



## Topological coincidence principles



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### Abstract

In this paper a number of general coincidence principles are presented for set valued maps defined on subsets of completely regular topological spaces.

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### 1. Introduction

In this paper we present coincidence principles for multimaps. We present two approaches. The first approach is based on the new notion of  $\Phi$ -essential and  $d$ - $\Phi$ -essential maps (see [1, 3–5]) and the second approach is based on the notion of extendability (see [2]). The arguments presented are based on a Urysohn type lemma and homotopy type arguments.

### 2. Continuation principles

Let  $E$  be a completely regular topological space and  $U$  an open subset of  $E$ .

We consider classes  $\mathbf{A}$  and  $\mathbf{B}$  of maps.

**Definition 2.1.** We say  $F \in \mathbf{A}(\bar{U}, E)$  (respectively  $F \in \mathbf{B}(\bar{U}, E)$ ) if  $F : \bar{U} \rightarrow 2^E$  and  $F \in \mathbf{A}(\bar{U}, E)$  (respectively  $F \in \mathbf{B}(\bar{U}, E)$ ); here  $2^E$  denotes the family of nonempty subsets of  $E$ .

In this section we fix a  $\Phi \in \mathbf{B}(\bar{U}, E)$ .

**Definition 2.2.** We say  $F \in \mathbf{A}_{\partial U}(\bar{U}, E)$  if  $F \in \mathbf{A}(\bar{U}, E)$  with  $F(x) \cap \Phi(x) = \emptyset$  for  $x \in \partial U$ ; here  $\partial U$  denotes the boundary of  $U$  in  $E$ .

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**Definition 2.3.** Let  $E$  be a completely regular (respectively normal) topological space, and  $U$  an open subset of  $E$ . Let  $F, G \in A_{\partial U}(\bar{U}, E)$ . We say  $F \cong G$  in  $A_{\partial U}(\bar{U}, E)$  if there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^E$  with  $H(\cdot, \eta(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $H_t(x) \cap \Phi(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ ,  $H_1 = F$ ,  $H_0 = G$  and  $\{x \in \bar{U} : \Phi(x) \cap H(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed); here  $H_t(x) = H(x, t)$ .

**Definition 2.4.** Let  $F \in A_{\partial U}(\bar{U}, E)$ . We say  $F : \bar{U} \rightarrow 2^E$  is  $\Phi$ -essential in  $A_{\partial U}(\bar{U}, E)$  if for every map  $J \in A_{\partial U}(\bar{U}, E)$  with  $J|_{\partial U} = F|_{\partial U}$  and  $J \cong F$  in  $A_{\partial U}(\bar{U}, E)$  there exists  $x \in U$  with  $J(x) \cap \Phi(x) \neq \emptyset$ .

**Theorem 2.5.** Let  $E$  be a completely regular (respectively normal) topological space,  $U$  an open subset of  $E$ , and let  $F \in A_{\partial U}(\bar{U}, E)$  be  $\Phi$ -essential in  $A_{\partial U}(\bar{U}, E)$ . Suppose there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^E$  with  $H(\cdot, \eta(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $\Phi(x) \cap H_t(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in (0, 1]$ ,  $H_0 = F$ , and  $\{x \in \bar{U} : \Phi(x) \cap H(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed). In addition assume

$$\left\{ \begin{array}{l} \text{if } \mu : \bar{U} \rightarrow [0, 1] \text{ is any continuous map with } \mu(\partial U) = 0, \text{ then} \\ \{x \in \bar{U} : \emptyset \neq \Phi(x) \cap H(x, t\mu(x)) \text{ for some } t \in [0, 1]\} \text{ is closed.} \end{array} \right. \tag{2.1}$$

Then there exists  $x \in U$  with  $\Phi(x) \cap H_1(x) \neq \emptyset$ ; here  $H_t(x) = H(x, t)$ .

*Proof.* Let

$$D = \{x \in \bar{U} : \Phi(x) \cap H(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}.$$

Notice  $D \neq \emptyset$  since  $F$  is  $\Phi$ -essential in  $A_{\partial U}(\bar{U}, E)$  (note from (2.1) that  $F \cong F$  in  $A_{\partial U}(\bar{U}, E)$ ). Also  $D$  is compact (respectively closed) if  $E$  is a completely regular (respectively normal) topological space. Note  $D \cap \partial U = \emptyset$  (note  $H_0 = F$  so for  $t = 0$  we have  $\Phi(x) \cap H_0(x) = \emptyset$  for  $x \in \partial U$  since  $F \in A_{\partial U}(\bar{U}, E)$ ). Thus there exists a continuous map  $\mu : \bar{U} \rightarrow [0, 1]$  with  $\mu(\partial U) = 0$  and  $\mu(D) = 1$ . Define  $J : \bar{U} \rightarrow 2^E$  by  $J(x) = H(x, \mu(x))$ . Note  $J \in A_{\partial U}(\bar{U}, E)$  with  $J|_{\partial U} = F|_{\partial U}$  (note if  $x \in \partial U$  then  $J(x) = H_0(x) = F(x)$  and  $J(x) \cap \Phi(x) = F(x) \cap \Phi(x) = \emptyset$ ). We now claim

$$J \cong F \text{ in } A_{\partial U}(\bar{U}, E). \tag{2.2}$$

If the claim is true then since  $F$  is  $\Phi$ -essential in  $A_{\partial U}(\bar{U}, E)$  then there exists a  $x \in U$  with  $J(x) \cap \Phi(x) \neq \emptyset$  (i.e.,  $H_{\mu(x)}(x) \cap \Phi(x) \neq \emptyset$ ), and thus  $x \in D$  so  $\mu(x) = 1$  and as a result  $H_1(x) \cap \Phi(x) \neq \emptyset$ .

It remains to show (2.2). Let  $Q : \bar{U} \times [0, 1] \rightarrow 2^E$  be given by  $Q(x, t) = H(x, t\mu(x))$ . Note  $Q(\cdot, \eta(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$  and (see (2.1) and Definition 2.3)

$$\{x \in \bar{U} : \emptyset \neq \Phi(x) \cap Q(x, t) = \Phi(x) \cap H(x, t\mu(x)) \text{ for some } t \in [0, 1]\}$$

is compact (respectively closed). Note  $Q_0 = F$  and  $Q_1 = J$ . Finally if there exists a  $t \in [0, 1]$  and  $x \in \partial U$  with  $\Phi(x) \cap Q_t(x) \neq \emptyset$  then  $\Phi(x) \cap H_{t\mu(x)}(x) \neq \emptyset$  so  $x \in D$ , and so  $\mu(x) = 1$ , i.e.,  $\Phi(x) \cap H_t(x) \neq \emptyset$ , a contradiction. Thus (2.2) holds.  $\square$

*Remark 2.6.* Suppose we change Definition 2.4 as follows. Let  $F \in A_{\partial U}(\bar{U}, E)$ . We say  $F : \bar{U} \rightarrow 2^E$  is  $\Phi$ -essential in  $A_{\partial U}(\bar{U}, E)$  if for every map  $J \in A_{\partial U}(\bar{U}, E)$  with  $J|_{\partial U} = F|_{\partial U}$  there exists  $x \in U$  with  $J(x) \cap \Phi(x) \neq \emptyset$ . The argument above (note (2.2) is not needed) yields the following result. Let  $E$  be a completely regular (respectively normal) topological space,  $U$  an open subset of  $E$  and let  $F \in A_{\partial U}(\bar{U}, E)$  be  $\Phi$ -essential in  $A_{\partial U}(\bar{U}, E)$ . Suppose there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^E$  with  $H(\cdot, \eta(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $\Phi(x) \cap H_t(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in (0, 1]$ ,  $H_0 = F$  and  $\{x \in \bar{U} : \Phi(x) \cap H(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed). Then there exists  $x \in U$  with  $\Phi(x) \cap H_1(x) \neq \emptyset$ ; here  $H_t(x) = H(x, t)$ .

