(c+1)+C .\right.
$$

Then, for $n$ large enough, by Lemma 2.4 , there exists a constant $\mathrm{J}>0$ such that

$$
\begin{equation*}
\left\|\frac{F\left(x, u_{n}, v_{n}\right)}{\left|u_{n}\right|^{l_{1}}+\left|v_{n}\right|^{l_{2}}} x\left\{\left|\left(u_{n}, v_{n}\right)\right|>R\right\}\right\|_{\Gamma} \leqslant J . \tag{3.14}
\end{equation*}
$$

Moreover, it is easy to see that

$$
\left\|\left(\left|\bar{u}_{n}\right|^{l_{1}}+\left|\bar{v}_{n}\right|^{l_{2}}\right) \chi\left\{\left|\left(u_{n}, v_{n}\right)\right|>R\right\}\right\|_{\tilde{\Gamma}} \leqslant\left\|\left(\left|\bar{u}_{n}\right|^{l_{1}}+\left|\bar{v}_{n}\right|^{l_{2}}\right)\right\|_{\tilde{\Gamma}} \leqslant\left\|\left|\bar{u}_{n}\right|^{l_{1}}\right\|_{\tilde{\Gamma}}+\left\|\left|\bar{v}_{n}\right|^{l_{2}}\right\|_{\tilde{\Gamma}}
$$

By Lemma 2.3 and Lemma 2.5, $\left(F_{4}\right)$ implies that $N$-function $\widetilde{\Gamma}$ satisfies a $\Delta_{2}$-condition globally. Then, by (2.2), $\|u\|_{\tilde{\Gamma}} \rightarrow 0$ as $\int_{\Omega} \widetilde{\Gamma}(|u|) \mathrm{d} x \rightarrow 0$. It follows from Lemma 2.5 and $\star$ that

$$
\begin{aligned}
\int_{\Omega} \widetilde{\Gamma}\left(\left|\bar{u}_{n}\right|^{l_{1}}\right) d x+ & \int_{\Omega} \widetilde{\Gamma}\left(\left|\bar{v}_{n}\right|^{l_{2}}\right) d x \\
& \leqslant \widetilde{\Gamma}(1) \int_{\Omega} \max \left\{\left|\bar{u}_{n}\right|^{l_{1} \tau_{\Gamma}},\left|\bar{u}_{n}\right|^{l_{1} \widetilde{m_{\Gamma}}}\right\} d x+\widetilde{\Gamma}(1) \int_{\Omega} \max \left\{\left.\bar{v}_{n}\right|^{l_{2} \widetilde{l}_{\Gamma}},\left|\bar{v}_{n}\right|^{l_{2} \widetilde{m_{\Gamma}}}\right\} d x \\
& \leqslant \widetilde{\Gamma}(1)\left(\int_{\Omega}\left|\bar{u}_{n}\right|^{l_{1} \widetilde{l_{\Gamma}}} d x+\int_{\Omega}\left|\bar{u}_{n}\right|^{l_{1} \widetilde{m_{\Gamma}}} d x+\int_{\Omega}\left|\bar{v}_{n}\right|^{l_{2} \widetilde{l_{\Gamma}}} d x+\int_{\Omega}\left|\bar{v}_{n}\right|^{l_{2} \widetilde{m_{\Gamma}}} d x\right)=o_{n}(1),
\end{aligned}
$$

which implies

$$
\begin{equation*}
\left\|\left(\left|\bar{u}_{n}\right|^{l_{1}}+\left|\bar{v}_{n}\right|^{l_{2}}\right) \chi\left\{\left|\left(u_{n}, v_{n}\right)\right|>R\right\}\right\|_{\tilde{\Gamma}} \leqslant\left\|\left|\bar{u}_{n}\right|^{l_{1}}\right\|_{\tilde{\Gamma}}+\left\|\left|\bar{v}_{n}\right|^{l_{2}}\right\|_{\tilde{\Gamma}}=o_{n}(1) . \tag{3.15}
\end{equation*}
$$

By combining (3.12), (3.13), (3.14), (3.15) with (3.10), we get a contradiction.
Case 2. Suppose that $\left\|\nabla u_{n}\right\|_{\Phi_{1}} \leqslant C$ or $\left\|\nabla v_{n}\right\|_{\Phi_{2}} \leqslant C$ for some $C>0$ and all $n \in \mathbb{N}$. Without loss of generality, we assume that $\left\|\nabla u_{n}\right\|_{\Phi_{1}} \rightarrow+\infty$ and $\left\|\nabla v_{n}\right\|_{\Phi_{2}} \leqslant C$, for some $C>0$ and all $n \in \mathbb{N}$. Let $\bar{u}_{n}=\frac{\mathfrak{u}_{n}}{\left\|\nabla \mathfrak{u}_{n}\right\|_{\Phi_{1}}}$ and $\bar{v}_{n}=\frac{v_{n}}{\left\|\nabla \mathfrak{u}_{n}\right\|_{\Phi_{1}}}$. Then $\left\|\bar{u}_{n}\right\|_{0, \Phi_{1}}=1$ and $\left\|\bar{v}_{n}\right\|_{0, \Phi_{2}} \rightarrow 0$. Passing to a subsequences $\left\{\left(\bar{u}_{n}, \bar{v}_{n}\right)\right\}$, by Remark 3.2, there exist $\bar{u} \in W_{0}^{1, \Phi_{1}}(\Omega)$ and $v \in W_{0}^{1, \Phi_{2}}(\Omega)$ such that
$\star \quad \bar{u}_{n} \rightharpoonup \bar{u}$ in $W_{0}^{1, \Phi_{1}}(\Omega), \quad \bar{u}_{n} \rightarrow \bar{u}$ in $L^{l_{1} \widetilde{l_{\Gamma}}}(\Omega)$ and in $L^{l_{1}} \widetilde{m_{\Gamma}}(\Omega), \quad \bar{u}_{n}(x) \rightarrow \bar{u}(x)$ a.e. in $\Omega$;
$\star \quad \bar{v}_{n} \rightarrow 0$ in $W_{0}^{1, \Phi_{2}}(\Omega), \quad \bar{v}_{n} \rightarrow 0$ in $L^{l_{2} \widetilde{l_{\Gamma}}}(\Omega)$ and in $L^{l_{2} \widetilde{m_{\Gamma}}}(\Omega), \quad \bar{v}_{n}(x) \rightarrow 0$ a.e. in $\Omega$;
$\star \quad v_{n} \rightharpoonup v$ in $W_{0}^{1, \Phi_{2}}(\Omega), \quad v_{n} \rightarrow v$ in $L^{l_{2} \widetilde{l}_{\Gamma}}(\Omega)$ and in $L^{l_{2}} \widetilde{m_{\Gamma}}(\Omega), \quad v_{n}(x) \rightarrow v(x)$ a.e. in $\Omega$.
Similarly, we firstly assume that $[\bar{u} \neq 0]$ has nonzero Lebesgue measure. We can see that

$$
\left|u_{n}\right|=\left|\bar{u}_{n}\right|\left\|\nabla u_{n}\right\|_{\Phi_{1}} \rightarrow+\infty \quad \text { in }[\bar{u} \neq 0] .
$$

Then, by (3.8), Remark 3.3 and Fatou's Lemma, we get a contradiction by

$$
c+1 \geqslant \int_{\Omega} \overline{\mathrm{F}}\left(\mathrm{x}, \mathrm{u}_{\mathrm{n}}, v_{\mathrm{n}}\right) \mathrm{d} x \rightarrow+\infty
$$

Next, we suppose that $[\bar{u} \neq 0]$ has zero Lebesgue measure, that is, $\bar{u}=0$ in $W_{0}^{1, \Phi_{1}}(\Omega)$. By Lemma 2.5 and $\star$, we have

$$
\begin{aligned}
\min \left\{\left|\left|\left|v_{n}\right|^{l_{2}}\left\|_{\widetilde{\Gamma}}^{\widetilde{c_{r}}},\right\|\right| v_{n}\right|^{l_{2}} \| \widetilde{\Gamma} \widetilde{\tilde{m}_{\Gamma}}\right\} & \leqslant \int_{\Omega} \widetilde{\Gamma}\left(\left|v_{n}\right|^{l_{2}}\right) \mathrm{d} x \\
& \leqslant \widetilde{\Gamma}(1) \int_{\Omega} \max \left\{\left|v_{n}\right|^{l_{2} \widetilde{l_{\Gamma}}},\left|v_{n}\right|^{l_{2} \widetilde{m_{\Gamma}}}\right\} \mathrm{d} x \\
& \leqslant \widetilde{\Gamma}(1)\left(\int_{\Omega}\left|v_{n}\right|^{l_{2} \widetilde{l_{\Gamma}}} d x+\int_{\Omega}\left|v_{n}\right|^{l_{2} \widetilde{m_{\Gamma}}} d x\right) \rightarrow C
\end{aligned}
$$

which shows that there exists a constant $L>0$ such that

$$
\begin{equation*}
\left\|\left|v_{n}\right|^{l_{2}}\right\|_{\tilde{\Gamma}} \leqslant \mathrm{L}, \quad \forall \mathrm{n} \in \mathbb{N} \tag{3.16}
\end{equation*}
$$