Again we consider the map  $F : \bar{U} \rightarrow 2^E$ . In our (quite abstract) result we will assume that we have a homotopy extension type property (i.e., a  $H : E \times [0, 1] \rightarrow 2^E$  with  $H_1|_{\bar{U}} = F$ ).

**Definition 2.7.** We say  $F \in \mathbf{A}(E, E)$  if  $F : E \rightarrow 2^E$  and  $F \in \mathbf{A}(E, E)$ .

**Definition 2.8.** Let  $E$  be a completely regular (respectively normal) topological space. If  $F, G \in \mathbf{A}(E, E)$ , then we say  $F \cong G$  in  $\mathbf{A}(E, E)$  if there exists a map  $\Lambda : E \times [0, 1] \rightarrow 2^E$  with  $\Lambda(\cdot, \eta(\cdot)) \in \mathbf{A}(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$ ,  $\Lambda_1 = G$ ,  $\Lambda_0 = F$  (here  $\Lambda_t(x) = \Lambda(x, t)$ ) and  $\{x \in E : \Phi(x) \cap \Lambda(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed).

We now fix a  $\Phi \in \mathbf{B}(E, E)$ .

**Theorem 2.9.** Let  $E$  be a completely regular (respectively normal) topological space and  $U$  an open subset of  $E$ . Suppose there exists a map  $H : E \times [0, 1] \rightarrow 2^E$  with  $H(\cdot, \eta(\cdot)) \in \mathbf{A}(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$  and with  $\Phi(x) \cap H(x, 0) = \emptyset$  for  $x \in E \setminus U$ , and  $\Phi(x) \cap H_t(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ , and  $\{x \in E : \Phi(x) \cap H(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed). In addition assume the following hold:

$$\text{for any } J \in \mathbf{A}(E, E) \text{ with } J \cong H_0 \text{ in } \mathbf{A}(E, E) \text{ there exists } x \in E \text{ with } \Phi(x) \cap J(x) \neq \emptyset, \tag{2.3}$$

$$\{x \in E \setminus U : H_t(x) \cap \Phi(x) \neq \emptyset \text{ for some } t \in [0, 1]\} \text{ is closed,} \tag{2.4}$$

and

$$\left\{ \begin{array}{l} \text{if } \mu : E \rightarrow [0, 1] \text{ is any continuous map with } \mu(\bar{U}) = 1, \text{ then} \\ \{x \in E : \emptyset \neq \Phi(x) \cap H(x, t\mu(x)) \text{ for some } t \in [0, 1]\} \text{ is closed.} \end{array} \right. \tag{2.5}$$

Then there exists  $x \in U$  with  $\Phi(x) \cap H_1(x) \neq \emptyset$ ; here  $H_t(x) = H(x, t)$ .

*Proof.* Let

$$D = \{x \in E \setminus U : \Phi(x) \cap H_t(x) \neq \emptyset \text{ for some } t \in [0, 1]\}.$$

We consider two cases, as  $D \neq \emptyset$  and  $D = \emptyset$ .

*Case (i).*  $D = \emptyset$ .

Then for every  $t \in [0, 1]$  we have  $\Phi(x) \cap H_t(x) = \emptyset$  for  $x \in E \setminus U$ . Also from  $H_1 \cong H_0$  in  $\mathbf{A}(E, E)$  and (2.3) we know there exists  $y \in E$  with  $\Phi(y) \cap H_1(y) \neq \emptyset$ . Since  $\Phi(x) \cap H_1(x) = \emptyset$  for  $x \in E \setminus U$  we deduce that  $y \in U$ , and we are finished.

*Case (ii).*  $D \neq \emptyset$ .

Now (note  $H_1 \cong H_0$  in  $\mathbf{A}(E, E)$  and (2.4))  $D$  is compact (respectively closed) and  $D \cap \bar{U} \neq \emptyset$  (since  $\Phi(x) \cap H_t(x) = \emptyset$  for  $x \in \partial U$  and  $t \in [0, 1]$ ). Then there exists a continuous map  $\mu : E \rightarrow [0, 1]$  with  $\mu(D) = 0$  and  $\mu(\bar{U}) = 1$ . Define a map  $R : E \rightarrow 2^E$  by

$$R(x) = H(x, \mu(x)).$$

Now  $R \in \mathbf{A}(E, E)$ . In fact  $R \cong H_0$  in  $\mathbf{A}(E, E)$ . To see this let  $\Omega : E \times [0, 1] \rightarrow 2^E$  be given by

$$\Omega(x, t) = H(x, t\mu(x)).$$

Note  $\Omega(\cdot, \eta(\cdot)) \in \mathbf{A}(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$ , and (note (2.5) and  $H_1 \cong H_0$  in  $\mathbf{A}(E, E)$ ),

$$\{x \in E : \Phi(x) \cap \Omega(x, t) = \Phi(x) \cap H(x, t\mu(x)) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact (respectively closed). Also  $\Omega_1 = R$  and  $\Omega_0 = H_0$ .

Now (2.3) guarantees that there exists  $x \in E$  with  $\Phi(x) \cap R(x) = \Phi(x) \cap H_{\mu(x)}(x) \neq \emptyset$ . If  $x \in E \setminus U$  then since  $x \in D$  we have  $\emptyset \neq \Phi(x) \cap H(x, \mu(x)) = \Phi(x) \cap H(x, 0)$ , a contradiction. Thus  $x \in U$  and so  $\emptyset \neq \Phi(x) \cap H(x, \mu(x)) = \Phi(x) \cap H(x, 1)$ .  $\square$

*Remark 2.10.* In Definition 2.8 and in the statement of Theorem 2.9 we could replace, any continuous map  $\eta : E \rightarrow [0, 1]$ , with any continuous map  $\eta : E \rightarrow [0, 1]$  with  $\eta(\bar{U}) = 1$ .

We now show that the ideas in this section can be applied to other natural situations. Let  $E$  be a Hausdorff topological vector space (so automatically a completely regular space),  $Y$  a topological vector space, and  $U$  an open subset of  $E$ . Also let  $L : \text{dom}(L) \subseteq E \rightarrow Y$  be a linear single valued map; here  $\text{dom}(L)$  is a vector subspace of  $E$ . Finally  $T : E \rightarrow Y$  will be a linear single valued map with  $L + T : \text{dom}(L) \rightarrow Y$  a bijection; for convenience we say  $T \in H_L(E, Y)$ .

**Definition 2.11.** We say  $F \in A(\bar{U}, Y; L, T)$  (respectively  $F \in B(\bar{U}, Y; L, T)$ ) if  $F : \bar{U} \rightarrow 2^Y$  and  $(L + T)^{-1}(F + T) \in A(\bar{U}, E)$  (respectively  $(L + T)^{-1}(F + T) \in B(\bar{U}, E)$ ).

We now fix a  $\Phi \in B(\bar{U}, Y; L, T)$ .

**Definition 2.12.** We say  $F \in A_{\partial U}(\bar{U}, Y; L, T)$  if  $F \in A(\bar{U}, Y; L, T)$  with  $(L + T)^{-1}(F + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for  $x \in \partial U$ .

**Definition 2.13.** Let  $F, G \in A_{\partial U}(\bar{U}, Y; L, T)$ . We say  $F \cong G$  in  $A_{\partial U}(\bar{U}, Y; L, T)$  if there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ ,  $H_1 = F$ ,  $H_0 = G$  and

$$\{x \in \bar{U} : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact; here  $H_t(x) = H(x, t)$ .

**Definition 2.14.** Let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$ . We say  $F$  is  $L$ - $\Phi$ -essential in  $A_{\partial U}(\bar{U}, Y; L, T)$  if for every map  $J \in A_{\partial U}(\bar{U}, Y; L, T)$  with  $J|_{\partial U} = F|_{\partial U}$  and  $J \cong F$  in  $A_{\partial U}(\bar{U}, Y; L, T)$  there exists  $x \in U$  with  $(L + T)^{-1}(J + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) \neq \emptyset$ .

**Theorem 2.15.** Let  $E$  be a topological vector space (so automatically completely regular),  $Y$  a topological vector space,  $U$  an open subset of  $E$ ,  $L : \text{dom}(L) \subseteq E \rightarrow Y$  a linear single valued map, and  $T \in H_L(E, Y)$ . Let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$  be  $L$ - $\Phi$ -essential in  $A_{\partial U}(\bar{U}, Y; L, T)$ . Suppose there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in (0, 1]$ ,  $H_0 = F$  (here  $H_t(x) = H(x, t)$ ) and  $\{x \in \bar{U} : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact. In addition assume

$$\left\{ \begin{array}{l} \text{if } \mu : \bar{U} \rightarrow [0, 1] \text{ is any continuous map with } \mu(\partial U) = 0, \text{ then} \\ \{x \in \bar{U} : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_{t\mu(x)} + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\} \text{ is closed.} \end{array} \right.$$

Then there exists  $x \in U$  with  $(L + T)^{-1}(H_1 + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) \neq \emptyset$ .

*Proof.* Let

$$D = \{x \in \bar{U} : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}.$$

Note  $D \neq \emptyset$  (note  $F$  is  $L$ - $\Phi$ -essential in  $A_{\partial U}(\bar{U}, Y; L, T)$ ) and  $D$  is compact,  $D \cap \partial U = \emptyset$  so there exists a continuous map  $\mu : \bar{U} \rightarrow [0, 1]$  with  $\mu(\partial U) = 0$  and  $\mu(D) = 1$ . Define  $J : \bar{U} \rightarrow 2^Y$  by  $J(x) = H(x, \mu(x))$ . Note  $J \in A_{\partial U}(\bar{U}, Y; L, T)$  and  $J|_{\partial U} = F|_{\partial U}$ . Also note  $J \cong F$  in  $A_{\partial U}(\bar{U}, Y; L, T)$  (to see this let  $Q : \bar{U} \times [0, 1] \rightarrow 2^Y$  be given by  $Q(x, t) = H(x, t\mu(x))$ ). Now since  $F$  is  $L$ - $\Phi$ -essential in  $A_{\partial U}(\bar{U}, Y; L, T)$  there exists  $x \in U$  with  $(L + T)^{-1}(J + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) \neq \emptyset$  (i.e.,  $(L + T)^{-1}(H_{\mu(x)} + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) \neq \emptyset$ ), and thus  $x \in D$  so  $\mu(x) = 1$  and we are finished.  $\square$

**Remark 2.16.** Suppose we change Definition 2.14 as follows. Let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$ . We say  $F$  is  $L$ - $\Phi$ -essential in  $A_{\partial U}(\bar{U}, Y; L, T)$  if for every map  $J \in A_{\partial U}(\bar{U}, Y; L, T)$  with  $J|_{\partial U} = F|_{\partial U}$  there exists  $x \in U$  with  $(L + T)^{-1}(J + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) \neq \emptyset$ . The argument above yields the following result. Let  $E$  be a topological vector space,  $Y$  a topological vector space,  $U$  an open subset of  $E$ ,  $L : \text{dom}(L) \subseteq E \rightarrow Y$  a linear single valued map, and  $T \in H_L(E, Y)$ . Let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$  be  $L$ - $\Phi$ -essential in  $A_{\partial U}(\bar{U}, Y; L, T)$ . Suppose there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T(\cdot)) \in A(\bar{U}, E)$  for any continuous

function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in (0, 1]$ ,  $H_0 = F$  (here  $H_t(x) = H(x, t)$ ) and  $\{x \in \bar{U} : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset$  for some  $t \in [0, 1]\}$  is compact. Then there exists  $x \in U$  with  $(L + T)^{-1}(H_1 + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) \neq \emptyset$ .

*Remark 2.17.* If  $E$  is a normal topological vector space then the assumption that  $D$  (in the proof of Theorem 2.15) is compact, can be replaced by  $D$  is closed, in the statement (and proof) of Theorem 2.15 and also the assumption that

$$\{x \in \bar{U} : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact, can be replaced by

$$\{x \in \bar{U} : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is closed, in Definition 2.13.

**Definition 2.18.** Let  $F : E \rightarrow 2^Y$ . We say  $F \in A(E, Y; L, T)$  if  $(L + T)^{-1}(F + T) \in A(E, E)$ .

**Definition 2.19.** If  $F, G \in A(E, Y; L, T)$  then we say  $F \cong G$  in  $A(E, Y; L, T)$  if there exists a map  $\Lambda : E \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(\Lambda(\cdot, \eta(\cdot)) + T) \in A(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$ ,  $\Lambda_1 = F$ ,  $\Lambda_0 = G$  (here  $\Lambda_t(x) = \Lambda(x, t)$ ) and

$$\{x \in E : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(\Lambda_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact.

We now fix a  $\Phi \in B(E, Y; L, T)$ .

**Theorem 2.20.** Let  $E$  be a completely regular topological vector space,  $Y$  a topological vector space,  $U$  an open subset of  $E$ ,  $L : \text{dom}(L) \subseteq E \rightarrow Y$  a linear single valued map, and  $T \in H_L(E, Y)$ . Suppose there exists a map  $H : E \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T) \in A(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$ ,  $(L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_0 + T)(x) = \emptyset$  for  $x \in E \setminus U$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ , and

$$\{x \in E : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact. In addition assume the following conditions holds:

$$\left\{ \begin{array}{l} \text{for any } J \in A(E, Y; L, T) \text{ with } J \cong H_0 \text{ in } A(E, Y; L, T) \text{ there exists } x \in E \text{ with} \\ (L + T)^{-1}(J + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) \neq \emptyset, \end{array} \right. \tag{2.6}$$

$$\{x \in E \setminus U : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\} \text{ is closed,} \tag{2.7}$$

and

$$\left\{ \begin{array}{l} \text{if } \mu : E \rightarrow [0, 1] \text{ is any continuous map with } \mu(\bar{U}) = 1, \text{ then} \\ \{x \in E : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_{t\mu(x)} + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\} \text{ is closed.} \end{array} \right.$$

Then there exists  $x \in U$  with  $(L + T)^{-1}(H_1 + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) \neq \emptyset$ ; here  $H_t(x) = H(x, t)$ .

*Proof.* Let

$$D = \{x \in E \setminus U : (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) \neq \emptyset \text{ for some } t \in [0, 1]\}.$$

We consider two cases, as  $D \neq \emptyset$  and  $D = \emptyset$ .

Case (i).  $D = \emptyset$ .

Then for every  $t \in [0, 1]$  we have  $(L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_t + T)(x) = \emptyset$  for  $x \in E \setminus U$ . Also from  $H_1 \cong H_0$  in  $A(E, Y; L, T)$  and (2.6) we see there exists  $y \in E$  with  $(L + T)^{-1}(\Phi + T)(y) \cap (L + T)^{-1}(H_1 + T)(y) \neq \emptyset$ . Since  $D = \emptyset$  we see that  $y \in U$ , and we are finished.

Case (ii).  $D \neq \emptyset$ .

Now (note  $H_1 \cong H_0$  in  $A(E, Y; L, T)$  and (2.7))  $D$  is compact, and  $D \cap \bar{U} \neq \emptyset$  (since  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for  $x \in \partial U$  and  $t \in [0, 1]$ ). Then there exists a continuous map  $\mu : E \rightarrow [0, 1]$  with  $\mu(D) = 0$  and  $\mu(\bar{U}) = 1$ . Define a map  $R : E \rightarrow 2^Y$  by  $R(x) = H(x, \mu(x))$ . Note  $R \in A(E, Y; L, T)$ . Also note  $R \cong H_0$  in  $A(E, Y; L, T)$  (to see this let  $\Omega : E \times [0, 1] \rightarrow 2^E$  be given by  $\Omega(x, t) = H(x, t\mu(x))$ ). Also  $\Omega_1 = R$  and  $\Omega_0 = H_0$ .