When $n$ large enough, (3.9) changed into

$$
\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+M \leqslant I\left(u_{n}, v_{n}\right)+\int_{\Omega} F\left(x, u_{n}, v_{n}\right) d x+M
$$

where $M$ is a positive constant with $M>4 J L$ (see (3.14) and (3.16)). Then, by (3.11), (3.14), (3.15), (3.16) and Hölder's inequality, above estimate means

$$
\begin{aligned}
1 & \leqslant \frac{I\left(u_{n}, v_{n}\right)+M}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+M}+\int_{\Omega} \frac{F\left(x, u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+M} d x \\
& =o_{n}(1)+\int_{\left|\left(u_{n}, v_{n}\right)\right| \leqslant R} \frac{F\left(x, u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+M} d x+\int_{\left|\left(u_{n}, v_{n}\right)\right|>R} \frac{F\left(x, u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+M} d x \\
& =o_{n}(1)+\int_{\left|\left(u_{n}, v_{n}\right)\right|>R} \frac{F\left(x, u_{n}, v_{n}\right)}{\left\|\nabla u_{n}\right\|_{\Phi_{1}}^{l_{1}}+M} d x \\
& \leqslant o_{n}(1)+\int_{\left|\left(u_{n}, v_{n}\right)\right|>R} \frac{F\left(x, u_{n}, v_{n}\right)}{\left|u_{n}\right|^{l_{1}+\left|v_{n}\right|^{l_{2}}}}\left(\left|\bar{u}_{n}\right|^{l_{1}}+\frac{1}{M}\left|v_{n}\right|^{l_{2}}\right) d x
\end{aligned}
$$

$$
\begin{aligned}
& \leqslant o_{n}(1)+2\left\|\frac{F\left(x, u_{n}, v_{n}\right)}{\left|u_{n}\right|^{l_{1}}+\left|v_{n}\right|^{l_{2}}} x\left\{\left|\left(u_{n}, v_{n}\right)\right|>R\right\}\right\|_{\Gamma}\left\|\left(\left|\bar{u}_{n}\right|^{l_{1}}+\frac{1}{M}\left|v_{n}\right|^{l_{2}}\right) x\left\{\left|\left(u_{n}, v_{n}\right)\right|>R\right\}\right\|_{\tilde{\Gamma}} \\
& \leqslant o_{n}(1)+2 J\left(\left\|\left|\bar{u}_{n}\right|^{l_{1}}\right\|_{\tilde{\Gamma}}+\frac{1}{M}\left\|\left|v_{n}\right|^{l_{2}}\right\|_{\tilde{r}}\right) \\
& \leqslant o_{n}(1)+2 J\left(o_{n}(1)+\frac{L}{M}\right)=o_{n}(1)+\frac{2 J L}{M}<o_{n}(1)+\frac{1}{2},
\end{aligned}
$$

which is a contradiction.
Lemma 3.9. Suppose that $\left(\phi_{1}\right)-\left(\phi_{3}\right),\left(F_{1}\right),\left(F_{3}\right)$ and $\left(F_{4}\right)$ hold. Then I satisfies $(C)_{c}$-condition.
Proof. Let $\left\{\left(u_{n}, v_{n}\right)\right\}$ be any $(C)_{c}$-sequence of I in W. Lemma 3.8 shows $\left\{\left(u_{n}, v_{n}\right)\right\}$ is bounded. Passing to a subsequence $\left\{\left(u_{n}, v_{n}\right)\right\}$, by Remark 3.2, there exists a point $(u, v) \in W$ such that
$\star \quad u_{n} \rightharpoonup u$ in $W_{0}^{1, \Phi_{1}}(\Omega), \quad u_{n} \rightarrow u$ in $L^{\Psi_{1}}(\Omega), \quad u_{n}(x) \rightarrow \mathfrak{u}(x)$ a.e. in $\Omega$;
$\star \quad v_{n} \rightharpoonup v$ in $W_{0}^{1, \Phi_{2}}(\Omega), \quad v_{n} \rightarrow v$ in $L^{\Psi_{2}}(\Omega), \quad v_{n}(x) \rightarrow v(x)$ a.e. in $\Omega$.
Now, we define operators
$\mathcal{F}: W_{0}^{1, \Phi_{1}}(\Omega) \rightarrow\left(W_{0}^{1, \Phi_{1}}(\Omega)\right)^{*}$ by $\langle\mathcal{F}(u), \tilde{u}\rangle:=\int_{\Omega} \phi_{1}(|\nabla u|) \nabla u \nabla \tilde{u} d x, u, \tilde{u} \in W_{0}^{1, \Phi_{1}}(\Omega)$, and $\mathcal{G}: W_{0}^{1, \Phi_{2}}(\Omega) \rightarrow\left(W_{0}^{1, \Phi_{2}}(\Omega)\right)^{*}$ by $\langle\mathcal{G}(v), \tilde{v}\rangle:=\int_{\Omega} \Phi_{2}(|\nabla v|) \nabla v \nabla \tilde{v} \mathrm{~d} x, \quad v, \tilde{v} \in W_{0}^{1, \Phi_{2}}(\Omega)$.

Then, we have

$$
\begin{align*}
\left\langle\mathcal{F}\left(\mathfrak{u}_{n}\right), \mathfrak{u}_{n}-u\right\rangle & =\int_{\Omega} \phi_{1}\left(\left|\nabla \mathfrak{u}_{n}\right|\right) \nabla \mathfrak{u}_{n} \nabla\left(u_{n}-u\right) d x  \tag{3.17}\\
& =\left\langle I^{\prime}\left(u_{n}, v_{n}\right),\left(u_{n}-u, 0\right)\right\rangle+\int_{\Omega} F_{u}\left(x, u_{n}, v_{n}\right)\left(u_{n}-u\right) d x .
\end{align*}
$$

Equation (3.5) shows that

$$
\begin{equation*}
\left|\left\langle\mathrm{I}^{\prime}\left(u_{n}, v_{n}\right),\left(u_{n}-u, 0\right)\right\rangle\right| \leqslant\left\|I^{\prime}\left(u_{n}, v_{n}\right)\right\|\left\|u_{n}-u\right\|_{0, \Phi_{1}} \rightarrow 0 . \tag{3.18}
\end{equation*}
$$

By $\left(F_{1}\right)$ and Hölder's inequality, we get

$$
\begin{align*}
\left|\int_{\Omega} F_{u}\left(x, u_{n}, v_{n}\right)\left(u_{n}-u\right) d x\right| & \leqslant c_{1} \int_{\Omega}\left(1+\psi_{1}\left(\left|u_{n}\right|\right)+\widetilde{\Psi}_{1}^{-1}\left(\Psi_{2}\left(v_{n}\right)\right)\right)\left|u_{n}-u\right| d x  \tag{3.19}\\
& \leqslant 2 c_{1}\left\|1+\psi_{1}\left(\left|u_{n}\right|\right)+\widetilde{\Psi}_{1}^{-1}\left(\Psi_{2}\left(v_{n}\right)\right)\right\|_{\widetilde{\Psi}_{1}}\left\|u_{n}-u\right\|_{\Psi_{1}} .
\end{align*}
$$