Now (2.6) guarantees that there exists  $x \in E$  with  $\emptyset \neq (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(R + T)(x) = (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_{\mu(x)} + T)(x)$ . If  $x \in E \setminus U$  then since  $x \in D$  we have  $\emptyset \neq (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_{\mu(x)} + T)(x) = (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_0 + T)(x)$ , a contradiction. Thus  $x \in U$  and so  $\emptyset \neq (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_{\mu(x)} + T)(x) = (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_1 + T)(x)$ .  $\square$

Remark 2.21. In Definition 2.19 and in the statement of Theorem 2.20 we could replace any continuous map  $\eta : E \rightarrow [0, 1]$  with any continuous map  $\eta : E \rightarrow [0, 1]$  with  $\eta(\bar{U}) = 1$ .

Remark 2.22. There is an analogue of Remark 2.17 (for normal topological vector spaces) in the statement of Theorem 2.20 and in Definition 2.19.

### 3. Generalized continuation principles

Let  $E$  be a completely regular topological space and  $U$  an open subset of  $E$ . Again we consider classes **A** and **B** of maps.

In this section we fix a  $\Phi \in B(\bar{U}, E)$ .

For any map  $F \in A(\bar{U}, E)$  let  $F^* = I \times F : \bar{U} \rightarrow 2^{\bar{U} \times E}$ , with  $I : \bar{U} \rightarrow \bar{U}$  given by  $I(x) = x$ , and let

$$d : \left\{ (F^*)^{-1}(B) \right\} \cup \{\emptyset\} \rightarrow \Omega \tag{3.1}$$

be any map with values in the nonempty set  $\Omega$ ; here  $B = \{(x, \Phi(x)) : x \in \bar{U}\}$ .

**Definition 3.1.** Let  $E$  be a completely regular (respectively normal) topological space, and  $U$  an open subset of  $E$ . Let  $F, G \in A_{\partial U}(\bar{U}, E)$ . We say  $F \cong G$  in  $A_{\partial U}(\bar{U}, E)$  if there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^E$  with  $H(\cdot, \eta(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $H_t(x) \cap \Phi(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ ,  $H_1 = F$ ,  $H_0 = G$  and  $\{x \in \bar{U} : (x, \Phi(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed); here  $H^*(x, t) = (x, H(x, t))$  and  $H_t(x) = H(x, t)$ .

**Definition 3.2.** Let  $F \in A_{\partial U}(\bar{U}, E)$  with  $F^* = I \times F$ . We say  $F^* : \bar{U} \rightarrow 2^{\bar{U} \times E}$  is  $d$ - $\Phi$ -essential if for every map  $J \in A_{\partial U}(\bar{U}, E)$  with  $J^* = I \times J$  and  $J|_{\partial U} = F|_{\partial U}$  and  $J \cong F$  in  $A_{\partial U}(\bar{U}, E)$  we have that  $d\left(\left(F^*\right)^{-1}(B)\right) = d\left(\left(J^*\right)^{-1}(B)\right) \neq d(\emptyset)$ .

Remark 3.3. If  $F^*$  is  $d$ - $\Phi$ -essential then

$$\emptyset \neq (F^*)^{-1}(B) = \{x \in \bar{U} : F^*(x) \cap B \neq \emptyset\} = \{x \in \bar{U} : (x, F(x)) \cap (x, \Phi(x)) \neq \emptyset\},$$

and this together with  $F(x) \cap \Phi(x) = \emptyset$  for  $x \in \partial U$  implies that there exists  $x \in U$  with  $(x, \Phi(x)) \cap F^*(x) \neq \emptyset$  (i.e.,  $\Phi(x) \cap F(x) \neq \emptyset$ ).

**Theorem 3.4.** Let  $E$  be a completely regular (respectively normal) topological space,  $U$  an open subset of  $E$ ,  $B = \{(x, \Phi(x)) : x \in \bar{U}\}$ ,  $d$  a map defined in (3.1) and let  $F \in A_{\partial U}(\bar{U}, E)$  and  $F^*$  be  $d$ - $\Phi$ -essential (here  $F^* = I \times F$ ). Suppose there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^E$  with  $H(\cdot, \eta(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $H_t(x) \cap \Phi(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in (0, 1]$ ,  $H_0 = F$  and

$\{x \in \bar{U} : (x, \Phi(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed); here  $H^*(x, t) = (x, H(x, t))$  and  $H_t(x) = H(x, t)$ . In addition assume

$$\begin{cases} \text{if } \mu : \bar{U} \rightarrow [0, 1] \text{ is any continuous map with } \mu(\partial U) = 0, \text{ then} \\ \{x \in \bar{U} : (x, \Phi(x)) \cap (x, H(x, t\mu(x))) \neq \emptyset \text{ for some } t \in [0, 1]\} \text{ is closed.} \end{cases}$$

Let  $H_1^* = I \times H_1$ . Then

$$d\left((H_1^*)^{-1}(B)\right) = d\left((F^*)^{-1}(B)\right) \neq d(\emptyset).$$

*Proof.* Let

$$D = \{x \in \bar{U} : (x, \Phi(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\},$$

where  $H^*(x, t) = (x, H(x, t))$ . Notice  $D \neq \emptyset$  since  $F^*$  is  $d$ - $\Phi$ -essential. Also  $D$  is compact (respectively closed) if  $E$  is a completely regular (respectively normal) topological space and  $D \cap \partial U = \emptyset$ . Thus there exists a continuous map  $\mu : \bar{U} \rightarrow [0, 1]$  with  $\mu(\partial U) = 0$  and  $\mu(D) = 1$ . Define  $R_\mu : \bar{U} \rightarrow 2^E$  by  $R_\mu(x) = H(x, \mu(x))$  and let  $R_\mu^* = I \times R_\mu$ . Note  $R_\mu \in A_{\partial U}(\bar{U}, E)$  with  $R_\mu|_{\partial U} = F|_{\partial U}$  (note if  $x \in \partial U$  then  $R_\mu(x) = H_0(x) = F(x)$  and  $R_\mu(x) \cap \Phi(x) = F(x) \cap \Phi(x) = \emptyset$ ).

Next we note since  $\mu(D) = 1$  that

$$(R_\mu^*)^{-1}(B) = \{x \in \bar{U} : (x, \Phi(x)) \cap (x, H(x, \mu(x))) \neq \emptyset\} = \{x \in \bar{U} : (x, \Phi(x)) \cap (x, H(x, 1)) \neq \emptyset\} = (H_1^*)^{-1}(B),$$

so

$$d\left((R_\mu^*)^{-1}(B)\right) = d\left((H_1^*)^{-1}(B)\right). \tag{3.2}$$

Also note  $R_\mu \cong F$  in  $A_{\partial U}(\bar{U}, E)$  (to see this let  $Q : \bar{U} \times [0, 1] \rightarrow 2^E$  be given by  $Q(x, t) = H(x, t\mu(x))$ ). As a result since  $F^*$  is  $d$ - $\Phi$ -essential we have  $d\left((R_\mu^*)^{-1}(B)\right) = d\left((F^*)^{-1}(B)\right) \neq d(\emptyset)$ . This together with (3.2) yields  $d\left((H_1^*)^{-1}(B)\right) = d\left((F^*)^{-1}(B)\right) \neq d(\emptyset)$ . □