Condition ( $\mathrm{F}_{1}$ ) shows that functions $\Psi_{1}$ and $\widetilde{\Psi}_{1}$ are N -functions satisfying $\Delta_{2}$-condition globally, which together with the convexity of N -function, Lemma 2.4, Remark 3.2 and the boundedness of $\left\{\left(u_{n}, v_{n}\right)\right\}$, implies that

$$
\int_{\Omega} \widetilde{\Psi}_{1}\left(1+\psi_{1}\left(\left|u_{n}\right|\right)+\widetilde{\Psi}_{1}^{-1}\left(\Psi_{2}\left(v_{n}\right)\right)\right) \mathrm{d} x \leqslant \mathrm{C} \int_{\Omega}\left(1+\Psi_{1}\left(u_{n}\right)+\Psi_{2}\left(v_{n}\right)\right) \mathrm{d} x \leqslant \mathrm{C}
$$

which, together with Lemma 2.4 again, shows that

$$
\begin{equation*}
\left\|1+\psi_{1}\left(\left|u_{n}\right|\right)+\widetilde{\Psi}_{1}^{-1}\left(\Psi_{2}\left(v_{n}\right)\right)\right\|_{\widetilde{\Psi}_{1}} \leqslant C \tag{3.20}
\end{equation*}
$$

for some $C>0$. Moreover, $\star$ shows that

$$
\begin{equation*}
\left\|u_{n}-u\right\|_{\Psi_{1}} \rightarrow 0 \tag{3.21}
\end{equation*}
$$

Then, combining (3.18), (3.19), (3.20), (3.21) with (3.17), we obtain

$$
\left\langle\mathcal{F}\left(u_{n}\right), u_{n}-u\right\rangle \rightarrow 0, \quad \text { as } n \rightarrow \infty .
$$

By [12, Proposition A.3], $\mathcal{F}$ is of the class ( $S_{+}$), that is, if a sequence $\left\{u_{n}\right\} \subset W_{0}^{1, \Phi_{1}}(\Omega)$ satisfying

$$
u_{n} \rightharpoonup u \quad \text { and } \quad \underset{n \rightarrow \infty}{\limsup }\left\langle\mathcal{F}\left(u_{n}\right), u_{n}-u\right\rangle \leqslant 0
$$

then $\mathfrak{u}_{n} \rightarrow u$ in $W_{0}^{1, \Phi_{1}}(\Omega)$. Thus $u_{n} \rightarrow u$ in $W_{0}^{1, \Phi_{1}}(\Omega)$. Similarly, we can obtain that $v_{n} \rightarrow v$ in $W_{0}^{1, \Phi_{2}}(\Omega)$. Therefore, $\left\{\left(u_{n}, v_{n}\right)\right\} \rightarrow(u, v)$ in $W$.

Proof of Theorem 3.1. By Lemmas 3.6, 3.7, 3.9 and the obvious fact $\mathrm{I}(0)=0$, all conditions of Lemma 3.5 hold. Then system (1.1) possesses a nontrivial weak solution which is a critical point of I.

## 4. Multiplicity

In this section, we present the following multiplicity result by using symmetric mountain pass theorem.
Theorem 4.1. Assume that $\left(\phi_{1}\right)-\left(\phi_{3}\right),\left(F_{0}\right),\left(F_{1}\right)$,
$\left(\mathrm{F}_{4}\right)$ and the following conditions hold:
( $\mathrm{F}_{5}$ )

$$
\lim _{|(u, v)| \rightarrow+\infty} \frac{F(x, u, v)}{|u|^{m_{1}}+|v|^{\mathbf{m}_{2}}}=+\infty \text { uniformly in } x \in \Omega
$$

$\left(\mathrm{F}_{6}\right) \mathrm{F}(\mathrm{x},-\mathrm{u},-v)=\mathrm{F}(\mathrm{x}, \mathrm{u}, v)$, for all $(\mathrm{x}, \mathrm{u}, v) \in \Omega \times \mathbb{R} \times \mathbb{R}$.
Then system (1.1) possesses infinitely many weak solutions $\left\{\left(\mathfrak{u}_{\mathrm{k}}, v_{\mathrm{k}}\right)\right\}$ such that

$$
\mathrm{I}\left(\mathfrak{u}_{\mathrm{k}}, v_{\mathrm{k}}\right):=\int_{\Omega} \Phi_{1}\left(\left|\nabla \mathfrak{u}_{\mathrm{k}}\right|\right) \mathrm{d} x+\int_{\Omega} \Phi_{2}\left(\left|\nabla v_{\mathrm{k}}\right|\right) \mathrm{d} x-\int_{\Omega} \mathrm{F}\left(\mathrm{x}, \mathfrak{u}_{\mathrm{k}}, v_{\mathrm{k}}\right) \mathrm{d} x \rightarrow+\infty, \text { as } \mathrm{k} \rightarrow \infty .
$$

Now, we display the symmetric mountain pass theorem as follows.
Lemma 4.2 ([30, Theorem 9.12]). Let E be an infinite-dimensional Banach space and let $\mathrm{I} \in \mathrm{C}^{1}(\mathrm{E}, \mathbb{R})$ be even, satisfy (PS)-condition, and $\mathrm{I}(0)=0$. If $\mathrm{E}=\mathrm{V} \oplus \mathrm{X}$, where V is finite dimensional, and I satisfies
( $\mathrm{I}_{1}$ ) there are constants $\rho, \alpha>0$ such that $\left.\mathrm{I}\right|_{\partial \mathrm{B}_{\rho} \cap \mathrm{X}} \geqslant \alpha$, and
( $\mathrm{I}_{2}$ ) for each finite dimensional subspace $\widetilde{\mathrm{E}} \subset \mathrm{E}$, there is an $\mathrm{R}=\mathrm{R}(\widetilde{\mathrm{E}})$ such that $\mathrm{I} \leqslant 0$ on $\widetilde{\mathrm{E}} \backslash \mathrm{B}_{\mathrm{R}(\tilde{\mathrm{E}})}$, where $B_{r}=\{u \in E:\|u\|<r\}$,
then I possesses an unbounded sequence of critical values.
Since $W_{0}^{1, \Phi_{i}}(\Omega)(i=1,2)$ are reflexive and separable Banach spaces, then there exist sequences $\left\{e_{i j}: \mathfrak{j} \in \mathbb{N}\right\} \subset W_{0}^{1, \Phi_{i}}(\Omega)(i=1,2)$ and $\left\{e_{i j}^{*}: j \in \mathbb{N}\right\} \subset W_{0}^{1, \Phi_{i}}(\Omega)^{*}(i=1,2)$ such that

$$
\begin{equation*}
\mathrm{W}_{0}^{1, \Phi_{i}}(\Omega)=\overline{\operatorname{span}\left\{e_{i j}: \mathfrak{j}=1,2, \cdots\right\}}, \quad \mathrm{W}_{0}^{1, \Phi_{i}}(\Omega)^{*}=\overline{\operatorname{span}\left\{e_{i j}^{*}: \mathfrak{j}=1,2, \cdots\right\}}, \quad \mathfrak{i}=1,2, \tag{4.1}
\end{equation*}
$$

and

$$
e_{i n}^{*}\left(e_{\mathfrak{i m}}\right)=\left\{\begin{array}{ll}
1 & \text { if } n=m  \tag{4.2}\\
0 & \text { if } n \neq m,
\end{array} \quad i=1,2\right.
$$

(see [37, Section 17]). Define

$$
\begin{equation*}
Y_{i(k)}:=\operatorname{span}\left\{e_{i j}: j=1, \cdots, k\right\}, \quad Z_{i(k)}:=\overline{\operatorname{span}\left\{e_{i j}: j=k+1, \cdots\right\}}, \quad i=1,2 . \tag{4.3}
\end{equation*}
$$

Since the embeddings $W_{0}^{1, \Phi_{i}}(\Omega) \hookrightarrow L^{\Psi_{i}}(\Omega)(i=1,2)$ are compact, then, with a similar discussion as [13, Lemma 2.10 ], we can get

$$
\begin{equation*}
\alpha_{i(k)}:=\sup \left\{\|z\|_{\Psi_{i}}:\|z\|_{0, \Phi_{i}}=1, z \in Z_{i(k)}\right\} \rightarrow 0, \quad i=1,2, \text { as } k \rightarrow \infty . \tag{4.4}
\end{equation*}
$$

Lemma 4.3. Let $Y_{i(k)}$ and $Z_{i(k)}$ be the subsets of $\mathrm{W}_{0}^{1, \Phi_{i}}(\Omega)$ defined by (4.3). Then

$$
W_{0}^{1, \Phi_{i}}(\Omega)=Y_{i(k)} \oplus Z_{i(k)}, \quad i=1,2, \quad k \in \mathbb{N} .
$$