*Remark 3.5.* Suppose we change Definition 3.2 as follows. Let  $F \in A_{\partial U}(\bar{U}, E)$  with  $F^* = I \times F$ . We say  $F^* : \bar{U} \rightarrow 2^{\bar{U} \times E}$  is  $d$ - $\Phi$ -essential if for every map  $J \in A_{\partial U}(\bar{U}, E)$  with  $J^* = I \times J$  and  $J|_{\partial U} = F|_{\partial U}$  we have that  $d\left((F^*)^{-1}(B)\right) = d\left((J^*)^{-1}(B)\right) \neq d(\emptyset)$ . The argument above yields the following result. Let  $E$  be a completely regular (respectively normal) topological space,  $U$  an open subset of  $E$ ,  $B = \{(x, \Phi(x)) : x \in \bar{U}\}$ ,  $d$  a map defined in (3.1) and let  $F \in A_{\partial U}(\bar{U}, E)$  and  $F^*$  be  $d$ - $\Phi$ -essential (here  $F^* = I \times F$ ). Suppose there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^E$  with  $H(\cdot, \eta(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $H_t(x) \cap \Phi(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in (0, 1)$ ,  $H_0 = F$  and  $\{x \in \bar{U} : (x, \Phi(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed); here  $H^*(x, t) = (x, H(x, t))$  and  $H_t(x) = H(x, t)$ . Then  $d\left((H_1^*)^{-1}(B)\right) = d\left((F^*)^{-1}(B)\right) \neq d(\emptyset)$ .

*Remark 3.6.* Suppose the following conditions holds (which is common in the literature on topological degree):

$$\begin{cases} \text{if } F, G \in A_{\partial U}(\bar{U}, E) \text{ with } F|_{\partial U} = G|_{\partial U} \text{ and } F \cong G \\ \text{in } A_{\partial U}(\bar{U}, E), \text{ then } d\left((F^*)^{-1}(B)\right) = d\left((G^*)^{-1}(B)\right). \end{cases} \tag{3.3}$$

Then Definition 3.2 reduces to the following. Let  $F \in A_{\partial U}(\bar{U}, E)$  with  $F^* = I \times F$ . We say  $F^* : \bar{U} \rightarrow 2^{\bar{U} \times E}$  is  $d$ - $\Phi$ -essential if  $d\left((F^*)^{-1}(B)\right) \neq d(\emptyset)$ .

Next in this paper we use the notion of extendability to establish new continuation theorems.

**Definition 3.7.** We say  $F \in A(E, E)$  if  $F : E \rightarrow 2^E$  and  $F \in \mathbf{A}(E, E)$ .

We now fix a  $\Phi \in B(E, E)$ .

For any map  $F \in A(E, E)$  let  $F^* = I \times F : E \rightarrow 2^{E \times E}$ , with  $I : E \rightarrow E$  given by  $I(x) = x$ , and let

$$d : \left\{ (F^*)^{-1}(B) \right\} \cup \{\emptyset\} \rightarrow \Omega \tag{3.4}$$

be any map with values in the nonempty set  $\Omega$ ; here  $B = \{(x, \Phi(x)) : x \in E\}$ . In our applications we will be interested in maps  $F : \bar{U} \rightarrow 2^E$  so  $F^* = I \times F : \bar{U} \rightarrow 2^{\bar{U} \times E}$  and in this case we consider

$$d : \left\{ (F^*)^{-1}(B_U) \right\} \cup \{\emptyset\} \rightarrow \Omega,$$

where  $B_U = \{(x, \Phi(x)) : x \in U\}$ .

**Definition 3.8.** If  $F, G \in A(E, E)$ , then we say  $F \cong G$  in  $A(E, E)$  if there exists a map  $\Lambda : E \times [0, 1] \rightarrow 2^E$  with  $\Lambda(\cdot, \eta(\cdot)) \in A(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$ ,  $\Lambda_1 = F$ ,  $\Lambda_0 = G$  (here  $\Lambda_t(x) = \Lambda(x, t)$ ) and  $\{x \in E : (x, \Phi(x)) \cap \Lambda^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$  is compact (respectively closed); here  $\Lambda^*(x, t) = (x, \Lambda(x, t))$ .

**Theorem 3.9.** Let  $E$  be a completely regular (respectively normal) topological space,  $U$  an open subset of  $E$  and  $d$  a map defined in (3.4). Suppose there exists a map  $H : E \times [0, 1] \rightarrow 2^E$  with  $H(\cdot, \eta(\cdot)) \in A(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$  and with  $\Phi(x) \cap H(x, 0) = \emptyset$  for  $x \in E \setminus U$ , and  $\Phi(x) \cap H_t(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ , and

$$\{x \in E : (x, \Phi(x)) \cap (x, H(x, t)) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact (respectively closed). In addition assume the following hold:

$$\left\{ \begin{array}{l} \text{for any } J \in A(E, E) \text{ with } J^* = I \times J \text{ and } J \cong H_0 \text{ in } A(E, E) \text{ we have that} \\ d \left( (J^*)^{-1}(B) \right) = d \left( (H_0^*)^{-1}(B) \right) \neq d(\emptyset), \\ \{x \in E \setminus U : (x, \Phi(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\} \text{ is closed,} \end{array} \right. \tag{3.5}$$

and

$$\left\{ \begin{array}{l} \text{if } \mu : E \rightarrow [0, 1] \text{ is any continuous map with } \mu(\bar{U}) = 1, \text{ then} \\ \{x \in E : \emptyset \neq (x, \Phi(x)) \cap (x, H(x, t\mu(x))) \text{ for some } t \in [0, 1]\} \text{ is closed;} \end{array} \right. \tag{3.6}$$

here  $H_0^* = I \times H_0$  and  $H^*(x, t) = (x, H(x, t))$ . Let  $H_1^* = I \times H_1$ . Then we have

$$d \left( (H_1^*)^{-1}(B_U) \right) = d \left( (H_0^*)^{-1}(B_U) \right) \neq d(\emptyset).$$

*Proof.* Let

$$D = \{x \in E \setminus U : (x, \Phi(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\},$$

where  $H^*(x, t) = (x, H(x, t))$ .

We consider two cases, as  $D \neq \emptyset$  and  $D = \emptyset$ .

Case (i).  $D = \emptyset$ .

Then for every  $t \in [0, 1]$  we have  $\Phi(x) \cap H_t(x) = \emptyset$  for  $x \in E \setminus U$ . Also from  $H_1 \cong H_0$  in  $A(E, E)$  and (3.5) we have

$$d \left( (H_1^*)^{-1}(B) \right) = d \left( (H_0^*)^{-1}(B) \right) \neq d(\emptyset). \tag{3.7}$$

Note  $(H_1^*)^{-1}(B) = \{x \in E : (x, \Phi(x)) \cap (x, H_1(x)) \neq \emptyset\}$ . Consider  $y \in E$  and  $(y, \Phi(y)) \cap H_1^*(y) \neq \emptyset$ . Then  $y \in E$  and  $\Phi(y) \cap H_1(y) \neq \emptyset$ . Now since  $D = \emptyset$  we have  $y \in U$  and  $\Phi(y) \cap H_1(y) \neq \emptyset$  i.e.,  $y \in U$  and  $(y, \Phi(y)) \cap H_1^*(y) \neq \emptyset$ . Consequently  $(H_1^*)^{-1}(B) \subseteq (H_1^*)^{-1}(B_U)$  and on the other hand it is immediate that  $(H_1^*)^{-1}(B_U) \subseteq (H_1^*)^{-1}(B)$ . Thus  $(H_1^*)^{-1}(B) = (H_1^*)^{-1}(B_U)$ . It is also immediate that  $(H_0^*)^{-1}(B) = (H_0^*)^{-1}(B_U)$ .

Thus (3.7) implies  $d \left( (H_1^*)^{-1}(B_U) \right) = d \left( (H_0^*)^{-1}(B_U) \right) \neq d(\emptyset)$ , and we are finished.