Proof. Let us prove that $W_{0}^{1, \Phi_{1}}(\Omega)=Y_{1(k)} \oplus Z_{1(k)}, k \in \mathbb{N}$. Then, with the same arguments, we can prove that $W_{0}^{1, \Phi_{2}}(\Omega)=Y_{2(k)} \oplus Z_{2(k)}, k \in \mathbb{N}$. It is clear that both $Y_{1(k)}$ and $Z_{1(k)}$ are closed subspaces of $W_{0}^{1, \Phi_{1}}(\Omega)$ for $k \in \mathbb{N}$. For any $x \in W_{0}^{1, \Phi_{1}}(\Omega)$, by (4.1), there exists a sequence $\left\{x_{n}\right\} \subset \operatorname{span}\left\{e_{1 j}: j=1,2, \cdots\right\}$ which converges to $x$. Let

$$
x_{n}=\sum_{l=1}^{N(n)} a_{l, n} e_{1 l}, \quad \text { where } a_{l, n} \in \mathbb{R}, N(n) \in \mathbb{N} \text { and } N(n) \geqslant k .
$$

Since $\left\{x_{n}\right\}$ is a Cauchy sequence, for any given $\delta>0$ there exists an $N$ such that

$$
\begin{equation*}
\left\|x_{n}-x_{m}-0\right\|_{0, \Phi_{1}}=\left\|x_{n}-x_{m}\right\|_{0, \Phi_{1}}=\left\|\sum_{l=1}^{N(n)} a_{l, n} e_{1 l}-\sum_{l=1}^{N(m)} a_{l, m} e_{1 l}\right\|_{0, \Phi_{1}}<\delta, \quad(m, n>N) . \tag{4.5}
\end{equation*}
$$

According to the continuity of $e_{1 j}^{*} \in W_{0}^{1, \Phi_{1}}(\Omega)^{*}(j=1, \cdots, k)$ and (4.2), for every $\varepsilon>0$, by (4.5), we can choose $\delta>0$ small enough such that

$$
\left|e_{1 j}^{*}\left(x_{n}-x_{m}\right)-e_{1 j}^{*}(0)\right|=\left|e_{1 j}^{*}\left(\sum_{l=1}^{N(n)} a_{l, n} e_{1 l}-\sum_{l=1}^{N(m)} a_{l, m} e_{1 l}\right)\right|=\left|a_{j, n}-a_{j, m}\right|<\varepsilon,
$$

which means that sequences $\left\{a_{j, n}: n=1,2, \cdots\right\}(j=1, \cdots, k)$ are Cauchy sequences in $\mathbb{R}$. Since $\mathbb{R}$ is complete, then there exist $a_{j} \in \mathbb{R}(j=1, \cdots, k)$ such that sequences $\left\{a_{j, n}\right\}$ converge to $a_{j}, j=1, \cdots, k$, as $n \rightarrow \infty$. Now we can choose a sequence $\left\{\tilde{x}_{n}\right\} \subset \operatorname{span}\left\{e_{1 j}: j=1,2, \cdots\right\}$ which satisfies

$$
\widetilde{x}_{n}=\sum_{j=1}^{k} a_{j} e_{1 j}+\sum_{l=k+1}^{N(n)} a_{l, n} e_{1 l} .
$$

We conclude that the sequence $\left\{\tilde{x}_{n}\right\}$ converges to $x$, because the sequence $\left\{x_{n}\right\}$ converges to $x$ and

$$
\begin{aligned}
\lim _{n \rightarrow \infty}\left\|x_{n}-\widetilde{x}_{n}\right\|_{0, \Phi_{1}} & =\lim _{n \rightarrow \infty}\left\|\sum_{l=1}^{k} a_{l, n} e_{1 l}-\sum_{j=1}^{k} a_{j} e_{1 j}\right\|_{0, \Phi_{1}} \\
& =\lim _{n \rightarrow \infty}\left\|\sum_{j=1}^{k}\left(a_{j, n}-a_{j}\right) e_{1 j}\right\|_{0, \Phi_{1}} \\
& \leqslant \lim _{n \rightarrow \infty} \sum_{j=1}^{k} \mid\left(a_{j, n}-a_{j}\right)\left\|e_{1 j}\right\|_{0, \Phi_{1}}=0 .
\end{aligned}
$$

Let

$$
y=\sum_{j=1}^{k} a_{j} e_{1 j} \quad \text { and } \quad z_{n}=\sum_{l=k+1}^{N(n)} a_{l, n} e_{1 l} .
$$

Then the sequence $\left\{z_{n}\right\} \subset \operatorname{span}\left\{e_{1 j}: j=k+1, \cdots\right\}$ converges to $x-y$, which implies $x-y \in Z_{1(k)}$. Note that $y \in Y_{1(k)}$ and $x=y+(x-y)$. We get $W_{0}^{1, \Phi_{1}}(\Omega)=Y_{1(k)}+Z_{1(k)}$. Now, we prove $Y_{1(k)} \cap Z_{1(k)}=\{0\}$.

Let $x \in Y_{1(k)} \cap Z_{1(k)}$. Then there exists a sequence $\left\{z_{n}\right\} \subset \operatorname{span}\left\{e_{1 j}: j=k+1, \cdots\right\}$ which converges to $x=\sum_{l=1}^{k} a_{l} e_{1 l}$. Let

$$
z_{n}=\sum_{l=k+1}^{N(n)} a_{l, n} e_{1 l} .
$$

By the continuity of $e_{1 j}^{*} \in W_{0}^{1, \Phi_{1}}(\Omega)^{*}(j=1, \cdots, k)$ and (4.2), we have

$$
\lim _{n \rightarrow \infty} e_{1 j}^{*}\left(z_{n}\right)=\lim _{n \rightarrow \infty} e_{1 j}^{*}\left(\sum_{l=k+1}^{N(n)} a_{l, n} e_{1 l}\right)=0=e_{1 j}^{*}\left(\sum_{l=1}^{k} a_{l} e_{1 l}\right)=a_{j}, \quad \text { for } j=1, \cdots, k,
$$

which implies $x=0$. Therefore, $W_{0}^{1, \Phi_{1}}(\Omega)=Y_{1(k)} \oplus Z_{1(k)}, k \in \mathbb{N}$.
Lemma 4.4. For Banach space $W=W_{0}^{1, \Phi_{1}}(\Omega) \times W_{0}^{1, \Phi_{2}}(\Omega)$, there exits a sequence $\left\{\eta_{(j)}\right\} \subset W$ defined by

$$
\eta_{(\mathfrak{j})}= \begin{cases}\left(e_{1 n}, 0\right) & \text { if } \mathfrak{j}=2 n-1,  \tag{4.6}\\ \left(0, e_{2 n}\right) & \text { if } \mathfrak{j}=2 n, \quad \text { for } n \in \mathbb{N},\end{cases}
$$

such that
(1)

$$
W=\overline{\operatorname{span}\left\{\mathfrak{\eta}_{(\mathfrak{j})}: \mathfrak{j}=1,2, \cdots\right\}},
$$

$$
\begin{equation*}
W=Y_{k} \oplus Z_{k} \tag{2}
\end{equation*}
$$

where

$$
Y_{k}:=\operatorname{span}\left\{\mathfrak{\eta}_{(j)}: \mathfrak{j}=1, \cdots, k\right\} \quad \text { and } \quad Z_{k}:=\overline{\operatorname{span}\left\{\eta_{(j)}: j=k+1, \cdots\right\}} .
$$

Proof.
(1) Since $W$ is complete, then it is obvious that $\overline{\operatorname{span}\left\{\eta_{(j)}: j=1,2, \cdots\right\} \subseteq W \text {. Now, we prove that } W \subseteq}$ $\operatorname{span}\left\{\mathfrak{\eta}_{(j)}: j=1,2, \cdots\right\}$. For every $(u, v) \in W$, by (4.1), there exist sequences
$\left\{u_{n}\right\} \subset \operatorname{span}\left\{e_{1 j}: j=1,2, \cdots\right\}$ and $\left\{v_{n}\right\} \subset \operatorname{span}\left\{e_{2 j}: j=1,2, \cdots\right\}$ which converge to $u$ in $W_{0}^{1, \Phi_{1}}(\Omega)$ and $v$ in $W_{0}^{1, \Phi_{2}}(\Omega)$, respectively. Let

$$
u_{n}=\sum_{j=1}^{N_{1}(n)} a_{j, n} e_{1 j} \quad \text { and } v_{n}=\sum_{j=1}^{N_{2}(n)} b_{j, n} e_{2 j}, \quad \text { where } a_{j, n}, b_{j, n} \in \mathbb{R} \quad \text { and } \quad N_{1}(n), N_{2}(n) \in \mathbb{N} .
$$