Case (ii).  $D \neq \emptyset$ .

Note  $D$  is compact (respectively closed) and also note  $D \cap \bar{U} \neq \emptyset$  (since  $\Phi(x) \cap H_t(x) = \emptyset$  for  $x \in \partial U$  and  $t \in [0, 1]$ ). Then there exists a continuous map  $\mu : E \rightarrow [0, 1]$  with  $\mu(D) = 0$  and  $\mu(\bar{U}) = 1$ . Define a map  $R : E \rightarrow 2^E$  by  $R(x) = H(x, \mu(x))$ . Note  $R \in A(E, E)$ . In fact  $R \cong H_0$  in  $A(E, E)$ . To see this let  $\Lambda : E \times [0, 1] \rightarrow 2^E$  be given by  $\Lambda(x, t) = H(x, t\mu(x))$ . Note  $\Lambda(\cdot, \eta(\cdot)) \in A(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$ , and (note (3.6) and  $H_1 \cong H_0$  in  $A(E, E)$ ),

$$\{x \in E : (x, \Phi(x)) \cap (x, H(x, t\mu(x))) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact (respectively closed). Also  $\Lambda_1 = R$  and  $\Lambda_0 = H_0$ .

Let  $R^* = I \times R$ . Now (3.5) guarantees that

$$d\left((R^*)^{-1}(B)\right) = d\left((H_0^*)^{-1}(B)\right) \neq d(\emptyset). \tag{3.8}$$

Note  $(R^*)^{-1}(B) = \{x \in E : (x, \Phi(x)) \cap (x, R(x)) \neq \emptyset\}$ . Consider  $x \in E$  and  $(x, \Phi(x)) \cap R^*(x) \neq \emptyset$ . Then  $x \in E$  and  $\emptyset \neq \Phi(x) \cap R(x) = \Phi(x) \cap H_{\mu(x)}(x)$ . If  $x \in E \setminus U$  then since  $x \in D$  we have  $\emptyset \neq \Phi(x) \cap H_{\mu(x)}(x) = \Phi(x) \cap H(x, 0)$ , which is a contradiction. Thus  $x \in U$  and  $\emptyset \neq \Phi(x) \cap R(x)$ . Consequently  $(R^*)^{-1}(B) \subseteq (R^*)^{-1}(B_U)$  and on the other hand it is immediate that  $(R^*)^{-1}(B_U) \subseteq (R^*)^{-1}(B)$ . Thus  $(R^*)^{-1}(B) = (R^*)^{-1}(B_U)$ . Also  $(H_0^*)^{-1}(B) = (H_0^*)^{-1}(B_U)$ . Thus (3.8) implies

$$d\left((R^*)^{-1}(B_U)\right) = d\left((H_0^*)^{-1}(B_U)\right) \neq d(\emptyset). \tag{3.9}$$

Finally notice (note  $\mu(\bar{U}) = 1$ ) that

$$\begin{aligned} (R^*)^{-1}(B_U) &= \{x \in U : (x, \Phi(x)) \cap (x, H(x, \mu(x))) \neq \emptyset\} \\ &= \{x \in U : (x, \Phi(x)) \cap (x, H(x, 1)) \neq \emptyset\} = (H_1^*)^{-1}(B_U), \end{aligned}$$

so from (3.9) we have  $d\left((H_1^*)^{-1}(B_U)\right) = d\left((H_0^*)^{-1}(B_U)\right) \neq d(\emptyset)$ . □

*Remark 3.10.* In Definition 3.8 and in the statement of Theorem 3.9 we could replace, any continuous map  $\eta : E \rightarrow [0, 1]$ , with, any continuous map  $\eta : E \rightarrow [0, 1]$  with  $\eta(\bar{U}) = 1$ .

Let  $E$  be a topological vector space,  $Y$  a topological vector space,  $U$  an open subset of  $E$ ,  $L : \text{dom}(L) \subseteq E \rightarrow Y$  a linear single valued map, and  $T \in H_L(E, Y)$ .

We now fix a  $\Phi \in B(\bar{U}, Y; L, T)$ .

For any map  $F \in A(\bar{U}, Y; L, T)$  let  $F^* = I \times (L + T)^{-1}(F + T) : \bar{U} \rightarrow 2^{\bar{U} \times E}$ , with  $I : \bar{U} \rightarrow \bar{U}$  given by  $I(x) = x$ , and let

$$d : \left\{ (F^*)^{-1}(B) \right\} \cup \{\emptyset\} \rightarrow \Omega \tag{3.10}$$

be any map with values in the nonempty set  $\Omega$ ; here  $B = \{(x, (L + T)^{-1}(\Phi + T)(x)) : x \in \bar{U}\}$ .

**Definition 3.11.** Let  $F, G \in A_{\partial U}(\bar{U}, Y; L, T)$ . We say  $F \cong G$  in  $A_{\partial U}(\bar{U}, Y; L, T)$  if there exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ ,  $H_1 = F$ ,  $H_0 = G$  and

$$\{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact; here  $H_t(x) = H(x, t)$  and  $H^*(x, \lambda) = (x, (L + T)^{-1}(H + T)(x, \lambda))$ .

**Definition 3.12.** Let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$  with  $F^* = I \times (L + T)^{-1}(F + T)$ . We say  $F^* : \bar{U} \rightarrow 2^{\bar{U} \times E}$  is  $d$ - $L$ - $\Phi$ -essential if for every map  $J \in A_{\partial U}(\bar{U}, Y; L, T)$  with  $J^* = I \times (L + T)^{-1}(J + T)$  and  $J|_{\partial U} = F|_{\partial U}$  and  $J \cong F$  in  $A_{\partial U}(\bar{U}, Y; L, T)$  we have that  $d\left((F^*)^{-1}(B)\right) = d\left((J^*)^{-1}(B)\right) \neq d(\emptyset)$ .

**Theorem 3.13.** Let  $E$  be a Hausdorff topological vector space,  $Y$  a topological vector space,  $U$  an open subset of  $E$ ,  $B = \{(x, (L + T)^{-1}(\Phi + T)(x)) : x \in \bar{U}\}$ ,  $L : \text{dom}(L) \subseteq E \rightarrow Y$  a linear single valued map,  $T \in H_L(E, Y)$ ,  $d$  a map defined in (3.10), and let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$  and  $F^*$  be  $d$ - $L$ - $\Phi$ -essential (here  $F^* = I \times (L + T)^{-1}(F + T)$ ). Suppose here exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in (0, 1]$ ,  $H_0 = F$ , and

$$\{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact; here  $H_t(x) = H(x, t)$  and  $H^*(x, \lambda) = (x, (L + T)^{-1}(H + T)(x, \lambda))$ . In addition assume

$$\begin{cases} \text{if } \mu : \bar{U} \rightarrow [0, 1] \text{ is any continuous map with } \mu(\partial U) = 0, \text{ then} \\ \{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap (x, (L + T)^{-1}(H_{t\mu(x)} + T)(x)) \neq \emptyset \text{ for some } t \in [0, 1]\} \text{ is closed.} \end{cases}$$

Let  $H_1^* = I \times (L + T)^{-1}(H_1 + T)$ . Then

$$d\left((H_1^*)^{-1}(B)\right) = d\left((F^*)^{-1}(B)\right) \neq d(\emptyset).$$

*Proof.* Let

$$D = \{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\},$$

where  $H^*(x, \lambda) = (x, (L + T)^{-1}(H + T)(x, \lambda))$ . Notice  $D \neq \emptyset$ ,  $D$  is compact, and  $D \cap \partial U = \emptyset$ . Thus there exists a continuous map  $\mu : \bar{U} \rightarrow [0, 1]$  with  $\mu(\partial U) = 0$  and  $\mu(D) = 1$ . Define  $R_\mu : \bar{U} \rightarrow 2^Y$  by  $R_\mu(x) = H(x, \mu(x)) = H_{\mu(x)}(x)$  and let  $R_\mu^* = I \times (L + T)^{-1}(R_\mu + T)$ . Note  $R_\mu \in A_{\partial U}(\bar{U}, Y; L, T)$  with  $R_\mu|_{\partial U} = F|_{\partial U}$  (note if  $x \in \partial U$  then  $R_\mu(x) = H_0(x) = F(x)$  and  $R_\mu(x) \cap \Phi(x) = F(x) \cap \Phi(x) = \emptyset$ ).