Then

$$
\left(u_{n}, v_{n}\right)=\left(\sum_{j=1}^{N_{1}(n)} a_{j, n} e_{1 j}, \sum_{j=1}^{N_{2}(n)} b_{j, n} e_{2 j}\right)=\sum_{j=1}^{N_{1}(n)} a_{j, n}\left(e_{1 j}, 0\right)+\sum_{j=1}^{N_{2}(n)} b_{j, n}\left(0, e_{2 j}\right) .
$$

By (4.6) and last equality, we get $\left\{\left(u_{n}, v_{n}\right)\right\} \subset \operatorname{span}\left\{\eta_{(j)}: j=1,2, \cdots\right\}$ and

$$
\left\|\left(u_{n}, v_{n}\right)-(u, v)\right\|=\left\|\left(u_{n}-u, v_{n}-v\right)\right\|=\left\|u_{n}-u\right\|_{0, \Phi_{1}}+\left\|v_{n}-v\right\|_{0, \Phi_{2}} \rightarrow 0, \text { as } n \rightarrow \infty,
$$

which implies that $(\mathfrak{u}, v) \in \overline{\operatorname{span}\left\{\mathfrak{\eta}_{(\mathfrak{j})}: \mathfrak{j}=1,2, \cdots\right\}}$. So, $W \subseteq \overline{\operatorname{span}\left\{\mathfrak{\eta}_{(\mathfrak{j})}: \mathfrak{j}=1,2, \cdots\right\}}$. Therefore, $\boldsymbol{w}=$ $\overline{\operatorname{span}\left\{\mathfrak{\eta}_{(j)}: \mathfrak{j}=1,2, \cdots\right\}}$.
(2) Combining Lemma 4.3 with (4.6), we can see that

$$
\eta_{(\mathfrak{n})} \notin \overline{\operatorname{span}\left\{\mathfrak{n}_{(\mathfrak{j})}: \mathfrak{j}=1,2, \cdots \text { and } \mathfrak{j} \neq \mathfrak{n}\right\}}, \quad \forall \mathfrak{n} \in \mathbb{N} .
$$

Then there exists (see [37, Section 17]) a sequence $\left\{\mathfrak{\eta}_{(j)}^{*}\right\} \subset W^{*}$ such that

$$
\eta_{(\mathfrak{n})}^{*}\left(\eta_{(\mathfrak{m})}\right)= \begin{cases}1 & \text { if } \mathfrak{n}=\boldsymbol{m} \\ 0 & \text { if } \mathfrak{n} \neq \boldsymbol{m} .\end{cases}
$$

With the same discussion as Lemma 4.3, we can obtain that $W=Y_{k} \oplus Z_{k}$.
Lemma 4.5. Suppose that $\left(\phi_{1}\right)-\left(\phi_{3}\right)$ and $\left(F_{1}\right)$ hold. Then there are constants $\rho, \alpha>0$ and $k \in \mathbb{N}$ such that $\left.\mathrm{I}\right|_{\partial \mathrm{B}_{\mathrm{p}} \cap \mathrm{Z}_{2 k}} \geqslant \alpha$.
Proof. For $(u, v) \in Z_{2 k}$, by (3.4), (4.4) and Lemma 2.4, we have

$$
\begin{aligned}
& \mathrm{I}(\mathbf{u}, v)=\int_{\Omega} \Phi_{1}(|\nabla \mathfrak{u}|) \mathrm{d} x+\int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{d} x-\int_{\Omega} \mathrm{F}(\mathrm{x}, \mathbf{u}, v) \mathrm{d} x \\
& \geqslant \int_{\Omega} \Phi_{1}(|\nabla u|) \mathrm{d} x+\int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{d} x-\mathrm{c}_{5} \int_{\Omega} \Psi_{1}(\mathfrak{u}) \mathrm{d} x-\mathrm{c}_{5} \int_{\Omega} \Psi_{2}(v) \mathrm{d} x-\mathrm{c}_{5}|\Omega| \\
& \geqslant \min \left\{\|\nabla u\|_{\Phi_{1}}^{l_{1}},\|\nabla u\|_{\Phi_{1}}^{m_{1}}\right\}+\min \left\{\|\nabla v\|_{\Phi_{2}}^{\boldsymbol{l}_{2}},\|\nabla v\|_{\Phi_{2}}^{m_{2}}\right\} \\
& -c_{5} \max \left\{\|u\|_{\Psi_{1}}^{\mathfrak{l}_{1}},\|u\|_{\Psi_{1}}^{\boldsymbol{m}_{\Psi_{1}}}\right\}-c_{5} \max \left\{\|v\|_{\Psi_{2}}^{\mathfrak{L}_{2}},\|v\|_{\Psi_{2}}^{\boldsymbol{m}_{\Psi_{2}}}\right\}-c_{5}|\Omega| \\
& \geqslant \min \left\{\|\nabla u\|_{\Phi_{1}}^{l_{1}},\|\nabla u\|_{\Phi_{1}}^{\boldsymbol{m}_{1}}\right\}+\min \left\{\|\nabla v\|_{\Phi_{2}}^{\boldsymbol{l}_{2}},\|\nabla v\|_{\Phi_{2}}^{m_{2}}\right\}
\end{aligned}
$$

Since $\alpha_{i(k)} \rightarrow 0, i=1,2$, as $k \rightarrow \infty$, then above inequality implies that there exist constants $\rho>0$, lager $\mathrm{k} \in \mathbb{N}$ and $\alpha>0$ such that $\left.\mathrm{I}\right|_{\partial \mathrm{B}_{\rho} \cap \mathrm{Z}_{2 \mathrm{k}}} \geqslant \alpha$.

Lemma 4.6. Suppose that $\left(\phi_{1}\right)-\left(\phi_{3}\right)$ and $\left(F_{5}\right)$ hold. Then for each finite dimensional subspace $\widetilde{W} \subset W$, there exists a positive constant $R=R(\widetilde{W})$ such that $I \leqslant 0$ on $\widetilde{W} \backslash B_{R}(\widetilde{W})$.
Proof. For each finite dimensional subspace $\widetilde{W} \subset W$, one has $\widetilde{W} \subseteq W_{1} \times W_{2}$, where $W_{1}$ and $W_{2}$ are finite dimensional subspaces of $W_{0}^{1, \Phi_{1}}(\Omega)$ and $W_{0}^{1, \Phi_{2}}(\Omega)$, respectively. Since any two norms in finite dimensional space is equivalent, then there exist positive constants $d_{1}, d_{2} . d_{3}, d_{4}$ such that

$$
\begin{align*}
& \mathrm{d}_{1}\|\nabla \mathrm{u}\|_{\Phi_{1}} \leqslant\|u\|_{\mathrm{L}^{m_{1}}(\Omega)} \leqslant \mathrm{d}_{2}\|\nabla \mathrm{u}\|_{\Phi_{1}}, \quad \forall u \in W_{1},  \tag{4.7}\\
& \mathrm{~d}_{3}\|\nabla v\|_{\Phi_{2}} \leqslant\|v\|_{\mathrm{L}^{m_{2}}(\Omega)} \leqslant \mathrm{d}_{4}\|\nabla v\|_{\Phi_{2}}, \quad \forall v \in W_{2} .
\end{align*}
$$

Moreover, ( $F_{5}$ ) and the continuity of function $F$ imply that for any given constant $M>\max \left\{\frac{2}{d_{1}^{m_{1}}}, \frac{2}{d_{3}^{m_{2}}}\right\}$, there exists a constant $C_{M}>0$ such that

$$
\begin{equation*}
F(x, u, v) \geqslant M\left(|u|^{m_{1}}+|v|^{m_{2}}-C_{M}, \quad \forall(x, u, v) \in \Omega \times \mathbb{R} \times \mathbb{R} .\right. \tag{4.8}
\end{equation*}
$$

Then, by (4.7), (4.8) and Lemma 2.4, when $(u, v) \in \widetilde{W}$ we have

$$
\begin{aligned}
& \mathrm{I}(\mathfrak{u}, v)=\int_{\Omega} \Phi_{1}(|\nabla \mathfrak{u}|) \mathrm{d} x+\int_{\Omega} \Phi_{2}(|\nabla v|) \mathrm{d} x-\int_{\Omega} \mathrm{F}(\mathrm{x}, \mathrm{u}, v) \mathrm{d} x \\
& \leqslant \max \left\{\|\nabla \mathfrak{u}\|_{\Phi_{1},}^{\mathrm{l}_{1}}\|\nabla \mathfrak{u}\|_{\Phi_{1}}^{\boldsymbol{m}_{1}}\right\}+\max \left\{\|\nabla v\|_{\Phi_{2}}^{\mathrm{l}_{2}},\|\nabla v\|_{\Phi_{2}}^{m_{2}}\right\}-M \int_{\Omega}\left(|\mathfrak{u}|^{\boldsymbol{m}_{1}}+|v|^{m_{2}}\right) \mathrm{d} x+\mathrm{C}_{M}|\Omega| \\
& \leqslant\|\nabla u\|_{\Phi_{1}}^{\mathfrak{L}_{1}}+\|\nabla u\|_{\Phi_{1}}^{m_{1}}+\|\nabla v\|_{\Phi_{2}}^{\mathrm{m}_{2}}+\|\nabla v\|_{\Phi_{2}}^{m_{2}}-M\|u\|_{\mathrm{L}^{m_{1}}(\Omega)}^{m_{1}}-M\|v\|_{\mathrm{L}^{m_{2}}(\Omega)}^{m_{2}}+\mathrm{C}_{M}|\Omega| \\
& \leqslant\|\nabla \mathfrak{u}\|_{\Phi_{1}}^{\mathfrak{l}_{1}}+\|\nabla \mathfrak{u}\|_{\Phi_{1}}^{m_{1}}+\|\nabla v\|_{\Phi_{2}}^{\mathrm{l}_{2}}+\|\nabla v\|_{\Phi_{2}}^{\mathrm{m}_{2}}-\mathrm{Md}_{1}^{m_{1}}\|\nabla \mathfrak{u}\|_{\Phi_{1}}^{\mathrm{m}_{1}}-\mathrm{Md}_{3}^{m_{2}}\|\nabla v\|_{\Phi_{2}}^{m_{2}}+\mathrm{C}_{M}|\Omega| \\
& =\|\nabla u\|_{\Phi_{1}}^{l_{1}}+\|\nabla v\|_{\Phi_{2}}^{l_{2}}-\|\nabla u\|_{\Phi_{1}}^{m_{1}}\left(M_{1}^{m_{1}}-1\right)-\|\nabla v\|_{\Phi_{2}}^{m_{2}}\left(M_{3}^{m_{2}}-1\right)+C_{M}|\Omega| .
\end{aligned}
$$

Note that $l_{i} \leqslant m_{i}(i=1,2)$. Then the above inequality implies that

$$
\lim _{r \rightarrow \infty} \sup _{(u, v) \in \partial \mathrm{B}_{\mathrm{r}} \cap \widetilde{W}} I(u, v)=-\infty .
$$

Thus, there exists an $R=R(\widetilde{W})$ such that $I \leqslant 0$ on $\widetilde{W} \backslash B_{R(\widetilde{W})}$.

Proof of Theorem 4.1. Let $\mathrm{E}=\mathrm{W}, \mathrm{V}=\mathrm{Y}_{2 \mathrm{k}}$, and $\mathrm{X}=\mathrm{Z}_{2 \mathrm{k}}$. Obviously, $\mathrm{I}(0)=0$ and $\left(\mathrm{F}_{6}\right)$ implies I is even. By Lemmas 3.9, 4.5 and 4.6 , all conditions of Lemma 4.2 hold. Then system (1.1) possesses infinitely many weak solutions $\left\{\left(u_{k}, v_{k}\right)\right\}$ which are critical points of I such that $I\left(u_{k}, v_{k}\right) \rightarrow+\infty$, as $k \rightarrow \infty$.

## 5. Comparing with Theorem 1.1

In order to compare our results with Theorem 1.1, in this section, we present the results for equation (1.2), which correspond to Theorem 3.1 and Theorem 4.1.

Theorem 5.1. Assume that conditions $\left(\phi_{1}\right)^{\prime}-\left(\phi_{3}\right)^{\prime},\left(f_{0}\right)$ in Theorem 1.1 and the following conditions hold:
$\left(f_{1}\right)$ there exist a continuous function $\psi:[0,+\infty) \rightarrow \mathbb{R}$, which satisfies that $\Psi:=\int_{0}^{|t|} \psi(s) d s, t \in \mathbb{R}$ is an N -function increasing essentially more slowly than $\Phi_{*}$ near infinity, moreover,

$$
m<l_{\Psi}:=\inf _{t>0} \frac{t \psi(t)}{\Psi(t)} \leqslant \sup _{t>0} \frac{t \psi(t)}{\Psi(t)}=: m_{\Psi}<+\infty
$$

such that

$$
|f(x, t)| \leqslant C(1+\psi(|t|))
$$

for all $(x, t) \in \Omega \times \mathbb{R}$, where constant $C>0$;
$\left(f_{2}\right)$

$$
\limsup _{t \rightarrow 0} \frac{|F(x, t)|}{\Phi(t)}=\lambda<\lambda_{1}, \quad \text { uniformly in } x \in \Omega
$$

where and in the sequel $F(x, t)=\int_{0}^{t} f(x, s) d s, t \in \mathbb{R}$ and $\lambda_{1}>0$ satisfies the Poincaré inequality given by

$$
\lambda_{1} \int_{\Omega} \Phi(u) \mathrm{d} x \leqslant \int_{\Omega} \Phi(|\nabla(u)|) \mathrm{d} x, \quad \forall u \in \mathrm{~W}_{0}^{1, \Phi}(\Omega)
$$

$\left(f_{3}\right)$

$$
\lim _{t \rightarrow \infty} \frac{F(x, t)}{\Phi(t)}=+\infty \text { uniformly in } x \in \Omega
$$

$\left(\mathrm{f}_{4}\right)$ there exists a continuous function $\gamma:[0, \infty) \rightarrow \mathbb{R}$ and it satisfies that $\Gamma(\mathrm{t}):=\int_{0}^{|\mathrm{t}|} \gamma(\mathrm{s}) \mathrm{ds}, \mathrm{t} \in \mathbb{R}$ is an N -function with

$$
1<l_{\Gamma}:=\inf _{t>0} \frac{\mathrm{t} \gamma(\mathrm{t})}{\Gamma(\mathrm{t})} \leqslant \sup _{\mathrm{t}>0} \frac{\mathrm{t} \gamma(\mathrm{t})}{\Gamma(\mathrm{t})}=: \mathrm{m}_{\Gamma}<+\infty
$$

and function $\mathrm{H}(\mathrm{t}):=|\mathrm{t}|^{\frac{l_{\Gamma}}{\Gamma^{-1}}}, \mathrm{t} \in \mathbb{R}$ increases essentially more slowly than $\Phi_{*}$ near infinity such that

$$
\Gamma\left(\frac{F(x, t)}{|t|^{l}}\right) \leqslant C \bar{F}(x, t), \quad x \in \Omega, \quad|t| \geqslant R
$$

where constants $\mathrm{C}, \mathrm{R}>0$ and

$$
\overline{\mathrm{F}}(\mathrm{x}, \mathrm{t}):=\mathrm{tf}(\mathrm{x}, \mathrm{t})-\mathrm{mF}(\mathrm{x}, \mathrm{t}), \quad \forall(\mathrm{x}, \mathrm{t}) \in \Omega \times \mathbb{R}
$$

Then (1.2) possesses a nontrivial weak solution.
Theorem 5.2. Assume that $\left(\phi_{1}\right)^{\prime}-\left(\phi_{3}\right)^{\prime},\left(f_{0}\right),\left(f_{1}\right),\left(f_{4}\right)$ and the following conditions hold:
( $f_{5}$ )

$$
\lim _{t \rightarrow \infty} \frac{F(x, t)}{|t|^{m}}=+\infty \text { uniformly in } x \in \Omega
$$

( $f_{6}$ ) $F(x,-t)=F(x, t)$, for all $(x, t) \in \Omega \times \mathbb{R}$.
Then (1.2) possesses infinitely many weak solutions $\left\{\mathfrak{u}_{\mathrm{k}}\right\}$ such that

$$
\mathrm{J}\left(\mathfrak{u}_{\mathrm{k}}\right):=\int_{\Omega} \Phi\left(\left|\nabla \mathfrak{u}_{\mathrm{k}}\right|\right) \mathrm{d} x-\int_{\Omega} \mathrm{F}\left(\mathrm{x}, \mathfrak{u}_{\mathrm{k}}\right) \mathrm{d} x \rightarrow+\infty, \text { as } \mathrm{k} \rightarrow \infty .
$$