Next we note, since  $\mu(D) = 1$ , that

$$\begin{aligned} (R_\mu^*)^{-1}(B) &= \{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap (x, (L + T)^{-1}(H_{\mu(x)} + T)(x)) \neq \emptyset\} \\ &= \{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap (x, (L + T)^{-1}(H_1 + T)(x)) \neq \emptyset\} = (H_1^*)^{-1}(B) \end{aligned}$$

and so

$$d\left((R_\mu^*)^{-1}(B)\right) = d\left((H_1^*)^{-1}(B)\right). \tag{3.11}$$

Also note  $R_\mu \cong F$  in  $A_{\partial U}(\bar{U}, Y; L, T)$  (to see this let  $Q : \bar{U} \times [0, 1] \rightarrow 2^Y$  be given by  $Q(x, t) = H(x, t\mu(x))$ ). As a result since  $F^*$  is  $d$ - $L$ - $\Phi$ -essential we have  $d\left((R_\mu^*)^{-1}(B)\right) = d\left((F^*)^{-1}(B)\right) \neq d(\emptyset)$ . This together with (3.11) yields  $d\left((H_1^*)^{-1}(B)\right) = d\left((F^*)^{-1}(B)\right) \neq d(\emptyset)$ .  $\square$

*Remark 3.14.* Suppose we change Definition 3.12 as follows. Let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$  with  $F^* = I \times (L + T)^{-1}(F + T)$ . We say  $F^* : \bar{U} \rightarrow 2^{\bar{U} \times E}$  is  $d$ - $L$ - $\Phi$ -essential if for every map  $J \in A_{\partial U}(\bar{U}, Y; L, T)$  with  $J^* = I \times (L + T)^{-1}(J + T)$  and  $J|_{\partial U} = F|_{\partial U}$  we have that  $d\left((F^*)^{-1}(B)\right) = d\left((J^*)^{-1}(B)\right) \neq d(\emptyset)$ . The argument above yields the following result. Let  $E$  be a Hausdorff topological vector space,  $Y$  a topological vector space,  $U$  an open subset of  $E$ ,  $B = \{(x, (L + T)^{-1}(\Phi + T)(x)) : x \in \bar{U}\}$ ,  $L : \text{dom}(L) \subseteq E \rightarrow Y$  a linear single valued map,  $T \in H_L(E, Y)$ ,  $d$  a map defined in (3.10) and let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$  and  $F^*$  be  $d$ - $L$ - $\Phi$ -essential (here  $F^* = I \times (L + T)^{-1}(F + T)$ ). Suppose here exists a map  $H : \bar{U} \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T(\cdot)) \in A(\bar{U}, E)$  for any continuous function  $\eta : \bar{U} \rightarrow [0, 1]$  with  $\eta(\partial U) = 0$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ ,  $H_1 = F$ ,  $H_0 = G$  and

$$\{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact; here  $H_t(x) = H(x, t)$  and  $H^*(x, \lambda) = (x, (L + T)^{-1}(H + T)(x, \lambda))$ . Let  $H_1^* = I \times (L + T)^{-1}(H_1 + T)$ . Then  $d\left((H_1^*)^{-1}(B)\right) = d\left((F^*)^{-1}(B)\right) \neq d(\emptyset)$ .

*Remark 3.15.* Suppose the following condition holds:

$$\begin{cases} \text{if } F, G \in A_{\partial U}(\bar{U}, Y; L, T) \text{ with } F|_{\partial U} = G|_{\partial U} \text{ and } F \cong G \\ \text{in } A_{\partial U}(\bar{U}, Y; L, T) \text{ then } d\left((F^*)^{-1}(B)\right) = d\left((G^*)^{-1}(B)\right). \end{cases}$$

Then Definition 3.12 reduces to the following. Let  $F \in A_{\partial U}(\bar{U}, Y; L, T)$  with  $F^* = I \times (L + T)^{-1}(F + T)$ . We say  $F^* : \bar{U} \rightarrow 2^{\bar{U} \times E}$  is  $d$ - $L$ - $\Phi$ -essential if  $d\left((F^*)^{-1}(B)\right) \neq d(\emptyset)$ .

*Remark 3.16.* If  $E$  is a normal topological vector space then the assumption that  $D$  (in the proof of Theorem 2.15) is compact, can be replaced by  $D$  is closed, in the statement (and proof) of Theorem 3.13 and also the assumption that

$$\{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact, can be replaced by

$$\{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is closed, in Definition 3.11; here  $H^*(x, \lambda) = (x, (L + T)^{-1}(H + T)(x, \lambda))$ .

We now fix a  $\Phi \in B(E, Y; L, T)$ .

**Definition 3.17.** Let  $F : E \rightarrow 2^Y$ . We say  $F \in A(E, Y; L, T)$  if  $(L + T)^{-1}(F + T) \in A(E, E)$ .

For any map  $F \in A(E, Y; L, T)$  let  $F^* = I \times (L + T)^{-1}(F + T) : E \rightarrow 2^{E \times E}$ , with  $I : E \rightarrow E$  given by  $I(x) = x$ , and let

$$d : \{(F^*)^{-1}(B)\} \cup \{\emptyset\} \rightarrow \Omega \tag{3.12}$$

be any map with values in the nonempty set  $\Omega$ ; here  $B = \{(x, (L + T)^{-1}(\Phi + T)(x)) : x \in E\}$ . In our applications we will be interested in maps  $F : \bar{U} \rightarrow 2^Y$  so  $F^* = I \times (L + T)^{-1}[F + T] : \bar{U} \rightarrow 2^{\bar{U} \times E}$  and in this case we consider

$$d : \{(F^*)^{-1}(B_U)\} \cup \{\emptyset\} \rightarrow \Omega,$$

where  $B_U = \{(x, (L + T)^{-1}(\Phi + T)(x)) : x \in U\}$ .

**Definition 3.18.** If  $F, G \in A(E, Y; L, T)$  then we say  $F \cong G$  in  $A(E, Y; L, T)$  if there exists a map  $\Lambda : E \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(\Lambda(\cdot, \eta(\cdot)) + T) \in A(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$ ,  $\Lambda_1 = F$  and  $\Lambda_0 = G$  (here  $\Lambda_t(x) = \Lambda(x, t)$ ) and

$$\{x \in E : (x, (L + T)^{-1}(\Phi + T)(x)) \cap \Lambda^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact; here  $\Lambda^*(x, \lambda) = (x, (L + T)^{-1}(\Lambda + T)(x, \lambda))$ .