Remark 5.3. Theorem 5.1 improves the result (i) of Theorem 1.1 in Section 1. In fact, by (2) in Lemma 2.3 and (2) in Lemma 2.6, $\left(f_{1}\right)^{\prime}$ shows that for any given constant $c>0$, it holds that

$$
\lim _{\mathrm{t} \rightarrow \infty} \frac{\Psi(\mathrm{ct})}{\Phi_{*}(\mathrm{t})} \leqslant \frac{\Psi(\mathrm{c}) \max \left\{\mathrm{t}^{\mathrm{l} \psi}, \mathrm{t}^{\mathrm{m} \psi}\right\}}{\Phi_{*}(1) \min \left\{\mathrm{t}^{\mathrm{l}^{*}}, \mathrm{t}^{\mathrm{m}^{*}}\right\}}=0,
$$

which implies $\Psi$ increases essentially more slowly than $\Phi_{*}$. Moreover, comparing $\left(f_{1}\right)^{\prime}$ with $\left(f_{1}\right)$, we can see that condition $m<l^{*}$ is not necessary in ( $f_{1}$ ), see example below. It is obvious that $\left(f_{2}\right)^{\prime}$ is equivalent to $\left(f_{2}\right)$. Since $\left(f_{3}\right)^{\prime}$ is equivalent to $\left(f_{5}\right)$, which, together with (2) in Lemma 2.3, implies $\left(f_{3}\right)$. In $\left(f_{4}\right)^{\prime}$, condition $\frac{N}{l}<l_{\Gamma}$ shows $\frac{l_{\Gamma}}{l_{\Gamma}-1}<l^{*}$, which implies that function $H(t):=|t|^{\frac{l_{\Gamma}}{\Gamma_{\Gamma}-1}}, t \in \mathbb{R}$ increases essentially more slowly than $\Phi_{*}$.

Next, in order to offer an example that satisfies our conditions but do not satisfy the conditions in Theorem 1.1, we firstly need the following lemma.
Lemma 5.4. Under the assumptions $\left(\phi_{1}\right)^{\prime}-\left(\phi_{3}\right)^{\prime}$, let $\underline{\mathrm{m}}:=\liminf _{\mathrm{t} \rightarrow+\infty} \frac{\mathrm{t} \phi(\mathrm{t})}{\Phi(\mathrm{t})}$. Then, function $\gamma(\mathrm{t}):=|\mathrm{t}|^{\mathrm{p}}, \mathrm{t} \in \mathbb{R}$ increases essentially more slowly than $\Phi_{*}$ near infinity, where $1<p<\underline{m}^{*}:=\frac{\mathfrak{m} N}{N-\underline{m}}$.
Proof. Choose $a>0$ such that $a^{*}:=\frac{a N}{N-a}=p$. It follows from the fact $p<\underline{m}^{*}$ that $a<\underline{m}$ and $p<\left(\frac{a+m}{2}\right)^{*}:=\frac{\frac{a+m}{2} N}{N-\frac{a+m}{2}}$. Then, there exists a constant $K>0$ such that

$$
\frac{\mathrm{t} \phi(\mathrm{t})}{\Phi(\mathrm{t})} \geqslant \frac{1}{2}(\mathrm{a}+\underline{\mathrm{m}}), \quad \forall \mathrm{t} \geqslant \mathrm{~K},
$$

which implies that

$$
\Phi(t) \geqslant C_{1}|t|^{\frac{1}{2}(a+\underline{m})}, \quad \forall t \geqslant k
$$

for some $C_{1}>0$. Then, by the definition of $\Phi_{*}$, when $t \geqslant \Phi(K)$ we have

$$
\begin{aligned}
\Phi_{*}^{-1}(t) & =\Phi_{*}^{-1}(\Phi(K))+\int_{\Phi(K)}^{t} \frac{\Phi^{-1}(s)}{s^{N+1}} d s \\
& \leqslant \Phi_{*}^{-1}(\Phi(K))+\left(\frac{1}{C_{1}}\right)^{\frac{2}{a+m}} \int_{\Phi(K)}^{t} s^{\left(\frac{2}{a+\underline{m}}-\frac{N+1}{N}\right)} d s \\
& =\Phi_{*}^{-1}(\Phi(K))+\left(\frac{1}{C_{1}}\right)^{\frac{2}{a+\underline{m}}} \frac{N(a+\underline{m})}{2 N-(a+\underline{m})}\left(t^{\frac{2 N-(a+m)}{N(a+\underline{m})}}-\Phi(K)^{\frac{2 N-(a+m)}{N(a+\underline{m})}}\right) \\
& \leqslant C_{2} t^{\frac{2 N-(a+\underline{m})}{N(a+\underline{m})}}
\end{aligned}
$$

for some $C_{2}>0$, which implies that

$$
\Phi_{*}(t) \geqslant\left(\frac{1}{C_{2}}\right)^{\frac{N(a+m)}{2 N-(a+m)}} t^{\frac{N(a+m)}{2 N-(a+\underline{m})}}=\left(\frac{1}{C_{2}}\right)^{\left(\frac{a+m}{2}\right)^{*}} t^{\left(\frac{a+m}{2}\right)^{*}}, \quad \forall t \geqslant \Phi_{*}^{-1}(\Phi(K)) .
$$

Thus, for any constant $c>0$, we have

$$
\lim _{t \rightarrow+\infty} \frac{\Upsilon(c t)}{\Phi_{*}(t)} \leqslant \lim _{t \rightarrow+\infty} c^{p} C_{2}^{\left(\frac{a+m}{2}\right)^{*}} t^{\left[p-\left(\frac{a+m}{2}\right)^{*}\right]}=0,
$$

which implies that $\Upsilon(t)=|t|^{p}, t \in \mathbb{R}$ increases essentially more slowly than $\Phi_{*}$ near infinity.

Example 5.5. In (1.2), let $N=6, \phi(|t|) t=2 t+4 t^{3}, t>0$ and $f(x, t)=5|t|^{3} t, t \in \mathbb{R}$. Then some simple computations show that

$$
\Phi(t)=t^{2}+t^{4} \text { and } F(x, t)=\bar{F}(x, t)=|t|^{5}, \quad t \in \mathbb{R}
$$

and

$$
l=2, \quad \mathrm{~m}=\underline{\mathrm{m}}=4, \quad \mathrm{l}^{*}=3 \quad \text { and } \quad \mathrm{m}^{*}=\underline{m}^{*}=12
$$

Clearly, assumptions $\left(\phi_{1}\right)^{\prime}-\left(\phi_{3}\right)^{\prime},\left(f_{0}\right),\left(f_{2}\right)$ and $\left(f_{3}\right)$ hold. In $\left(f_{1}\right)$, choose function $\psi(t)=10 t^{9}, t \geqslant 0$ satisfying $\Psi(t)=|t|^{10}, t \in \mathbb{R}$ and $l_{\Psi}=m_{\Psi}=10$. Then, $\left(f_{1}\right)$ holds because Lemma 5.4 shows $\Psi$ increases essentially more slowly than $\Phi_{*}$ near infinity. However, the fact $l^{*}<m$ implies that $\left(f_{1}\right)^{\prime}$ does not hold. In $\left(f_{4}\right)$, choose function $\gamma(t)=\frac{4}{3} t^{\frac{1}{3}}, t \geqslant 0$ satisfying $\Gamma(t)=|t|^{\frac{4}{3}}, t \in \mathbb{R}$ and $l_{\Psi}=m_{\Psi}=\frac{4}{3}$. Then,

$$
\Gamma\left(\frac{F(x, t)}{|t|^{l}}\right)=|t|^{4} \leqslant|t|^{5}, \forall|t| \geqslant 1
$$

and Lemma 5.4 shows $H(t)=|t|^{\left.\right|^{\frac{l_{\Gamma}}{\Gamma}}}=t^{8}, t \in \mathbb{R}$ increases essentially more slowly than $\Phi_{*}$ near infinity.
Remark 5.6. In [12], based on Lieberman's interior regularity and boundary regularity results (see [25, 26]), maximum principle (see [29]) and other tools, Carvalho et al. investigated some important properties of solutions like (ii) in Theorem 1.1 under a stronger condition $\left(\phi_{4}\right)^{\prime}$. However, in the system case, those methods for the scalar case may not be useful any more. To extend the result (ii) in Theorem 1.1 to system (1.1), new methods maybe need to be established. We will try to do it in our future work.

## 6. Examples

In this section, we present some examples to illustrate our main results. For system (1.1), $\phi_{i}(i=1,2)$ can be chosen from the following cases which satisfy all $\left(\phi_{1}\right)-\left(\phi_{3}\right)$ type conditions:

1. Let $\phi(\mathrm{t})=\mathrm{t}^{\mathrm{p}-1}, \mathrm{t}>0,1<\mathrm{p}+1<\mathrm{N}$. In this case, simple computations show that $\mathrm{l}=\mathrm{m}=\mathrm{p}+1$.
2. Let $\phi(\mathrm{t})=\mathrm{t}^{\mathrm{p}-1}+\mathrm{t}^{\mathrm{q}-1}, \mathrm{t}>0,1<\mathrm{p}+1<\mathrm{q}+1<\mathrm{N}<\frac{(\mathrm{p}+1)(\mathrm{q}+1)}{\mathrm{q}-\mathrm{p}}$. In this case, simple computations show that $l=p+1, m=q+1$.
3. Let $\phi(t)=2 p\left(1+t^{2}\right)^{p-1}, t>0,1 \leqslant p<\frac{N}{2}$. In this case, simple computations show that $l=2, m=$ $2 p$.
4. Let $\phi(\mathrm{t})=\frac{\mathrm{t}^{\mathrm{q}-1}}{\log \left(1+\mathrm{t}^{\mathrm{p}}\right)}, \mathrm{t}>0,1<\mathrm{p}+1<\mathrm{q}+1<\mathrm{N}<\frac{(\mathrm{q}-\mathrm{p}+1)(\mathrm{q}+1)}{\mathrm{p}}$. In this case, simple computations show that $l=q-p+1, m=q+1$.
5. Let $\phi(t)=t^{q-1} \log \left(1+t^{p}\right), t>0, p, q>0$ and $p+q+1<N<\frac{(q+1)(p+q+1)}{p}$. In this case, simple computations show that $l=q+1, m=p+q+1$.

Based on this fact, it is easy to choose $\phi_{i}(i=1,2)$ and $N$ such that $\left(\phi_{1}\right)-\left(\phi_{3}\right)$ hold with $l_{i}^{*}>\mathfrak{m}_{i} \geqslant 4(i=$ 1,2 ), and $\max \left\{\frac{N}{l_{1}}, \frac{N}{l_{2}}\right\}<\min \left\{\frac{m_{1}}{m_{1}-l_{1}}, \frac{m_{2}}{m_{2}-l_{2}}\right\}$. Then,

$$
F(x, u, v)=|u|^{m_{1}} \log (1+|u|)+|v|^{m_{2}} \log (1+|v|)+|u|^{\frac{m_{1}+\varepsilon}{2}}|v|^{\frac{m_{2}+\varepsilon}{2}}
$$

satisfies $\left(F_{0}\right)-\left(F_{6}\right)$, where constant $\epsilon>0$ satisfying $\epsilon<\frac{2 l_{1}^{*} l_{2}^{*}-m_{1} l_{2}^{*}-m_{2} l_{1}^{*}}{l_{1}^{*}+l_{2}^{*}}$ and $\max \left\{\frac{N}{l_{1}}, \frac{N}{l_{2}}\right\}<\min \left\{\frac{m_{1}}{m_{1}-l_{1}+\epsilon}, \frac{m_{2}}{m_{2}-l_{2}+\epsilon}\right\}$. In fact,

$$
\mathrm{F}_{\mathfrak{u}}(x, u, v)=\mathfrak{m}_{1}|u|^{m_{1}-2} u \log (1+|u|)+\frac{|u|^{m_{1}-1} u}{1+|u|}+\frac{\mathfrak{m}_{1}+\epsilon}{2}|u|^{\frac{m_{1}+\varepsilon-4}{2}}|v|^{\frac{m_{2}+\varepsilon}{2}} \mathbf{u},
$$

$$
\mathrm{F}_{v}(\mathrm{x}, \mathrm{u}, v)=\mathrm{m}_{2}|v|^{\mathrm{m}_{2}-2} v \log (1+|v|)+\frac{|v|^{m_{2}-1} v}{1+|v|}+\frac{\mathrm{m}_{2}+\epsilon}{2}|u|^{\frac{m_{2}+\epsilon}{2}}|v|^{\frac{m_{2}+\epsilon-4}{2}} v,
$$

then

$$
\overline{\mathrm{F}}(x, u, v)=\frac{|u|^{m_{1}+1}}{\mathfrak{m}_{1}(1+|u|)}+\frac{|v|^{m_{2}+1}}{m_{2}(1+|v|)}+\frac{\left(m_{1}+m_{2}\right) \epsilon}{2 m_{1} m_{2}}|u|^{\frac{m_{1}+e}{2}}|v|^{\frac{m_{2}+e}{2}} \geqslant \frac{|u|^{m_{1}+1}}{m_{1}(1+|u|)}+\frac{|v|^{m_{2}+1}}{m_{2}(1+|v|)} .
$$

It is obvious that $F$ satisfies $\left(F_{0}\right)$ and $\left(F_{6}\right)$. Since

$$
\lim _{|(u, v)| \rightarrow 0} \frac{F(x, u, v)}{|u|^{m_{1}}+|v|^{m_{2}}}=0 \quad \text { and } \quad \lim _{|(u, v)| \rightarrow+\infty} \frac{F(x, u, v)}{|u|^{m_{1}}+|v|^{m_{2}}}=+\infty
$$

which, together with (2) in Lemma 2.3, shows that $\left(F_{2}\right),\left(F_{3}\right)$ and $\left(F_{5}\right)$ hold. Since $0<\epsilon<\frac{2 l_{1}^{*} l_{2}^{*}-\mathfrak{m}_{1} 1_{2}^{*}-m_{2} l_{1}^{*}}{l_{1}^{*}+l_{2}^{*}}$, by the Young's inequality, there exist $\psi_{i}(t)=t^{a_{i}-1}, t>0, m_{i}<a_{i}<l_{i}^{*},(i=1,2)$ such that ( $F_{1}$ ) holds. Next, we check $\left(F_{4}\right)$. Choose $\gamma(t)=k t^{k-1}, t>0$, where $\max \left\{\frac{N}{l_{1}}, \frac{N}{l_{2}}\right\}<k \leqslant \min \left\{\frac{m_{1}}{m_{1}-l_{1}+\epsilon}, \frac{m_{2}}{m_{2}-l_{2}+\epsilon}\right\}$. Then $\Gamma(t)=|t|^{k}, t \in \mathbb{R}$ and $l_{\Gamma}=m_{\Gamma}=k$. Since $\max \left\{\frac{N}{l_{1}}, \frac{N}{l_{2}}\right\}<k$, similar arguments as Remark 5.3 show that $H_{i}(t):=|t|^{\frac{\mathfrak{l}^{2} l_{r}}{\Gamma^{-1}}}, t \in \mathbb{R}(i=1,2)$ increase essentially more slowly than $\Phi_{i *}(i=1,2)$ near infinity, respectively. Moreover,

$$
\begin{aligned}
& \limsup _{|(u, v)| \rightarrow \infty}\left(\frac{|\mathcal{F}(x, u, v)|}{|u|^{l_{1}}+|v|^{l_{2}}}\right)^{k} \frac{1}{\bar{F}(x, u, v)} \\
& \leqslant \limsup _{|(u, v)| \rightarrow \infty} \frac{\left(|\mathfrak{u}|^{m_{1}} \log (1+|\mathfrak{u}|)+|v|^{m_{2}} \log (1+|v|)+|\mathfrak{u}|^{\frac{m_{1}+e}{2}}|v|^{\frac{m_{2}+e}{2}}\right)^{k}}{\left(|\mathfrak{u}|^{l_{1}}+|v|^{\mathbf{l}_{2}}\right)^{k}\left(\frac{|\mathfrak{u}|^{m_{1}+1}}{\boldsymbol{m}_{1}(1+|u|)}+\frac{|v|^{m_{2}+1}}{\boldsymbol{m}_{2}(1+|v|)}\right)} \\
& \leqslant C_{k} \limsup _{|(u, v)| \rightarrow \infty} \frac{|\mathfrak{u}|^{k m_{1}}(\log (1+|\mathfrak{u}|))^{k}+|v|^{k m_{2}}(\log (1+|v|))^{k}+|\mathfrak{u}|^{k\left(m_{1}+\varepsilon\right)}+|v|^{k\left(m_{2}+\varepsilon\right)}}{\frac{| |^{k l_{1}+m_{1}+1}}{m_{1}(1+|u|)}+\frac{|v|^{k} 2_{2}+m_{2}+1}{m_{2}(1+|v|)}} \\
& <+\infty,
\end{aligned}
$$

which shows that there exist constants $c_{3}, r>0$ such that (3.3) holds.

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