**Theorem 3.19.** Let  $E$  be a Hausdorff topological vector space,  $Y$  a topological vector space,  $U$  an open subset of  $E$ ,  $L : \text{dom}(L) \subseteq E \rightarrow Y$  a linear single valued map,  $T \in H_L(E, Y)$  and  $d$  a map defined in (3.12). Suppose there exists a map  $H : E \times [0, 1] \rightarrow 2^Y$  with  $(L + T)^{-1}(H(\cdot, \eta(\cdot)) + T) \in A(E, E)$  for any continuous function  $\eta : E \rightarrow [0, 1]$ ,  $(L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_0 + T)(x) = \emptyset$  for  $x \in E \setminus U$ ,  $(L + T)^{-1}(H_t + T)(x) \cap (L + T)^{-1}(\Phi + T)(x) = \emptyset$  for any  $x \in \partial U$  and  $t \in [0, 1]$ , and

$$\{x \in E : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}$$

is compact; here  $H^*(x, \lambda) = (x, (L + T)^{-1}(H + T)(x, \lambda))$ . In addition assume the following hold:

$$\begin{cases} \text{for any } J \in A(E, Y; L, T) \text{ with } J^* = I \times (L + T)^{-1}(J + T) \\ \text{and } \Phi \cong H_0 \text{ in } A(E, Y; L, T) \text{ we have that } d\left((J^*)^{-1}(B)\right) = d\left((H_0^*)^{-1}(B)\right) \neq d(\emptyset), \end{cases} \tag{3.13}$$

$$\left\{ \begin{array}{l} \{x \in E \setminus U : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\} \\ \text{is closed} \end{array} \right.$$

and

$$\left\{ \begin{array}{l} \text{if } \mu : E \rightarrow [0, 1] \text{ is any continuous map with } \mu(\bar{U}) = 1, \text{ then} \\ \{x \in \bar{U} : (x, (L + T)^{-1}(\Phi + T)(x)) \cap (x, (L + T)^{-1}(H_{t\mu(x)} + T)(x)) \neq \emptyset \text{ for some } t \in [0, 1]\} \text{ is closed.} \end{array} \right.$$

Here  $H_0^* = I \times (L + T)^{-1}(H_0 + T)$ . Let  $H_1^* = I \times (L + T)^{-1}(H_1 + T)$ . Then we have  $d\left(\left(H_1^*\right)^{-1}(B_U)\right) = d\left(\left(H_0^*\right)^{-1}(B_U)\right) \neq d(\emptyset)$ .

*Proof.* Let

$$D = \{x \in E \setminus U : (x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) \neq \emptyset \text{ for some } t \in [0, 1]\}.$$

We consider two cases, as  $D \neq \emptyset$  and  $D = \emptyset$ .

Case (i).  $D = \emptyset$ .

Then for every  $t \in [0, 1]$  we have  $(x, (L + T)^{-1}(\Phi + T)(x)) \cap H^*(x, t) = \emptyset$ . Also from  $H_1 \cong H_0$  in  $A(E, Y; L, T)$  and (3.13) we have

$$d\left(\left(H_1^*\right)^{-1}(B)\right) = d\left(\left(H_0^*\right)^{-1}(B)\right) \neq d(\emptyset). \tag{3.14}$$

Note  $\left(H_1^*\right)^{-1}(B) = \{x \in E : (x, (L + T)^{-1}(\Phi + T)(x)) \cap (x, (L + T)^{-1}(H_1 + T)(x)) \neq \emptyset\}$ . Consider  $y \in E$  and  $(y, (L + T)^{-1}(\Phi + T)(y)) \cap H_1^*(y) \neq \emptyset$ . Then  $y \in E$  and  $\Phi(y) \cap (L + T)^{-1}(H_1 + T)(y) \neq \emptyset$ . Now since  $D = \emptyset$  we have  $y \in U$  and  $\Phi(y) \cap (L + T)^{-1}(H_1 + T)(y) \neq \emptyset$  i.e.,  $y \in U$  and  $(y, (L + T)^{-1}(\Phi + T)(y)) \cap H_1^*(y) \neq \emptyset$ . Consequently  $\left(H_1^*\right)^{-1}(B) \subseteq \left(H_1^*\right)^{-1}(B_U)$  and on the other hand it is immediate that  $\left(H_1^*\right)^{-1}(B_U) \subseteq \left(H_1^*\right)^{-1}(B)$ . Thus  $\left(H_1^*\right)^{-1}(B) = \left(H_1^*\right)^{-1}(B_U)$ . It is also immediate that  $\left(H_0^*\right)^{-1}(B) = \left(H_0^*\right)^{-1}(B_U)$ .

Thus (3.14) implies  $d\left(\left(H_1^*\right)^{-1}(B_U)\right) = d\left(\left(H_0^*\right)^{-1}(B_U)\right) \neq d(\emptyset)$ , and we are finished.

Case (ii).  $D \neq \emptyset$ .

Note  $D$  is compact and also note  $D \cap \bar{U} \neq \emptyset$ . Then there exists a continuous map  $\mu : E \rightarrow [0, 1]$  with  $\mu(D) = 0$  and  $\mu(\bar{U}) = 1$ . Define a map  $R : E \rightarrow 2^Y$  by

$$R(x) = H(x, \mu(x)).$$

Note  $R \in A(E, Y; L, T)$ . In fact  $R \cong H_0$  in  $A(E, Y; L, T)$  (to see this let  $\Lambda : E \times [0, 1] \rightarrow 2^Y$  be given by  $\Lambda(x, t) = H(x, t\mu(x))$ ).

Let  $R^* = I \times (L + T)^{-1}(R + T)$ . Now (3.13) guarantees that

$$d\left(\left(R^*\right)^{-1}(B)\right) = d\left(\left(H_0^*\right)^{-1}(B)\right) \neq d(\emptyset). \tag{3.15}$$

Note  $\left(R^*\right)^{-1}(B) = \{x \in E : (x, (L + T)^{-1}(\Phi + T)(x)) \cap (x, (L + T)^{-1}(R + T)(x)) \neq \emptyset\}$ . Consider  $x \in E$  and  $(x, (L + T)^{-1}(\Phi + T)(x)) \cap R^*(x) \neq \emptyset$ . Then  $x \in E$  and  $\emptyset \neq (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(R + T)(x) = (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_{\mu(x)} + T)(x)$ . If  $x \in E \setminus U$  then since  $x \in D$  we have  $\emptyset \neq (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_{\mu(x)} + T)(x) = (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(H_0 + T)(x)$  which is a contradiction. Thus  $x \in U$  and  $\emptyset \neq (L + T)^{-1}(\Phi + T)(x) \cap (L + T)^{-1}(R + T)(x)$ . Consequently  $\left(R^*\right)^{-1}(B) \subseteq \left(R^*\right)^{-1}(B_U)$  and on the other hand it is immediate that  $\left(R^*\right)^{-1}(B_U) \subseteq \left(R^*\right)^{-1}(B)$ . Thus  $\left(R^*\right)^{-1}(B) = \left(R^*\right)^{-1}(B_U)$ . Also  $\left(H_0^*\right)^{-1}(B) = \left(H_0^*\right)^{-1}(B_U)$ . Thus (3.15) implies

$$d\left(\left(R^*\right)^{-1}(B_U)\right) = d\left(\left(H_0^*\right)^{-1}(B_U)\right) \neq d(\emptyset). \tag{3.16}$$

Finally notice

$$\begin{aligned} (\mathbf{R}^*)^{-1}(B_U) &= \{x \in U : (x, (L+T)^{-1}(\Phi+T)(x)) \cap (x, (L+T)^{-1}(H_{\mu(x)}+T)(x)) \neq \emptyset\} \\ &= \{x \in U : (x, (L+T)^{-1}(\Phi+T)(x)) \cap (x, (L+T)^{-1}(H_1+T)(x)) \neq \emptyset\} = (H_1^*)^{-1}(B_U), \end{aligned}$$

so from (3.16) we have  $d\left(\left(H_1^*\right)^{-1}\left(B_U\right)\right) = d\left(\left(H_0^*\right)^{-1}\left(B_U\right)\right) \neq d(\emptyset)$ .  $\square$

*Remark 3.20.* In Definition 3.18 and in the statement of Theorem 3.19 we could replace, any continuous map  $\eta : E \rightarrow [0, 1]$ , with, any continuous map  $\eta : E \rightarrow [0, 1]$  with  $\eta(\bar{U}) = 1$ .

*Remark 3.21.* There is an analogue of Remark 3.16 (for normal topological vector spaces) in the statement of Theorem 3.19 and in Definition 3.18.

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